

EE-206

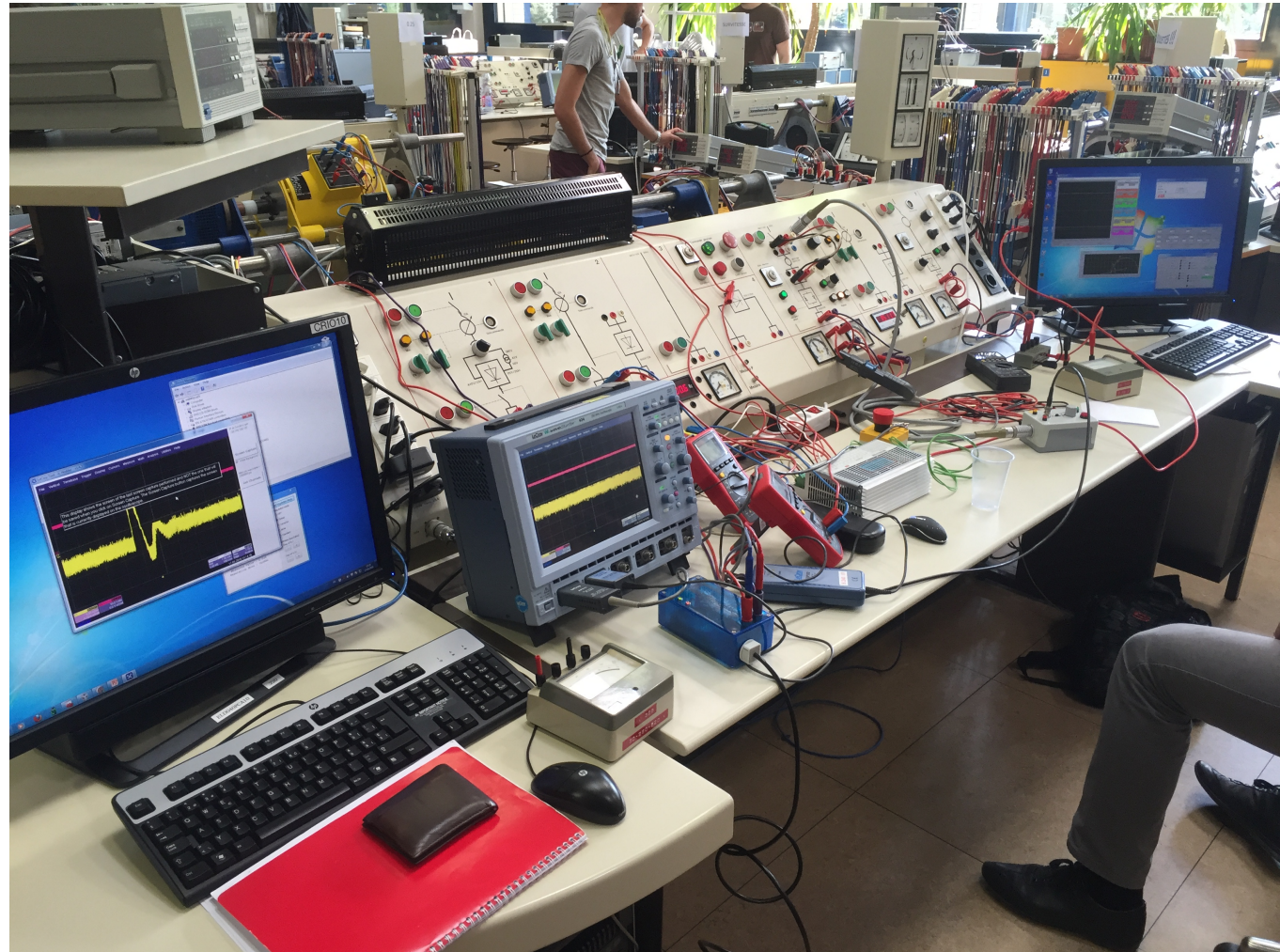
Systemes de mesure

LabVIEW crash course

- LabVIEW: what & why?
- Getting started
- Controls vs indicators

LabVIEW crash course

- LabVIEW:
what & why?



LabVIEW Trivia

- What does LabVIEW stand for?

Laboratory **V**irtual **I**nstrument **E**ngineering **W**orkbench.

- What is LabVIEW?

LabVIEW is a **graphical programming language**, typically used for data acquisition, instrument control, and industrial automation.

Introduced in 1986, it is supported by several OS (mostly Windows, Unix and Linux) and it can be installed on PCs as well as industrial controllers.

