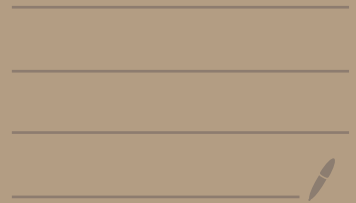


Information Theory & Coding

Oct 26th, 2020



Last week:

"C" of a channel: given a $P(y|x)$

$$C(P) = \max_{P_X} I(X; Y)$$

- seen that $P_X \mapsto I(X; Y)$ is a concave \cap function.

- convex set $S \subseteq \mathbb{R}^k$: $(x, y) \in S \iff 0 \leq \lambda \leq 1$
 $\Rightarrow (\lambda x + (1-\lambda)y \in S)$

- convex/concave function $f: S \mapsto \mathbb{R}$

$$f(\lambda x + (1-\lambda)y) \underset{\cup}{\geq} \lambda f(x) + (1-\lambda)f(y)$$

- $f: (a, b) \mapsto \mathbb{R} \iff \cup/\cap \quad f'' \underset{\cup}{\geq} 0$

$$P_X \mapsto I(X; Y) \text{ is } \cap$$

$$P_X \equiv \underbrace{(p_X(1), p_X(2), \dots, p_X(k))}_{\in \mathbb{R}^k}$$

P_X is distributed on $\{1, \dots, k\}$

$$\text{with } p_X(k) \geq 0, \sum_{k=1}^k p_X(k) = 1$$

$$S_k: \text{simplex-}k = \left\{ (p_1, \dots, p_k) : p_i \geq 0, \sum_i p_i = 1 \right\}$$

$S_k \iff$ a convex set.

Properties of vectors which maximize

$$\begin{array}{ccc} p & \mapsto & f(p) \\ \textcircled{1} & & \uparrow \\ S_k & & \mathbb{R} \end{array}$$

Thm: given $f: S_k \rightarrow \mathbb{R}$, smooth (differentiable)

and given $p = (p_1, \dots, p_k) \in S_k$. If p

maximizes f on the simplex, then

$$\left[\begin{array}{l} \exists \mu \text{ s.t.} \\ \frac{\partial f}{\partial p_i} \leq \mu \quad \forall i \\ \frac{\partial f}{\partial p_i} = \mu \quad \forall i \text{ } p_i > 0. \end{array} \right] \text{KKT} \\ \text{-conditions}$$

Pf: If p maximizes f , p must also be a local maximum. So let's take a look at a $q \in S_k$

$$\text{s.t. } q_i = p_i \text{ except } \begin{array}{l} q_1 = p_1 + \varepsilon \\ q_2 = p_2 - \varepsilon \end{array} \quad \varepsilon > 0$$

$$\underline{q_2 = p_2 - \varepsilon}$$

assume $p_2 > 0$

$$\underline{f(q)} = \underline{f(p)} + \left(\varepsilon \frac{\partial f}{\partial p_1} - \varepsilon \frac{\partial f}{\partial p_2} \right) + o(\varepsilon)$$

Since $f(q) \leq f(p)$ it must be the case that

$$\frac{\partial f}{\partial p_1} \leq \frac{\partial f}{\partial p_2}$$

Consequently for every $\left[i, j \text{ s.t. } p_j > 0 \right]$ we must have

$$\frac{\partial f}{\partial p_i} \leq \frac{\partial f}{\partial p_j}$$

\Rightarrow there exists a constant μ s.t

$$\frac{\partial f}{\partial p_i} = \mu \quad \forall i \text{ s.t } p_i > 0$$

$$\frac{\partial f}{\partial p_i} \leq \mu \quad \forall i$$

Thm: Suppose $f: S_K \rightarrow \mathbb{R}$ is concave. If

$S_K \ni p$ satisfies the KKT conditions then

$$f(p) \geq f(q) \quad \forall q \in S_K.$$

Pf: Suppose f is concave, $p \in S_K$ satisfying KKT

and $q \in S_K$. (we need to prove $f(q) \leq f(p)$.)

