3D User Interface design for Virtual Reality applications

Which is better: Naturalism or Magic?

The 3 universal tasks: Navigation, Selection, Manipulation

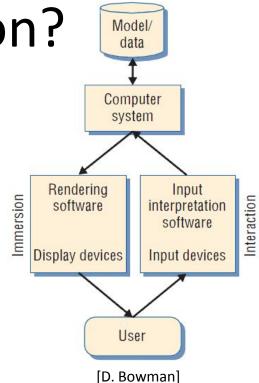
Based on [3DUI theory & practice 2nd edition 2017], [A2012], D. Bowman course notes, Virginia Tech. and [CACM sept. 2012]



Why 3D interaction?

- 3D / VE apps. should be useful
 - Immersion
 - Leverage on human natural skills
 - Immediacy of visualization (real-time feedback)

But, current VE apps have serious usability problems



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What makes 3D interaction difficult?

- Spatial input
- Lack of constraints
- Lack of standards
- Lack of tools
- Lack of precision
- Fatigue
- Layout more complex
- Perception



Two approaches: naturalism vs magic

- Naturalism (or interaction fidelity):
 - use natural movement and body parts to make the VE work exactly like the real world
 - walking
 - full-body action used partially (sport games)
 or totally (to drive an avatar posture or training)



- Magic: give user new abilities
 - Perceptual
 - Physical
 - Cognitive

naturalism vs magic (2)

- The level of naturalism depends on the interaction technique and the application:
 - steering wheel metaphore :
 - is natural for driving simulator
 - is not for shooting a virtual basket ball [B2012]



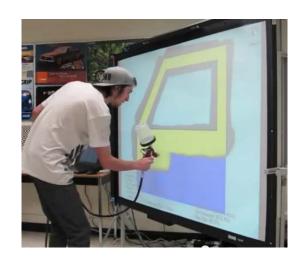
[Youtube:watch?v=6cLvkTCryBY]

- Some actions in VR/game have no natural equivalent, e.g. teleportation
- •in-between case: mapping a bycicle riding movement with hand and arm movement



naturalism vs magic [B2012] (3)

- Are 3D UIs inherently more natural than traditional UIs?
- Should we strive primarily for high-level of naturalism, or are other interaction design criteria more important (next slide)?



[Youtube:watch?v=JFTRXG1y0r8]

- Does a more natural interface result in better performances, greater user engagement, or increased ease of learning?
- When the most natural mapping cannot be used, is it better to use a moderately natural technique, or are traditional techniques more appropriate?



Interaction design criteria

- Performance
 - efficiency, accuracy, productivity
- Usability
 - ease of use, ease of learning, user comfort
- Usefulness
 - users focus on tasks, interaction helps users meet system goals, transfert of skill in the real world.



Components of 3D interactions

The three universal tasks:

- Navigation
- Selection
- Manipulation

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Other 3DUI components

- System control
- Symbolic input
- Constraints
- Passive haptic feedback
- Two-handed interaction







The Navigation component

- Most common task
- is composed of :
 - Travel: the physical movement from place to place
 - Natural travel (walk) is not always the best
 - Steering a vehicle
 - Target-based: choose from a list, point at object,etc
 - Wayfinding: where am I? where do I have to go? How do I get there? ...
 - Map-based, e.g. GPS metaphore

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Travel: naturalistic techniques

 walking and turning the head is obviously natural but technically difficult:



- Head-Monted-Display (HMD) with 6D tracking of the head and <u>sufficient space</u>
- without HDM -> constrained by the display location
- redirected walking [Razzaque PhD 2005 UNC]
- walking-in-place [Usoh et al,1999], Wiibalance
- dedicated interfaces (next slides)

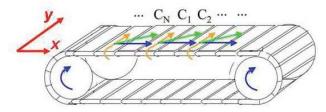
Travel naturalistic interfaces (1)

Ground-referenced haptic device: bidirectional treadmill [EU Project Cyberwalk]



Control Design and Experimental Evaluation of the 2D CyberWalk Platform, De Luca, Mattone & Giordano, Buelthoff, IROS2009 / MPI, TUM, ETHZ, URoma

Goal: offer omnidirectional navigation through effective2D body displacement instead of resorting to a metaphore