Graphical Program

MATLAB, HTML, Java are all traditional textual languages: the code consists of a sequence of operations/instructions.

LabVIEW is a graphical (G) programming language:

- no text but a sort of block diagram
- each block correspond to an operation/instrument
- each block has different options/configurations
- the connection defines the order of the different stages and the flow of the data

Advantages

LabVIEW yields also signal processing functionalities, but it is mostly used for:

1. remote instrument control
2. measurement data acquisition
3. automatic control routines

NB: a program in LabVIEW is called **Virtual Instrument (VI)** as it behaves as an instrument with controls and outputs (either numeric results or graphs).

Examples

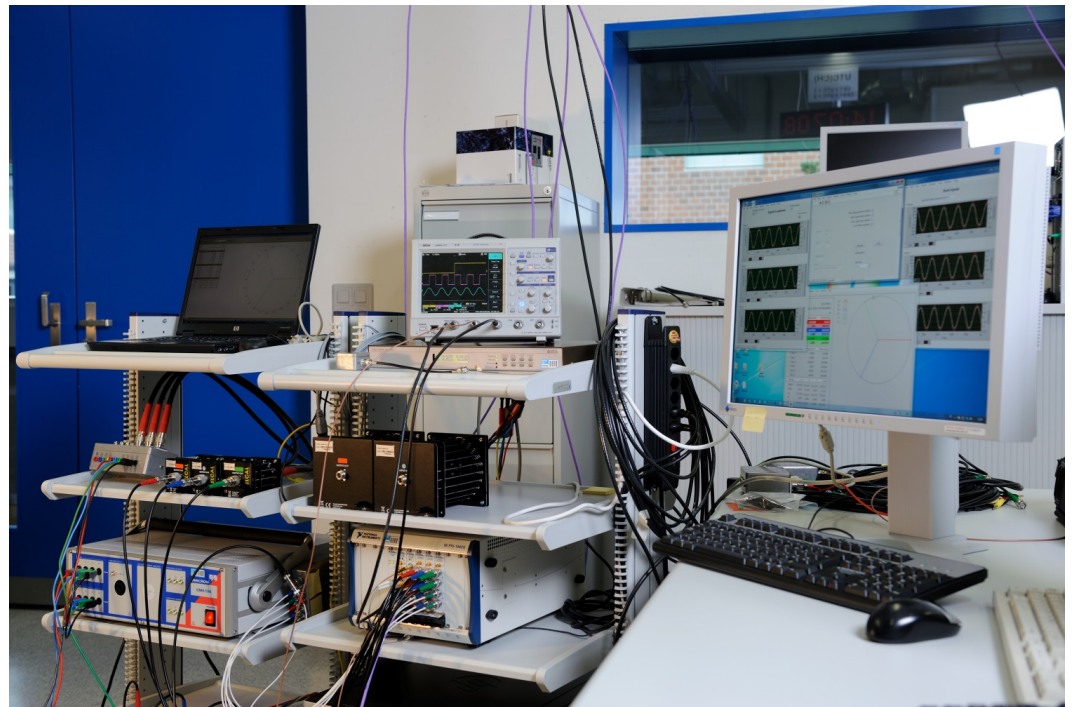
- Plug & play acquisition board
- ➔ compact **Data AcQ**quisition platform (cDAQ)
- extension of the PC
- pluggable modules
- data acquisition
- data transfer
- programmable trigger
- control outputs



Examples

- Coordination and interface between different instruments
- ➔ **PCI eXtensions for Instrumentation (PXI)**

- waveform generator
- voltage amplifier
- current amplifier
- shunt & dividers
- GPS synchronization
- data acquisition
- graph and result logs