take $\lambda \in (0,1)$ and consider

$$f((1-\lambda)p + \lambda q) \geq (1-\lambda)f(p) + \lambda f(q)$$

$$\text{So } f(q) \leq \frac{1}{\lambda} \left[f((1-\lambda)p + \lambda q) - (1-\lambda)f(p) \right]$$

$$= f(p) + \frac{1}{\lambda} \left[f(p + \lambda(q-p)) - f(p) \right]$$

In particular

$$f(q) - f(p) \leq \lim_{\lambda \rightarrow 0} \frac{1}{\lambda} \left[f(p + \lambda(q-p)) - f(p) \right]$$

By Taylor's theorem

$$f(p + \lambda(q-p)) = f(p) + \sum_i \lambda(q_i - p_i) \frac{\partial f}{\partial p_i} + o(\lambda^2)$$

$$\text{So } \frac{f(p + \lambda(q-p)) - f(p)}{\lambda} = \sum_i (q_i - p_i) \frac{\partial f}{\partial p_i} + o(\lambda)$$

$$\Rightarrow \lim_{\lambda \rightarrow 0} \frac{f(p + \lambda(q-p)) - f(p)}{\lambda} = \sum_i (q_i - p_i) \frac{\partial f}{\partial p_i}$$

if we show $\sum_i (q_i - p_i) \frac{\partial f}{\partial p_i} \leq 0$ we will be done.

To that end, remember that p satisfies KKT so

$$\text{that } \exists \mu \text{ s.t. } \frac{\partial f}{\partial p_i} \leq \mu \quad \forall i$$

$$\frac{\partial f}{\partial p_i} = \mu \quad \forall i \text{ s.t. } p_i > 0.$$

$$\sum_i (q_i - p_i) \frac{\partial f}{\partial p_i} \stackrel{\geq 0}{\leq} \sum_{i: p_i > 0} (q_i - p_i) \mu + \sum_{i: p_i = 0}^{\geq 0} (q_i - 0) \frac{\partial f}{\partial p_i}$$

$$\leq \sum_i (q_i - p_i) \mu$$

$$= \mu - \mu \quad (\text{because } \sum_i q_i = 1 = \sum_i p_i)$$

$$= 0. \quad //$$

Conclusion: for $f: S_K \rightarrow \mathbb{R}$ concave \cap ,

KKT is necessary & sufficient for maximization.

Examples: consider the 3-simplex, and

$$\underline{f(p_1, p_2, p_3) = p_1 p_2 p_3}$$

$$\underline{\log f(p_1, p_2, p_3) = \log p_1 + \log p_2 + \log p_3} \quad \text{is } \cap$$

to maximize $f \cong$ to maximize $\log f$

KKT conditions:

$$\frac{\partial \log f}{\partial p_i} = \mu \quad \forall i$$

$$\frac{1}{p_1} = \mu, \quad \frac{1}{p_2} = \mu, \quad \frac{1}{p_3} = \mu$$

$\Rightarrow p_1 = p_2 = p_3 = \frac{1}{3}$ is the only maximizer.

Ex':

$$f(p_1, p_2, p_3) = p_1^2 p_2 p_3^3$$

$$\log f = 2 \log p_1 + \log p_2 + 3 \log p_3 \quad \text{is } \cap$$

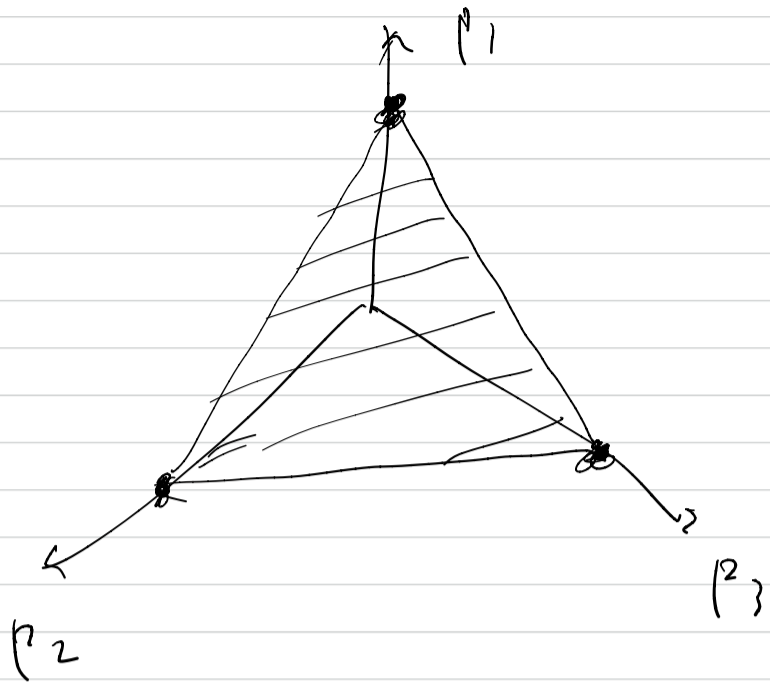
$$\Rightarrow \frac{2}{p_1} = \mu, \quad \frac{1}{p_2} = \mu, \quad \frac{3}{p_3} = \mu$$