Concept: synchronized linear belts C_1 , C_2 , ... C_N , are displaced with a common velocity V_x in the blue direction, which is orthogonal to the individual velocities V_y (orange) of each belt. Hence it is possible to synthesize a combined velocity with any direction (green) in the plane

Travel naturalistic interfaces (2)



Results:

- Max V_x or V_y : 1.4 m/s
- Max combined: 2 m/s
- Max acc. along y (a belt): 1.3 m/s²
- •Max acc. along x (all belts): 0.25 m/s²

Issue:

- drift in case of sudden user stop
- walking on a treadmill is not natural walk

<u>System Architecture:</u>

- The control always pulls the walker towards the platform center (x_0, y_0) .
- The combined walker + platform movement is used to update the viewpoint in the virtual scene
- The user free displacement is measured with a VICON system
- Given the current platform movement, user location, velocity V_d and estimated acceleration, the Oberver component determines an update of the platform velocity to bring the user back in the middle without sudden change.

Travel naturalistic interfaces (2.5)



Recent concept/proto:

- infinadeck.com
- not yet on the market

Updated tradeoff:

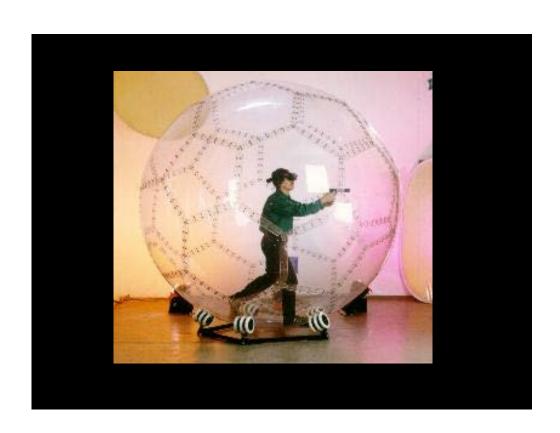
- smaller size -> less inertia but less space for navigating
- compensated by the tethered system

https://youtu.be/seML5CQBzP8?t=4

Naturalistic navigation interfaces (3)

Locomotion tracking with virtusphere

- An omni-directional freerolling sphere
- 10 feet diameter (~3m)
- To be used with headmounted display for walkthrough applications, games, etc...



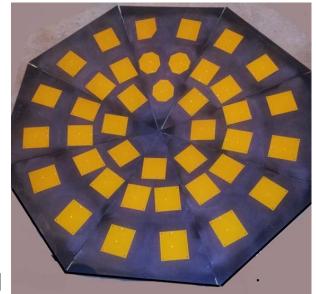
• Limitations:

- balance control on spherical floor,
- sphere inertia at fast speed
- mechanical sound of the movement,
- small field of view of HMD

Naturalistic navigation interfaces (4)

- Locomotion tracking with virtuix OMNI (prototype)
 - An omni-directional interface, feet tracking with capacitive sensors in the base
 - 3 feet diameter (~1m)
 - To be used with headmounted display
 - not yet fully evaluated
 - 2016/03: start shipping to first subscribers (USA only)
 - non-flat surface

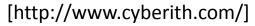




Naturalistic navigation interfaces (4.5)

- Locomotion tracking with Cyberith (Austria)
 - An omni-directional interface with sensor in the base plate, pillars and ring
 - flat slippery surface
 - Use overshoes
 - Can jump or seat too
 - Price on demand





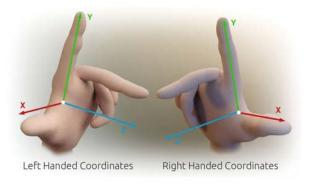




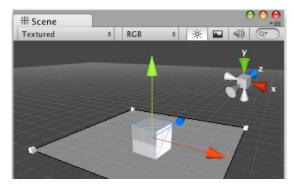
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Travel magic techniques

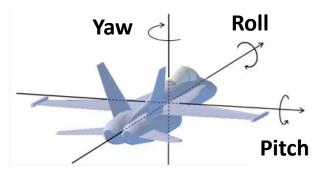
- Side note on coordinate systems and orientation control
 - No standard convention regarding handeness
 - **UNITY is left-handed**, vs right handed (most graphic libraries)
 - No standard regarding the vertical direction
 - UNITY is Y-Up (vs Z-Up in CAD-CAM)
 - Relative agreement on the choice of angles to control head, body, hand orientation (same as a plane)
 - Yaw (turn around the vertical axis)
 - **Pitch** (forward/backward inclination)
 - **Roll** (less used but see teleportation example)



