# MICRO-461 Low-power Radio Design for the IoT

#### **3. Wireless Communication**

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## Outline

- General Considerations
- Analog Modulation
- Digital Modulation
- Power Efficiency of Modulation Schemes
- Noncoherent Detection

#### **Baseband and Bandpass Waveforms**



- Transmitted waveform in RF communications is usually a high frequency carrier modulated by the signal to be transmitted, because
  - In wireless, the antenna size should be a significant fraction of the carrier wavelength to achieve a reasonable gain
  - Because of regulation, communication can only occur in certain parts of the spectrum
  - In certain cases, modulation allows simpler detection at the receive end in presence of nonidealities in the communication channel
- Two types of signals:
  - **Baseband** signal: nonzero in vicinity of  $\omega$ =0 and zero elsewhere
  - **Bandpass** signals: waveform with spectrum nonzero around a carrier frequency  $\omega_c$

## Modulation and Demodulation



 Modulation converts a baseband signal into a bandpass counterpart by varying certain parameters of the sinusoidal carrier

$$x(t) = a(t) \cdot \cos\left[\omega_{c}t + \theta(t)\right]$$

- where a(t) and  $\theta(t)$  are usually real functions of time
- $\phi(t) = \omega_c t + \theta(t)$  is the total phase and  $\theta(t)$  the excess phase
- The instantaneous frequency is the time derivative of the phase  $\omega_c + d\theta/dt$  is the total frequency and  $d\theta/dt$  is the excess frequency
- The inverse of modulation is demodulation (or detection) with the goal of extracting the baseband signal with maximum signal-to-noise ratio

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### **Analog Modulation – Amplitude Modulation**



Amplitude modulation (AM) waveform

$$x_{AM}(t) = A_c \left[ 1 + m \cdot x_{BB}(t) \right] \cos \omega_c t$$

- where *m* is the **modulation index**
- The bandwidth of  $x_{AM}(t)$  is twice the bandwidth of  $x_{BB}(t)$
- The signal  $A_c \cos \omega_c t$  is generated by a local oscillator (LO)

#### **Analog Modulation – Amplitude Modulation**



- The AM signal can be demodulated using a multiplier and a LP filter (envelope detection)
- Except for broadcast radios and sound in television, AM finds limited use in today's wireless systems
- This is because carrying information in the amplitude both makes the signal susceptible to noise and requires a highly linear power amplifier in the transmitter

#### **Analog Modulation – Phase and Frequency Modulations**



Phase or Frequency modulation (PM or FM) waveform

$$x_{PM}(t) = A_c \cos\left[\omega_c t + \theta(t)\right] \quad \text{with} \quad \theta(t) = \begin{cases} m \cdot x_{BB}(t) & \text{for PM} \\ m \cdot \int_{-\infty}^{t} x_{BB}(t) dt & \text{for FM} \end{cases}$$

• where *m* is the **modulation index** 

# Analog vs. Digital



- Imagine a system in which you transmit a signal over a vey large distance
- Due to very large attenuation amplifiers are put between the transmitter and receiver
- If the transmitted signal is analog, each amplifier degrades the signal quality (adds noise), the larger the distance the worse the signal quality

- If the transmitted signal is digital (a discrete set of symbols is used for transmission), it can be fully reconstructed at each regeneration stage
- It is possible to reconstruct the TX signal on the RX side without the loss of quality

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# **Digital Modulation**



- Carrier modulated by a digital baseband signal
- Digital counter parts of AM, PM and FM
  - Amplitude shift keying (ASK)
  - Phase shift keying (PSK) and
  - Frequency shift keying (FSK)
- In RF, PSK and FSK more widely used because of a their lower sensitivity to amplitude noise

# **Binary and M-ary Signaling**



- Digital waveform  $x_{BB}(t) = \sum b_n \cdot p(t nT_b)$ 
  - Binary:  $b_n$  can take two distinct discrete values (+1 and -1 or +1 and 0)
  - M-ary:  $b_n$  can take M distinct discrete levels
- In the example below (M = 4), the original bit stream is converted into groups of 2 bits and each group is converted into 1 of 4 possible levels
- Fewer transitions per unit time, but higher amplitude resolution in the receiver
- Symbol rate is  $\frac{1}{2}$  the bit rate