$$\Rightarrow p_1 = 2p_2, \quad p_3 = 3p_2$$

$$(p_1, p_2, p_3) = \frac{1}{6} (2, 1, 3) = \left(\frac{1}{3}, \frac{1}{6}, \frac{1}{2}\right)$$

is the maximizer.

3-simplex:



K -simplex has

$$\left. \begin{array}{l} (1, 0, 0) \\ (0, 1, 0) \\ \vdots \\ (0, \dots, 0, 1) \end{array} \right\}$$

K standard unit-vectors
as its "corner" points.

Let us now specialize the KKT conditions to the problem

of maximizing $p_x \rightarrow f(p_x) = I(x; y)$

Suppose $X = \{1, \dots, K\}$

$Y = \{1, \dots, J\}$ then

$$f(p_x) = f(\underbrace{p_1, \dots, p_K}_{\in S_K}) = \sum_{ij} p_i p_{j|i} \log_2 \frac{p_{j|i}}{\sum_{k=1}^K p_k p_{j|k}}$$

$$\left(= \sum_{ij} \underbrace{p(x)}_{p_i} \underbrace{p(y|x)}_{p_{j|i}} \log_2 \frac{p(y|x)}{p(y)} \right)$$

$$\frac{\partial f}{\partial p_1} = \sum_{ij} \frac{\partial}{\partial p_1} \left(p_i p_{j|i} \log_2 \frac{p_{j|i}}{\sum_k p_k p_{j|k}} \right)$$

$$= \sum_{ij} \mathbb{1}\{i=1\} p_{j|i} \log_2 \frac{p_{j|i}}{\sum_k p_k p_{j|k}} - \underbrace{p_i p_{j|i}}_{p_i p_{j|i}} \frac{p_{j|i}}{\sum_k p_k p_{j|k}}$$

$$= \sum_j p_{j|1} \log_2 \frac{p_{j|1}}{\sum_k p_k p_{j|k}} - \sum_j p_{j|1} =$$

$$= \sum_j p_{j|z} l_{j|z} \frac{p_{j|z}}{\sum_k p_k p_{j|k}} - 1$$

$$\Rightarrow \frac{\partial f}{\partial p_i} = \sum_j p_{j|i} l_{j|i} \frac{p_{j|i}}{\sum_k p_k p_{j|k}} \quad \underbrace{(l_{j|i})}_{\text{smiley}}$$

KKT conditions become: p_x maximizes $I(x; y)$ iff

$$\left\{ \begin{array}{l} \exists \mu \text{ s.t.} \\ \sum_y p(y|x) l_{y|x} \frac{p(y|x)}{p_y(y)} \stackrel{\forall x}{=} \mu \quad \forall x \\ \stackrel{\forall x}{=} \mu \quad \forall x \quad p(x) > 0 \end{array} \right\}$$

if p_x satisfies KKT then

$$\underline{p_x(x)} \sum_y p(y|x) l_{y|x} \frac{p(y|x)}{p_y(y)} = \mu p_x(x) \quad \forall x.$$