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UNITY convention for 3D coordinate system





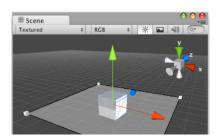
Travel magic techniques (2)

- Steering: (like in most games / driving metaphor)
 - input device provides front,back,left,right constant speed
 - handheld device, leaning on wiiBalance (inspired by [Wells96])
 - "human joystick": user stepping is mapped into oriented velocity
 - variants regarding which direction is considered forward
 - towards the center of the display vs device pointing direction
 - beneficial to separate viewing direction from travel direction
- Target-based / Teleportation / Dash tranfert
 - point in 3D with ray & jump (instantaneous or fast blurred movement = dash)
 - specify a point of interest from a list (easier but constrained if predefined targets)
- Map-based (with additional 2D map)
 - manipulate user icon on the map

Travel magic techniques: teleportation

The **Yaw** angle defines the radial Pointing direction

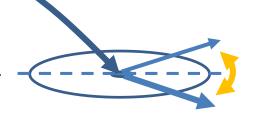
Standard straight line selection metaphor



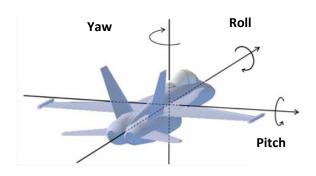


Pitch angle

Recent parabolic curve selection metaphor -> less fatiguing for pointing a target location on the floor



The **Roll** angle can be used to define the target radial Direction (video)



Yaw

Seated steering with the feet: 3d Rudder

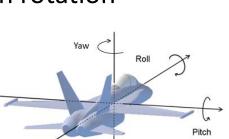
- Dedicated to navigation; frees the hands for other actions
- Low inertia, relatively precise input device (~foot mouse)

 3 degrees of mobility in rotation (with low amplitude)

Roll



COMBINED MOVEMENTS





Possible steering mapping:

- Yaw to direction changes (turning)
- Pitch to front-back translation (car)
- Roll to side translation (walk)

Other mapping are possible for generating events from short movements



Naturalistic/Magic travel technique

- Grab the Air [M1995]
 - grab the world and pull yourself through it (or pull it to yourself)
 - naturalistic inspiration: crawling, pulling a rope, swimming, climbing, browsing a book
 - can be achieved with one or two hands
 - can be combined with scaling
 - rotation should be ignored
 - activate through explicit trigger or gesture recognition





Navigation design guidelines

- There is no unique technique that suits all needs
- The simpler the better
 - Target-based technique for motion to an object
 - Steering technique for search/exploration
 - involve low inertia
- Provide transitional motion to maintain awareness of space (teleportation does disorient users)
- Naturalistic technique is best if the goal is training a real-world task, or to increase presence



The Selection component

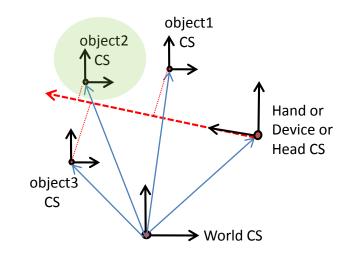
- specifying one or more objects from the environment
- Goal:
 - indicate action on object (e.g. delete, duplicate, etc..)
 - Make object active, travel to object,...
- Natural metaphors:
 - touching or pointing at with a virtual hand
 - touching requires travel if target not within arms' reach
 - pointing at with <u>ray/cone casting</u> is still considered natural
 - ray built from hand/device/head orientation
 - or from eye-to-finger direction (Image Plane)



Selection by ray-casting

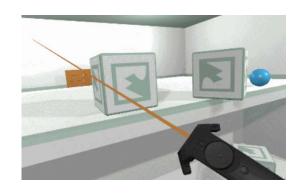
Ray casting technique:

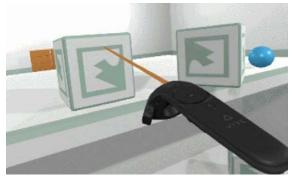
- get world hand/device/head pos & orientation
- compute objects distances to ray segment
- continuously highlight closest object to ray
- select the closest one when a dedicated event is produced by the user (e.g. button press on google cardboard HMD or simply a timeout event when an object has been the closest for X seconds).

