# Solution suggestions série 7 continued

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## Preliminary exercise

Let X and Y be affine spaces of directions V and W resp.

### Question 1

Let  $\{v_1, ..., v_n\}$  be a basis of V and  $\{w_1, ..., w_n\}$  be arbitrary vectors in W. **T.S.**:  $\exists$  a unique  $\varphi \in Hom_k(V, W)$  s.t.  $\varphi_0(v_i) = w_i \forall 1 \le i \le n$ 

Let  $v \in V$ , we have  $v = \sum c_i v_i$  where  $c_i \in k \forall 1 \le i \le n$  are unique. Define  $\varphi_0(v) = \sum c_i w_i$ . We leave it to the reader to check  $\varphi_0$  is linear. Uniqueness is clear from linearity.

### Question 2

Let  $P_0 \in X$ ,  $Q_0 \in Y$  and  $\varphi_0 \in Hom_k(V, W)$ .

**T.S.** There exists a unique affine transformation  $\varphi : X \to Y$  s.t.  $\varphi(P_0) = Q_0$  and  $\varphi_0$  is the linear part of  $\varphi$ .

Let  $P \in X$ ,  $P = P_0 + v$  for a unique  $v \in V$ . Define  $\varphi(P) = Q_0 + \varphi_0(v)$ . It follows from Théorème 3.1, that  $\varphi$  is an affine transformation. If  $\psi : X \to Y$ is an affine transformation, we have  $\psi(P) = \psi(P_0) + lin(\psi)(v)$ . So an affine transformation is uniquely determined by the image of one point and the linear part.

Compare this question to the theorem in the solution of exercise 5.

### Exercise 3

Let  $\varphi$  be the affine morphism from  $\mathbb{R}^3$  to  $\mathbb{R}^3$  that maps

$$P_0 = (1, 1, 1), P_1 = (1, 1, 2), P_2 = (1, 2, 1), P_3 = (2, 2, 4)$$

 $\mathrm{to}$ 

$$Q_0 = (1, 2, 3), \ Q_1 = (1, 3, 3), \ Q_2 = (2, 3, 6), \ Q_3 = (1, 2, 4).$$

### Question 1

We compute  $v_i := P_i - P_0$ 

$$v_1 = (0, 0, 1), v_2 = (0, 1, 0), v_3 = (1, 1, 3)$$

These vectors form a basis of  $\mathbb{R}^3$  i.e. the points  $P_i$  are in general position. It follows from the theorem in solution of exercise 5 that  $\varphi$  exists and is unique.

### Question 2

We also compute  $w_i := Q_i - Q_0$ 

$$w_1 = (0, 1, 0), w_2 = (1, 1, 3), w_3 = (0, 0, 1)$$

Let  $f : \mathbb{R}^3 \to \mathbb{R}^3$  be the linear map which satisfies  $f(e_i) = v_i$  and let  $g : \mathbb{R}^3 \to \mathbb{R}^3$  be the linear map which satisfies  $g(e_i) = w_i$ , where  $\{e_1, e_2, e_3\}$  is the standard basis of  $\mathbb{R}^3$ . It follows that  $\varphi_0 = g \circ f^{-1}$ . Note that the above statements use first question of the preliminary exercise. We made the above construction to calculate the matrix of  $\varphi_0$  (w.r.t. the standard basis of  $\mathbb{R}^3$ ). Here are the matrices of  $f, g, \varphi_0$ : (w.r.t the standard basis)

$$M_f = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & 3 \end{pmatrix}, M_f^{-1} = \begin{pmatrix} -3 & 0 & 1 \\ -1 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}, M_g = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 3 & 1 \end{pmatrix}$$

and we get

$$M_{\varphi_0} = \left(\begin{array}{rrrr} -1 & 1 & 0\\ -4 & 1 & 1\\ -2 & 3 & 0 \end{array}\right)$$

The translation vector is given by  $w = Q_0 - P_0 = (0, 1, 2)$ . So  $\varphi(P_0 + v) = P_0 + w + \varphi_0(v)$ . The image of  $\varphi$  is  $\mathbb{R}^3$  because  $\varphi_0$  is surjective.

 $arphi^{-1}({f 3},{f 2},{f 1}):$ 

 $(3,2,1) - Q_0 = (2,0,-2)$ . Further  $\varphi_0^{-1}(2,0,-2) = (-8,-6,-26)$ . We conclude that  $\varphi^{-1}(3,2,1) = P_0 + (-8,-6,-26) = (-7,-5,-25)$ .