# **Basis Functions**

• Binary FSK  

$$x_{FSK}(t) = \begin{cases} A_c \cdot \cos \omega_1 t & \text{if } b_n = 0 \\ A_c \cdot \cos \omega_2 t & \text{if } b_n = 1 \end{cases}$$

- Can also be represented by a linear combination of two orthogonal basis functions φ<sub>1</sub>(t) and φ<sub>2</sub>(t)
- Where  $x_{FSK}(t) = a_1 \cdot \varphi_1(t) + a_2 \cdot \varphi_2(t) = \begin{bmatrix} a_1 & a_2 \end{bmatrix} \cdot \begin{bmatrix} \varphi_1(t) & \varphi_2(t) \end{bmatrix}$

where  $\varphi_1(t) = A_c \cdot \cos \omega_1 t$  and  $\varphi_2(t) = A_c \cdot \cos \omega_2 t$ 

 More generally each symbol in a digital modulated waveform is represented by a linear combination of orthogonal basis functions

$$x(t) = \sum_{n=1}^{N} \alpha_n \cdot \varphi_n(t) \quad \text{with} \quad \int_{0}^{T_s} \varphi_m(t) \varphi_k(t) dt = 0 \quad \text{for } m \neq k$$

• where *T<sub>S</sub>* is the **symbol period** and *N* the **dimension** of the set of basis functions

# **Signal Constellations**

- Modulated waveforms can be visualized in terms of the a<sub>1</sub> and a<sub>2</sub> coefficients ignoring the basis functions
- a<sub>1</sub> and a<sub>2</sub> can be plotted in a Cartesian coordinates resulting in the signal constellation (or signal space)



 Such plots proves valuable in understanding various effects (such as noise, distortion, ...) in digital modems

### **Signal Constellations**

Another example is the ASK modulation

$$x_{ASK}(t) = \begin{cases} A_c \cdot \cos \omega_c t & \text{if } b_n = 1\\ 0 & \text{if } b_n = 0 \end{cases} \quad \text{or} \quad x_{ASK}(t) = a_1 \cdot \varphi_1(t)$$

• Where 
$$a_1(t) = \begin{cases} A_c & \text{if } b_n = 1 \\ 0 & \text{if } b_n = 0 \end{cases}$$
 and  $\varphi_1(t) = \cos \omega_c t$ 

• This scheme has **one dimension** with the constellation shown below



**Digital Modulation** 

## **Effect of Noise on Signal Constellation**

 The effect of noise on an ASK and FSK signals and their corresponding constellations are shown below



## **Optimum Detection – Matched Filter**



• The SNR is maximized when the impulse response h(t) of the filter is given by

$$h(t) = p^* \big( T_b - t \big)$$

- where *T<sub>b</sub>* is the bit duration
- If the matched filter input is a pulse p(t) and additive white noise with PSD  $N_0/2$ , the maximum SNR is given by

$$SNR_{\text{max}} = \frac{2E_p}{N_0}$$
 with  $E_p = \int_{-\infty}^{+\infty} |p(t)|^2 dt$ 

• where  $E_p$  is the signal energy

#### **Optimum Detection – Correlator**



The output of the matched filter at the end of the bit period is given by

$$y(T_b) = \int_{-\infty}^{+\infty} x(\tau)h(T_b - \tau)d\tau = \int_{-\infty}^{+\infty} x(\tau)p(\tau)d\tau$$

• where x(t) = p(t) + n(t). If p(t) is zero outside  $[0, T_b]$ , then

$$y(T_b) = \int_0^{T_b} x(\tau) p(\tau) d\tau$$

• which suggests that a correlation function must be performed between the input (signal + noise) and the known pulse shape p(t) for one bit period