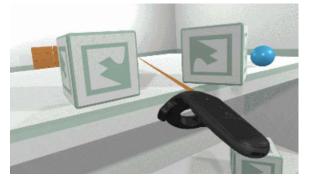


Weakness:

difficult to select small/far objects target object can be occluded



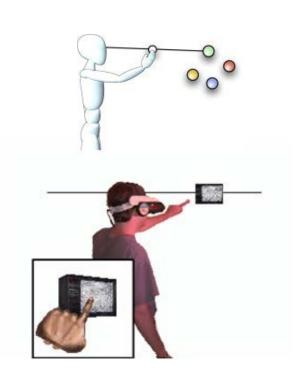




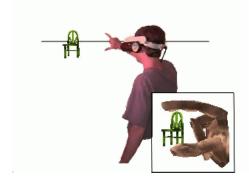
selection by occlusion or framing (image-plane technique)

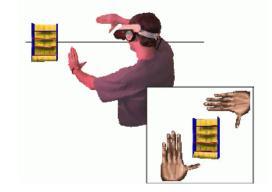
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- Ray casting from eye through the finger tip [Pierce 1997]:
 - get world head pos/orient ->eye position
 - get hand pos/orient -> finger tip position
 - compute objects distances to "eye-throughfinger" ray
 - highlight/select closest to ray <=> the finger tip is occluding the object in the image plane



- Alternate approaches:
 - •use 2 fingers or 2 hands to frame the desired object

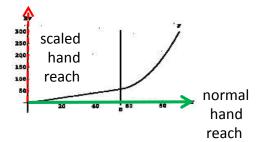




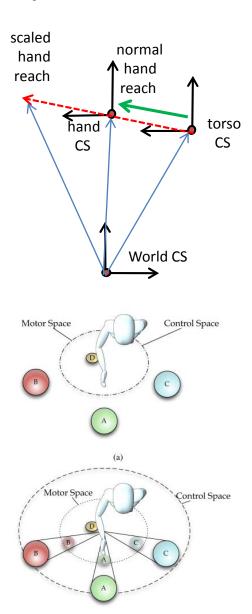


Magic selection technique

- extended "hyper-natural" touching or pointing metaphors
 - ex: the Go-Go technique [Poupirev96]:
 - compute the torso-to-hand vector
 - apply the scaling factor
 - 1:1 scaling factor near the body
 - non-linear scaling above a threshold



 once selected the object is attached to the hand and can be manipulated



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Magic selection technique

World in Miniature (WIM)

 scale-down the model to enhance user reach ability [Stoakley 1995]

remove part of the model (cut-aways)

to ease the WIM visualization [Andujar 2010]





The Manipulation component

- modify object properties: position, orientation, scale, shape, color, texture, behavior, etc.
 - For positioning: Virtual hand, ray casting, scaling
 - For orienting: the object should be hand-centered
 - apply the hand (re)-orientation to the manipulated object
 - Haptic feedback (future lecture) is required for highly specialized and high risk training (*surgery*)

Magic technique: miniature proxy copy of objects



Magic manipulation technique

 HOMER (Hand-centered Object Manipulation Extending Raycasting)
 [B2005]

- similar to the Go-Go technique :
 - select with the ray
 - manipulate with the hand
- easy selection & manipulation
- large distances
- hand-centered orientation is easy
- hard to move objects away

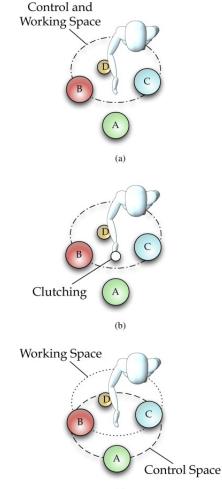


Time





- clutching occurs when a manipulation cannot be achieved in a single motion. The object must be released and regrasped to complete the task.
- also means: relocate the working space within a more comfortable reach space to be able to complete a manipulation task. -> see image on the right





Selection & Manipulation design guidelines

- How to validate a selection and report the event ?
 - provide feedback: graphical, audio, tactile
 - highlight candidate objects for selection
 - confirm user decision when a candidate object is chosen
- Display a virtual hand as a position/orientation ref
- selection should not be activated while manipulating
 - Beware of the « Midas touch »!
- Minimize clutching in manipulation
 - grasp-release-regrasp- etc...
- what happen after manipulating ?
 - remain there ? snap to grid ? fall gently ?