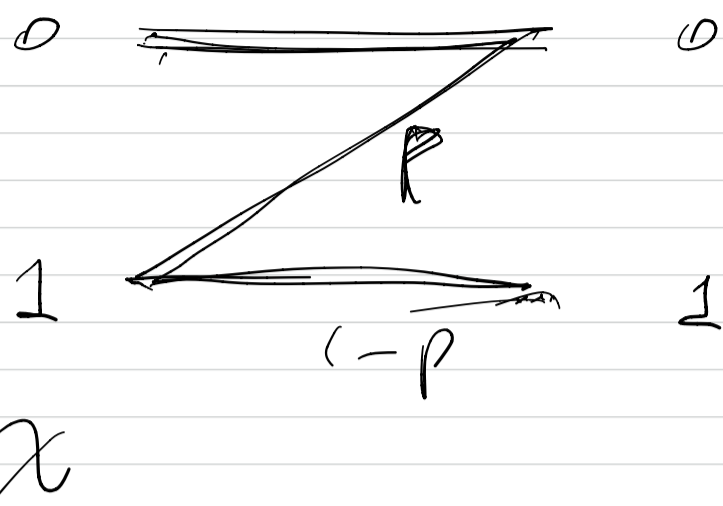
$$\Rightarrow \sum_x \dots = \mu$$

$$I(X; Y) = C(P)$$

so the " μ " in the KKT is $= C(P)$.

Example: P : channel

Z -channel (P)



$$P(0|0) = 1$$

$$P(1|0) = 0$$

$$P(0|1) = P$$

$$P(1|1) = 1-P$$

KKT conditions:

$$\lambda = 0$$

$$1 \log_2 \frac{1}{P_Y(0)} = C$$

$$\lambda = 1$$

$$P \log_2 \frac{P}{P_Y(0)} + (1-P) \log_2 \frac{1-P}{P_Y(1)} = C$$

$$\Rightarrow (1-P) \log_2 \frac{1-P}{P_Y(1)} = \log_2 \frac{1}{P_Y(0)} - P \log_2 \frac{P}{P_Y(0)}$$

$$\Rightarrow (1-P) \log_2 \frac{P_X(0)}{P_Y(1)} = h_2(P)$$

$$\log_2 \frac{P_Y(0)}{P_Y(1)} = \frac{h_2(P)}{1-P} \Rightarrow$$

$$\frac{P_Y(0)}{P_Y(1)} = 2^{\frac{h_2(P)}{1-P}}$$

$$\underline{\underline{(P_Y(1), P_Y(2)) = \frac{\left(2^{h_2(p)/(1-p)}, 1 \right)}{1 + 2^{h_2(p)/(1-p)}}}}$$

$$\underline{\underline{C = \log_2 \left(1 + 2^{-h_2(p)/(1-p)} \right)}}$$

The KKT conditions for $p_2 \mapsto I(X; Y)$

are useful in finding the $C(\cdot)$ of channels constructed from other channels:

Ex: $P_1(y_1 | x_1)$ $x_1 \in \mathcal{X}_1, y_1 \in \mathcal{Y}_1$

Given $P_2(y_2 | x_2)$ $x_2 \in \mathcal{X}_2, y_2 \in \mathcal{Y}_2$

$C(P_1), C(P_2)$ are already known.

a new channel is defined as follows:

$$\underline{\underline{P(y_1, y_2 | x_1, x_2) = P_1(y_1 | x_1) P_2(y_2 | x_2)}}$$

we can prove

$$\underline{\underline{C(P) \stackrel{?}{=} C(P_1) + C(P_2)}} \quad \text{via KKT conditions}$$

We have now seen some structural aspects of the computation of $C(P)$.

We also have our "bad news" theorem.

$$\underbrace{S(H)}_{\text{amount of source entropy to be covered}} > \underbrace{C(P)}_{\text{channel rate}} \Rightarrow \text{reliable communication} \rightarrow \text{not possible}$$

amount of source entropy to be covered / channel rate

i.e., there is a $p = f(S(H), C(P))$ s.t.

any comm. system has symbol error probability $\geq p$.

We shall embark on a program to show that

at communication rates $R < C(P)$

\leftarrow # of bits of information / channel use

we can design arbitrarily reliable comm. systems (enc, dec)

namely

Thm: given a channel P (mem.less, stationary)

$$R < C(P), \epsilon > 0 \Rightarrow \exists \text{ enc, dec s.t.}$$

$$P_e(\text{enc}, P, \text{dec}) < \epsilon$$

$$\text{rate}(\text{enc}) \geq R$$