#### **Optimum Detection – Correlator**



- The above discussion can be generalized to the case of a two-dimensional signal space such as FSK for example
- The correlators serve to find how similar  $x_{FSK}(t)$  is to  $\cos(\omega_1 t)$  or  $\cos(\omega_2 t)$  by integrating  $x_{FSK}(t) \cos(\omega_1 t)$  and  $x_{FSK}(t) \cos(\omega_2 t)$  over one bit period

#### **Coherent and Noncoherent Detection**



- Coherent detection require phase synchronization between the received waveform and the one synthesized within the receiver (usually matched filter detection schemes require phase synchronization and are hence coherent detection)
- Can be done by extraction of the carrier from the received waveform (using for example a Costas loop)

#### **Coherent and Noncoherent Detection**



- Some modulated waveforms can be demodulated using **noncoherent detection**
- A simple example is the FSK detector shown below
- This circuit uses two narrowband filters centered around  $\omega_1$  and  $\omega_2$  followed by envelope detectors
- Noncoherent detection detectors are more widely used in RF due to their lower complexity

# **Binary Modulation**



- Digital modulation with binary baseband waveforms: ASK (OOK), PSK (BPSK) and FSK (BFSK)
- Binary data represented by two real **pulse shapes**  $p_1(t)$  and  $p_2(t)$ 
  - For example in BFSK  $p_1(t) = A_c \cos(\omega_1 t)$  and  $p_2(t) = A_c \cos(\omega_2 t)$  for  $0 < t < T_b$

# **Bit Error Rate (BER)**



PDF=Probability density function

• The max SNR is then given by

$$SNR_{\text{max}} = \frac{2E_d}{N_0}$$
 with  $E_d = \int_{-\infty}^{+\infty} |p_1(t) - p_2(t)|^2 dt$ 

- which is maximum for  $p_1(t) = -p_2(t)$
- The bit error rate (BER) assuming additive white gaussian noise (AWGN), ideal matched filter detection and equiprobable states

$$P_{e} = Q\left(\sqrt{\frac{E_{d}}{2N_{0}}}\right) \quad \text{with} \quad Q(x) = \frac{1}{\sqrt{2\pi}} \int_{x}^{\infty} e^{-\frac{u^{2}}{2}} du \cong \frac{e^{-\frac{x^{2}}{2}}}{x\sqrt{2\pi}} \quad \text{for } x > 3$$

# **Binary Phase Shift Keying (BPSK)**



• In BPSK, the binary baseband signal is given by

$$x_{BPSK}(t) = A_c \cdot \cos(\omega_c t + \phi) \quad \text{where} \quad \phi = \begin{cases} 0 & \text{if } b_n = 0 \\ \pi & \text{if } b_n = 1 \end{cases}$$

which can also be written as

$$x_{BPSK}(t) = \alpha \cdot \cos(\omega_c t)$$
 where  $\alpha = \begin{cases} +A_c & \text{if } b_n = 1 \\ -A_c & \text{if } b_n = 0 \end{cases}$ 

# **Binary Phase Shift Keying (BPSK)**



• Since  $p_1(t) = -p_2(t)$ , the correlating signal in the detector is then

$$p_1(t) - p_2(t) = 2p_1(t) = 2A_c \cdot \cos(\omega_c t)$$



## **BPSK – BER**

• The signal energy  $E_d$  of a BPSK signal is given by

$$E_{d} = \int_{-\infty}^{+\infty} |p_{1}(t) - p_{2}(t)|^{2} dt = \int_{0}^{T_{b}} (2A_{c} \cdot \cos(\omega_{c}t))^{2} dt = 2A_{c}^{2}T_{b}$$

and hence the BER is then given by

$$P_e = Q\left(\sqrt{\frac{E_d}{2N_0}}\right) = Q\left(\sqrt{\frac{A_c^2 T_b}{N_0}}\right)$$

 To make fair comparisons with other modulation schemes, we define the average energy per bit E<sub>b</sub> as

$$E_b = \frac{A_c^2 T_b}{2}$$
 and hence  $P_{e,BPSK} = Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$ 

Note that *E<sub>b</sub>* contains both the amplitude and the period of the signal, the error rate can be lowered by increasing the signal power (i.e. increasing *A<sub>c</sub>*) or decreasing the data rate (i.e. increasing *T<sub>b</sub>*)