Benefits & Limitations of Naturalism (1)

[Bowman, MacMahan, Ragan, CACM Sept 2012]

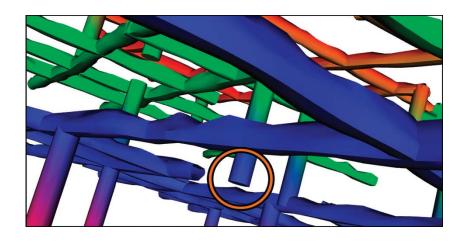
Benefits and limitations of natural 3D interaction for particular user tasks, taken from our prior research.

| Task | Benefits of naturalism | Limitations of naturalism |
|------------------------------|--|--|
| Viewpoint rotation | Users prefer physical turning. ³² | Users prefer virtual turning to a combination of physical and virtual turning. ³² |
| | Natural turning techniques have better performance than virtual turning for visual search. ³⁸ | |
| Viewpoint translation/travel | Head tracking can improve spatial understanding and detailed spatial judgments. ³³ | The benefits of head tracking may depend on other factors, such as stereoscopic display. ³³ |
| | | Moderately natural techniques can have poorer performance than traditional techniques. ³⁸ |
| Manipulation | Natural techniques improve performance of complex manipulation tasks. ³⁴ | Highly natural techniques have limited range. ²⁸ |
| | Hyper-natural techniques enhance users' abilities. ²⁸ | Hyper-natural techniques often reduce precision. ³⁶ |
| | It is possible to design hyper-natural techniques that feel natural and have high levels of precision. ³⁶ | |
| Vehicle steering | Higher levels of interaction fidelity can be more fun for users. ³ | Moderately natural techniques can have poorer performance than traditional techniques. ³ |
| Aiming | Highly natural aiming techniques can have better performance than mouse-based techniques. ³⁸ | |
| Multiple tasks | High levels of interaction fidelity, when paired with high display fidelity, can have very good performance. ³⁸ | High levels of naturalism may not be beneficial if the overall interface is unfamiliar. ³⁸ |
| | Users feel that highly natural techniques are more engaging and induce higher levels of presence. ³⁸ | |

Benefits & Limitations of Naturalism (2)

[Bowman, MacMahan, Ragan, CACM Sept 2012]

- Traditional interaction interfaces (2D/desktop/mouse, joystick, etc...)
 - are limited in their potential for naturalism
 - but have minimal HW and sensing requirements and are well established & ubiquitous
- 3D Natural interfaces can be seen as more fun & engaging
- Naturalism is most effective when very high level of fidelity can be achieved and when the user interface is familiar to the user
 - can provide a significant advantage
 - already well-mastered skills
 - ex: travel with head tracking ->
- <u>Hypernatural</u> techniques outperform natural ones. However they may reduce presence, the understanding of actions, and the ability of transfer to real world





Components of 3D interactions

The three universal tasks:

- Navigation
- Selection
- Manipulation



Other 3DUI components

- System control
- Symbolic input
- Constraints
- Passive haptic feedback
- Two-handed interaction







System control

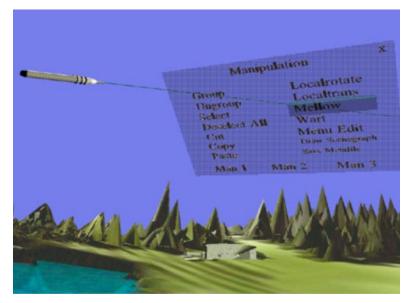
- Sometimes seen as a "catch-all" for 3D interaction techniques other than travel, selection, & manipulation
- Issuing a command to:
 - Change the system mode (interpretation of user input)
 - Change the system state
- Often composed of other tasks



Floating menus

- Can occlude environment
- Using 3D selection for a 1D task

- Other types:
 - Rotating menu
 - TULIP (3 items)

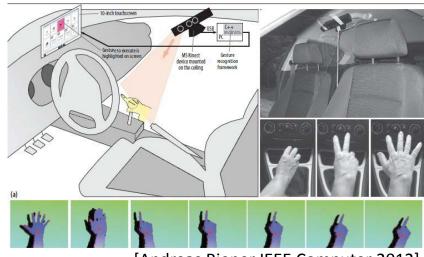


Body-centered enhance usage [Mine97]