Calculating in the same way as above  $\varphi^{-1}(Q) = P_0 + \varphi_0^{-1}(Q - Q_0)$ . Note that  $\varphi$  is invertible since it is surjective between affine space of same dimension or by observing that  $Q_i$ 's are in general position and using the second corollary to our theorem. (solution of exercise 5) Also note:

$$M_{\varphi_0^{-1}} = \left( \begin{array}{ccc} -3 & 0 & 1 \\ -2 & 0 & 1 \\ -10 & 1 & 3 \end{array} \right)$$

### Question 3

Now set

$$Q_0 = (1, 2, 3), Q_1 = (1, 3, 3), Q_2 = (1, 7/3, 10/3), Q_3 = (1, 2, 4).$$

There exists a unique  $\varphi$  mapping  $P_i$  to  $Q_i$  resp.(this only uses the fact that  $P_i$  are in general position). We list properties  $\varphi$ , calculations are left to the reader.

$$M_{\varphi_0} = \begin{pmatrix} 0 & 0 & 0 \\ -10/3 & 1/3 & 1 \\ 2/3 & 1/3 & 0 \end{pmatrix}, \text{ Translation vector is } (0, 1, 2).$$

The image of  $\varphi$  is the 2 dimensional affine subspace given by  $\{Q_0 + \lambda(0,1,0) + \mu(0,0,1) | \lambda, \mu \in \mathbb{R}\} = \{(1,2+\lambda,3+\mu) | \lambda, \mu \in \mathbb{R}\}$ . In particular  $\varphi^{-1}(3,2,1) = \phi$ .

### Question 4

Now consider

$$P_0 = (1, 1, 1), P_1 = (1, 1, 2), P_2 = (3/2, 3/2, 3), P_3 = (2, 2, 4)$$

$$Q_0 = (1, 2, 3), \ Q_1 = (1, 3, 3), \ Q_2 = (1, 5/2, 7/2), \ Q_3 = (1, 2, 4)$$

We want to understand if there exists an affine transformation that maps the  $P_i$  to  $Q_i$  and if it is unique. In the light of the preliminary exercise, this reduces to studying the existence and uniqueness of a linear map  $\varphi_0$  which maps  $v_i := P_i - P_0$  to  $w_i := Q_i - Q_0, \forall 1 \le i \le 3$ . We have,

$$v_1 = (0, 0, 1), v_2 = (1/2, 1/2, 2), v_3 = (1, 1, 3)$$

to

to

$$w_1 = (0, 1, 0), w_2 = (0, 1/2, 1/2), w_3 = (0, 0, 1).$$

Observe that  $v_2 = \frac{1}{2}v_3 + \frac{1}{2}v_1$  and that  $v_1$  and  $v_3$  are linearly independent. (In other words  $v_1$ ,  $v_2$  and  $v_3$  lie in a 2-dimensional subspace.) Moreover  $w_2 = \frac{1}{2}w_3 + \frac{1}{2}w_1$ , so any linear transformation that maps  $v_1$  to  $w_1$  and  $v_3$  to  $w_3$ , automatically maps  $v_2$  to  $w_2$ ! Linear maps  $\varphi_0$  with the above property therefore exist but are not unique. We proceed to describe the linear maps with this property, using first part of the preliminary exercise:

Let us consider as a basis for  $\mathbb{R}^3$ (Check!),

$$v'_1 = (0, 0, 1), v'_2 = (1, 0, 0), v'_3 = (1, 1, 3)$$

we want to consider the linear transformation  $\varphi^w$  that maps the  $v_i$ 's respectively to

$$w'_1 = (0, 1, 0), w'_2 = w := (c_1, c_2, c_3), w'_3 = (0, 0, 1)$$

We can therefore parametrize all the linear maps which map  $v_1$  to  $w_1$  and  $v_3$  to  $w_3$  by  $\varphi^w$  for  $w \in \mathbb{R}^3$ . This is an affine subspace of  $Hom_{\mathbb{R}}(\mathbb{R}^3, \mathbb{R}^3)$  (the vector space of linear transformations from  $\mathbb{R}^3$  to  $\mathbb{R}^3$ ). More explicitly, the linear transformations of interest are of the form  $\varphi^w = \varphi^0 + c_1\psi^{e_1} + c_2\psi^{e_2} + c_3\psi^{e_3}, c_1, c_2, c_3 \in \mathbb{R}$  (i.e. the affine subspace  $\varphi^0 + (\mathbb{R}\psi^{e_1} \oplus \mathbb{R}\psi^{e_2} \oplus \mathbb{R}\psi^{e_3})$ ) and  $\psi^w$  is the linear transformation that maps

$$v_1' = (0, 0, 1), v_2' = (1, 0, 0), v_3' = (1, 1, 3)$$

respectively to

$$w'_1 = (0, 0, 0), w'_2 = w, w'_3 = (0, 0, 0).$$

and  $e_i$  is the ith standard basis vector

Any affine transformation that maps  $P_i$  to  $Q_i$  has linear part  $\phi^w$  for some  $w \in \mathbb{R}^3$  and maps  $P_0$  to  $Q_0$ .