**Digital Modulation** 

# **Binary Frequency Shift Keying (BFSK)**

• In BFSK, the binary baseband signal is given by

 $x_{FSK}(t) = \alpha_1 \cdot \cos(\omega_1 t) + \alpha_2 \cdot \cos(\omega_2 t) \text{ where } \begin{bmatrix} \alpha_1 & \alpha_2 \end{bmatrix} = \begin{bmatrix} 0 & A_c \end{bmatrix} \text{ or } \begin{bmatrix} A_c & 0 \end{bmatrix}$ 

For the two basis functions to be orthogonal over one bit period, we need

$$\int_{0}^{T_{b}} \cos(\omega_{1}t) \cdot \cos(\omega_{2}t) \cdot dt = 0$$

• Assuming  $\omega_1 + \omega_2 \gg \omega_1 - \omega_2$ , the above equation reduces to  $\frac{\sin((\omega_1 - \omega_2) \cdot T_b)}{\omega_1 - \omega_2} = 0 \quad \text{thus} \quad (\omega_1 - \omega_2) \cdot T_b = n\pi$ 

• For minimum spacing between  $\omega_1$  and  $\omega_2$ 

$$(\omega_1 - \omega_2) \cdot T_b = \pi$$
 or  $f_1 - f_2 \triangleq \Delta f = \frac{1}{2T_b}$ 

The FSK signal bandwidth is approximately given by Carson's rule

$$B_T \cong 2\left(\Delta f + \frac{1}{T_b}\right)$$
 for orthogonal FSK  $B_T \cong \frac{3}{T_b}$ 



BFSK is 2-dimensional scheme with

$$p_1(t) = A_c \cdot \cos(\omega_1 t)$$
 and  $p_2(t) = A_c \cdot \cos(\omega_2 t)$ 

• The corresponding constellation is shown above

# BFSK – BER

• Since  $p_1(t)$  and  $p_2(t)$  are orthogonal

$$E_{d} = \int_{-\infty}^{+\infty} \left( p_{1}^{2}(t) + p_{2}^{2}(t) \right) dt = A_{c}^{2} T_{b}$$

and hence the BER is then given by

$$P_e = Q\left(\sqrt{\frac{A_c^2 T_b}{2N_0}}\right)$$

• As in BFSK the average energy per bit is given by

$$E_b = \frac{A_c^2 T_b}{2}$$
 and hence  $P_{e,BFSK} = Q\left(\sqrt{\frac{E_b}{N_0}}\right)$ 

- For the same BER, the bit energy in BFSK is twice that in BPSK (3dB advantage of BPSK over BFSK)
- Nevertheless BFSK is widely used for low data rate applications where  $E_b$  can be maximized by allowing a long  $T_b$

#### **Quadrature Modulation – Principle**



- In many applications it is beneficial to subdivide a binary data stream into pairs of two bits and represent each pair with one of four levels performing modulation
- For example bits  $b_m$  and  $b_{m+1}$  can be impressed upon a single carrier as

$$x(t) = b_m A_c \cos(\omega_c t) - b_{m+1} A_c \sin(\omega_c t)$$

• This is possible because  $\cos(\omega_c t)$  and  $\sin(\omega_c t)$  are orthogonal

## **Quadrature Modulation – Constellation**



- Assuming  $b_m$  and  $b_{m+1}$  are rectangular pulses with height ±1  $x(t) = \alpha_1 \cos(\omega_c t) + \alpha_2 \sin(\omega_c t)$
- Where  $\alpha_1$  and  $\alpha_2$  can take on a value of  $+A_c$  or  $-A_c$
- Two broad categories: quadrature phase shift keying (QPSK) and minimum shift keying (MSK)
- QPSK includes offset QPSK (OQPSK) and  $\pi$ /4-QPSK and MSK includes Gaussian MSK (GMSK)