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Gestural commands

- Can be "natural"
- limited vocabulary
- Fuzzy recognition issues
 - Usually HMM [Be2009]
 - toolkit: http://ftm.ircam.fr



[Andreas Riener IEEE Computer 2012]

- Gesture as command doesn't mimic our use of gestures in the real world
- Tradeoff between direct control/fatigue [O2014]
- pen-based sketch can be powerful
- More appropriate in multimodal interfaces (provide more than one technique, e.g. voice)



System control design guidelines

- Don't disturb flow of action
- Use consistent spatial reference
- Allow multimodal input (redundancy)
- Structure available functions hierarchically
- Prevent mode errors by giving feedback

- Communication of symbols (text, numbers, and other symbols/marks) to the system
- Is this an important task for 3D UIs?



[Celluon 2010]



Pranav Mistry: The thrilling potential of SixthSense technology

Keyboards: miniature, low key-count, etc..

Pen-based: pen stroke recognition

Gestures: sign language, numeric, etc

Speech: single char, whole words, general

Constraints

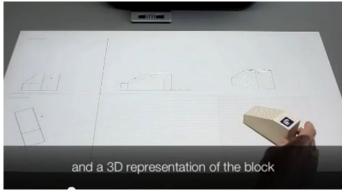
- Artificial limitations designed to help users interact more precisely or efficiently
- Examples:
 - Snap-to grid
 - Intelligent virtual objects / tools
 - Single Degree Of Freedom controls
 - projected movement in 1D (translation or rotation)

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Passive haptic feedback/Tangible

- Tangible interfaces
- Props or "near-field" haptics
- Examples:
 - Flight simulator controls
 - Pirates' steering wheel, cannons
 - Elevator railing
- Increase presence
- improve interaction

(e.g. S. Cuendet 2013)







Two-handed interaction

- Symmetric vs. Asymmetric
- <u>Dominant</u> vs. <u>Non-Dominant</u> hand
- Guiard's principles
 - 1) ND hand provides frame of reference

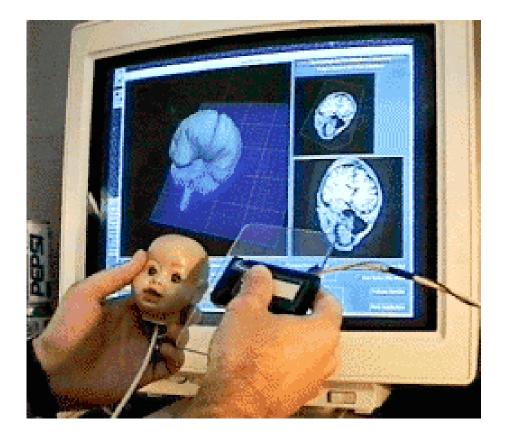


[Scott Mackenzie 2003]

Two-handed interaction (2)

- Guiard's principles
 - 2) ND hand used for coarse tasks,D hand used for fine grained tasks

3) Manipulation initiated by ND hand



[Ken Hinkley et al 1999]

Two handed interaction (3)



Combining gesture recognition and continuous input



- Allows surgeon to explore patient image stack data while operating in a sterile environment [O2014]
- ND hand for mode selection
- D hand for continuous control of image parameters
- Currently experimented clinically

Pen & tablet





 Involves 2D interaction, two-handed interaction, constraints, and props

Recent project: Google Tilt Brush with HTC Vive HMD



Conclusions

- Usability one of the most crucial issues facing VE applications, including ergonomy (fatigue)
- Implementation details critical to ensure usability
- Simply adapting 2D interfaces is not sufficient
- Strengths of 3D interactions:
 - complex 3D data exploration
 - professional tool gesture /protocole training in 3D
 - touchless interaction (e.g. surgeon, driving,...)
 - simple cases of Rehabilitation & ExerGame



More work needed on...

- System control performance (e.g. latency)
- Symbolic input
- Mapping interaction techniques to devices
- Integrating interaction techniques into complete UIs
- Development tools for 3D Uis
- resources: www.3dui.org
- research in VR: http://knowledgebase.cs.vt.edu/

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carpenter demo: http://www.youtube.com/watch?v=vnlLeCYxmCs

Parnav Mistry TED talk: http://www.youtube.com/watch?v=YrtANPtnhyg