# **Quadrature Phase Shift Keying (QPSK)**



 In analogy with BPSK, QPSK uses one of four phases of a sinusoid according to the symbol

$$x(t) = \sqrt{2}A_c \cos\left(\omega_c t + k\frac{\pi}{4}\right) \quad \text{with } k = 1, 3, 5, 7$$

- Coherent detection can be performed as shown below
- Determines the most likely value of the symbol from the set [±1 ±1]

#### **QPSK – Constellation and BER**



QPSK seems to have a higher BER because the points are located closer to each other

• For fair comparison between BPSK and QPSK it should be assumed that the transmitters produce the same average output power of  $A_c^2/2$ 

$$x_{BPSK}(t) = \pm A_c \cos(\omega_c t)$$
 and  $x_{QPSK}(t) = A_c \cos\left(\omega_c t + k\frac{\pi}{4}\right) = \pm \frac{A_c}{\sqrt{2}} \cos(\omega_c t) \pm \frac{A_c}{\sqrt{2}} \sin(\omega_c t)$ 

- Fair comparison also requires identical bit rates (identical binary data period  $T_b$ )
- Bit energy of BPSK is half the symbol energy of QPSK
- BPSK and QPSK have nearly the same BER  $P_{e,QPSK} = P_{e,BPSK} = Q \left| \sqrt{\frac{2E_b}{N_c}} \right|$

#### **QPSK – Phase Changes**



- Abrupt phase changes can occur in QPSK
- They are undesirable since they generate envelope variation after filtering (requires linear PA)

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## **Offset-QPSK (OQPSK) – Principle**



- The phase change of 180° of QPSK can be reduced to 90° by introducing a time offset of ½ symbol period between the two data streams
- OQPSK does not allow for differential encoding (encoding the phase change) which is required for noncoherent detection

#### $\pi$ /4-QPSK – Principle



- In contrast to OQPSK,  $\pi/4$ -QPSK allows for differential encoding
- The  $\pi/4$ -QPSK signal consist of two QPSK schemes, one rotated by  $\pi/4$

$$x_1(t) = A_c \cos\left(\omega_c t + k\frac{\pi}{4}\right) \text{ for } k \text{ odd,}$$
$$x_2(t) = A_c \cos\left(\omega_c t + k\frac{\pi}{4}\right) \text{ for } k \text{ even.}$$

#### $\pi$ /4-QPSK – Generation



(a) Evolution of  $\pi/4$ -QPSK in time domain, (b) possible phase

#### **Raised-Cosine Pulse Shaping**



Figure 2.16 Raised-cosine pulse: (a) in time domain, (b) in frequency domain.

- It was assumed that the baseband bits are represented by rectangular pulses
- For better spectrum efficiency, more band-limited pulses should be used (such as raised-cosine)

$$p(t) = \frac{\sin\left(\pi t/T_S\right)}{\pi t/T_S} \cdot \frac{\cos\left(\pi \alpha t/T_S\right)}{1 - \left(2\alpha t/T_S\right)^2} \qquad P(f) = \begin{cases} T_S & 0 < |f| < \frac{1 - \alpha}{2T_S} \\ \frac{T_S}{2} \left[ 1 + \cos\left(\frac{\pi T_S}{\alpha} \left(|f| - \frac{1 - \alpha}{2T_S}\right)\right) \right] & \frac{1 - \alpha}{2T_S} < |f| < \frac{1 + \alpha}{2T_S} \\ 0 & \frac{1 + \alpha}{2T_S} < |f| \end{cases}$$



**Digital Modulation** 

#### **Raised-Cosine Pulse Shaping**

Raised-cosine signaling can be obtained by filtering each bit (represented by a Dirac impulse) by a filter having an impulse response equal to p(t)



Figure 2.17 Raised-cosine filtering.

 In practice the raised-cosine filter is decomposed into two sections one placed in the transmitter and the other in the receiver



Figure 3.42 Decomposition of a raised-cosine filter into two sections.

# Minimum Shift Keying (MSK)



- MSK is continuous phase modulation to avoid sharp phase transitions
- OQPSK with half-cosines instead of rectangular pulses

$$x(t) = a_m \cos(\omega_1 t) \cos(\omega_c t) - a_{m+1} \sin(\omega_1 t) \sin(\omega_c t)$$

• Where  $a_m$  and  $a_{m+1}$  are rectangular pulses toggling between +1 and -1

# Gaussian Minimum Shift Keying (GMSK)



 Pulse shape obtained by passing the baseband rectangular pulse through a Gaussian impulse response

$$h(t) = \exp\left(-\alpha t^2\right)$$

#### **Noncoherent Detection**

- Matched filters (example of which are coherent detectors or correlators) provide the highest SNR and hence the lowest BER
- Coherent detector require that the phase of the local oscillator (LO) in the receiver is equal to that of the received signal which requires carrier recovery
- Phase alignment necessitate substantial circuit complexity and becomes especially difficult at low signal levels in the presence of interferers and signal fading
- For this reason many RF systems employ noncoherent detection despite its somewhat inferior performance

#### **Noncoherent FSK Detection**



It can be shown that the BER is given by

$$P_e = \frac{1}{2} \exp \frac{-E_b}{2T_b B_p N_0} = \frac{1}{2} \exp \frac{-E_b}{2N_0} \quad \text{for } B_p = \frac{1}{T_b}$$

- Where  $B_p$  is the bandwidth of each bandpass filter and  $E_b$  is the bit energy
- For error rates on the order of  $10^{-3}$  it requires an  $E_b/N_0$  that is only 1.5dB greater than that of an ideal coherent FSK detection

# **Differential Phase Shift Keying**



- Simple PSK waveforms cannot be detected noncoherently (requires time origin)
- However noncoherent detection is possible if the information is coded in the phase change from one bit (or symbol) to the next (does not require time origin)
- Differential PSK (DPSK)  $D_{out}\left[\left(m+1\right)T_b\right] = \overline{D_{in}\left(mT_b\right) \oplus D_{out}\left(mT_b\right)}$
- For BER=10<sup>-3</sup> DPSK requires approximately 3dB higher SNR than coherent PSK

# Outline

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#### Power Efficiency of Modulation Schemes

Noncoherent Detection

#### **Power Efficiency of Modulation Schemes**

- Modulated waveform  $x(t) = A(t)\cos(\omega_c t + \varphi(t))$
- Constant envelope if A(t) = const., otherwise variable envelope
  - Can define peak to average power ratio (PAPR) for variable envelope signals
- $3^{rd}$ -order memoryless nonlinearity with  $A(t) = A_c$

$$y(t) = \alpha_3 x^3(t) + \dots$$
  
=  $\alpha_3 A_c^3 \cos^3 \left( \omega_c t + \varphi(t) \right) + \dots$   
=  $\frac{\alpha_3 A_c^3}{4} \cos \left( 3\omega_c t + 3\varphi(t) \right) + \frac{3\alpha_3 A_c^3}{4} \cos \left( \omega_c t + \varphi(t) \right)$ 

- For BER=10<sup>-3</sup> DPSK requires approximately 3dB higher SNR than coherent PSK
- Bandwidth of original signal typically much smaller than  $\omega_c$
- From Carson's rule, the bandwidth occupied by third harmonic remains small

# **Spectral Regrowth**

- Consider a variable-envelope signal applied to the same nonlinear system  $x(t) = I(t)\cos(\omega_c t) + Q(t)\sin(\omega_c t)$
- where I(t) and Q(t) are the baseband in-phase and quadrature components

$$y(t) = \alpha_3 \Big[ I(t)\cos(\omega_c t) + Q(t)\sin(\omega_c t) \Big]^3$$
  
=  $\alpha_3 I^3(t) \frac{\cos(3\omega_c t) + 3\cos(\omega_c t)}{4} - \alpha_3 Q^3(t) \frac{-\cos(3\omega_c t) + 3\sin(\omega_c t)}{4} + \dots$ 

- Spectrum contains the spectra of  $I^3(t)$  and  $Q^3(t)$  centered around  $\omega_c$
- Since these components generally exhibit a broader spectrum than do *I(t)* and *Q(t)* the spectrum grows when a variable envelope signal passes through a nonlinear system

#### **Error Vector Magnitude**



- Transmitter nonlinearity and other non-ideal effects cause the constellation points to deviate from their ideal values
- Error vector magnitude (EVM) provides a quantitative measure of impairments that corrupt the transmitted signal

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# **Performance of Modulation Techniques**

- The performance of a modulation technique for RF applications is determined by three parameters:
  - The signal-to-noise ratio (SNR) or bit-error-rate (BER) in case of digital modulation, defining the quality of the modulation scheme
  - The **spectral efficiency** measuring the bandwidth required by the modulation scheme
  - The power efficiency depending on the type of power amplifier required by the modulation technique
  - Some modulated waveforms (constant envelope) can be processed by means of a nonlinear amplifier whereas some other require linear amplifier

#### **Generic Transceiver**



## **Wireless Standards: Specifications**

- Frequency bands and channelization
  - Each standard defines frequency bands in which the communication takes place
- Data Rates
  - The standard specifies the data rates that must be supported
- Type of modulation
  - Types of supported modulations as well as pulse shaping are defined by the standard
- Duplexing/Multiplexing Methods
  - Most systems support some kind of frequency (FDD or FDMA) or time (TDD or TDMA) multiple access techniques
  - Some systems employ code division multiple access (CDMA)
    - Direct sequence or frequency hopping

# **Wireless Standards: Specifications**

- TX output power
  - Minimum and maximum power of the transmitter defined by the standard (peak and average)
- TX EVM and spectral mask
  - Standard specifies the signal quality that must be respected
  - EVM specifies the deviation from ideal constellation points
  - Spectral mask determines limits to emission in adjacent bands (maximum PSD levels and adjacent channel leakage ratio - ACLR)
- RX sensitivity
  - Minimum detectable signal level defined by the standard in terms of BER
- RX input level range
  - Receiver must be able to handle certain signal range with acceptable noise and distortion

## **Wireless Standards: Specifications**



- RX tolerance to blockers and dynamic range
  - The standard specifies the largest interferer that the RX must be able to tolerate while receiving a weak desired signal
  - Dynamic range of the receiver implicitly determined

#### **Bluetooth: Air Interface**



2.4 GHz ISM band

- 1 Mb/s data rate in each channel, 1 MHz wide channels
  - 80 channels
  - Higher data rates supported by newer versions of the standard (BT enhanced data rate)

#### **Bluetooth: Modulation**

Gaussian minimum shift keying (GMSK)



Figure 1.3: Standard Enhanced Data Rate packet format

#### **Bluetooth: Spectral Mask**



- Different classes of devices supported
- Output power can go up to 20 dBm
- Most commercial devices support output power of 0 dBm
- Receiver must be able to handle input signals up to -20 dBm

## **Bluetooth: Blockers**



- Reference sensitivity of -70 dBm
  - Most commercial devices in the -90 dBm range
- Blocking test for adjacent and alternate channels:
  - Desired signal 10 dB higher than reference sensitivity. Adjacent channel with equal power modulated. Alternate adjacent channel with -30 dBm modulated.
- Blocking test for third or higher adjacent channel:
  - Desired signal 3 dB above sensitivity level, modulated blocker in third or higher adjacent channel with power -27 dBm

#### **Bluetooth: Blockers**



- Reference sensitivity –70 dBm
- Out of band blockers:
  - Desired signal at -67 dBm, tone level of -27 dBm or -10 dBm must be tolerated according to the tone frequency range

# **Transmitter Example**



- Transmitter targeting BT and IEEE 802.15.6
- Digital baseband implemented on an FPGA
  - For testing only
  - Spectral mask and EVM requirements
  - No packet formation, continuous stream used

# **Transmitter Example: Digital-Analog Interface**



- Polar architecture typical in LP transmitters
- Amplitude modulation implemented directly in the power amplifier
- Phase modulated directly at the DCO (digitally controlled oscillator)

## **Transmitter Example**



Spectral mask and EVM measurement

### **Transmitter Example**





EPFI

#### References

Most of this Chapter is based on Chapter 3 of Reference [1]

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