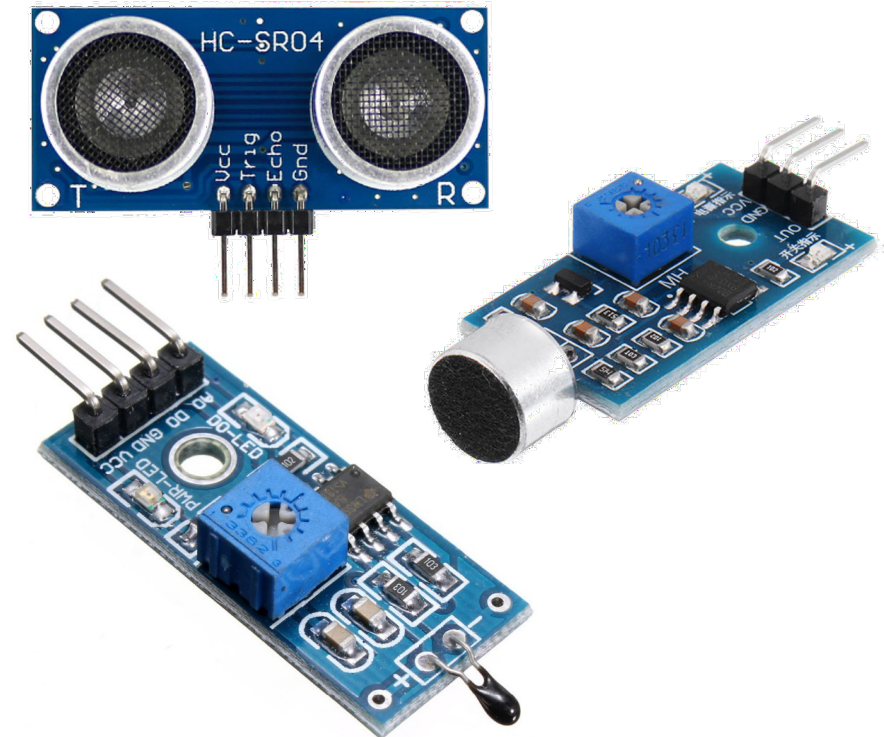
Examples

- Real-time stand-alone measurement unit
- ➔ compact **Reconfigurable IO** modules (**cRIO**)
- real-time controller
- network interface
- pluggable modules
- FPGA board for (fast, deterministic)



Examples

- Interface with third-party sensors (Arduino style)
→ e.g. ultrasound, thermistor, microphone
- integrated libraries
- dedicated functions
- app examples
- self-test routines
- automatic scaling



Getting started

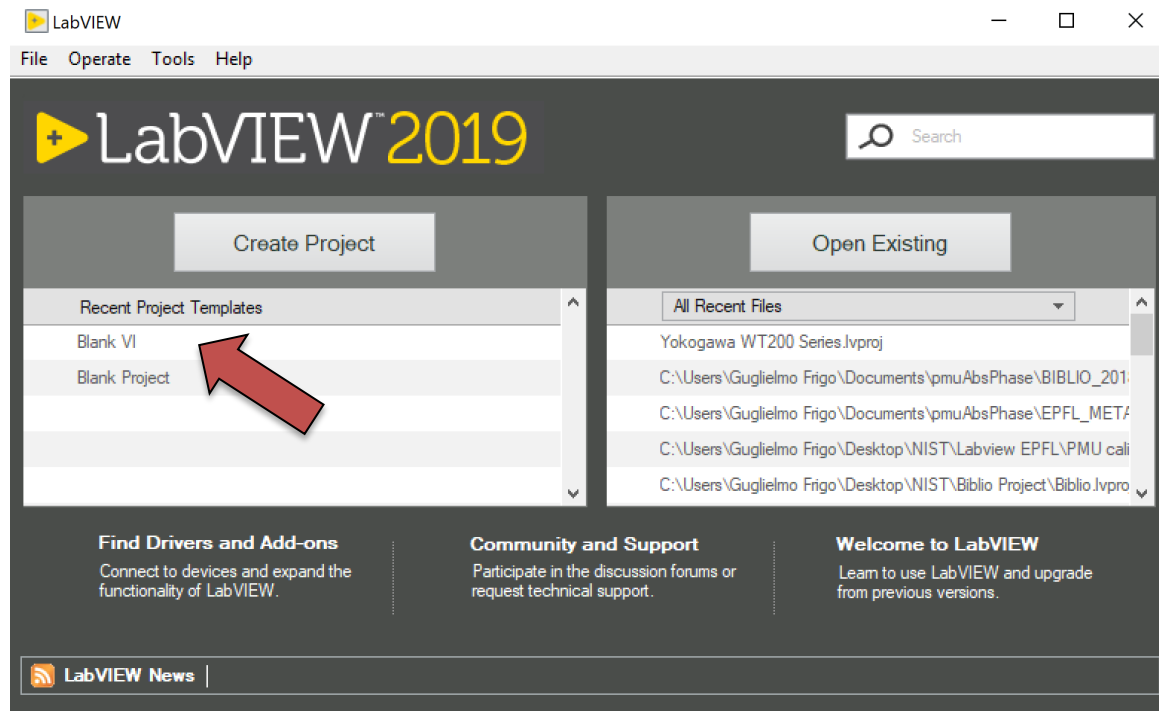
Let's launch Labview..

Create a file:

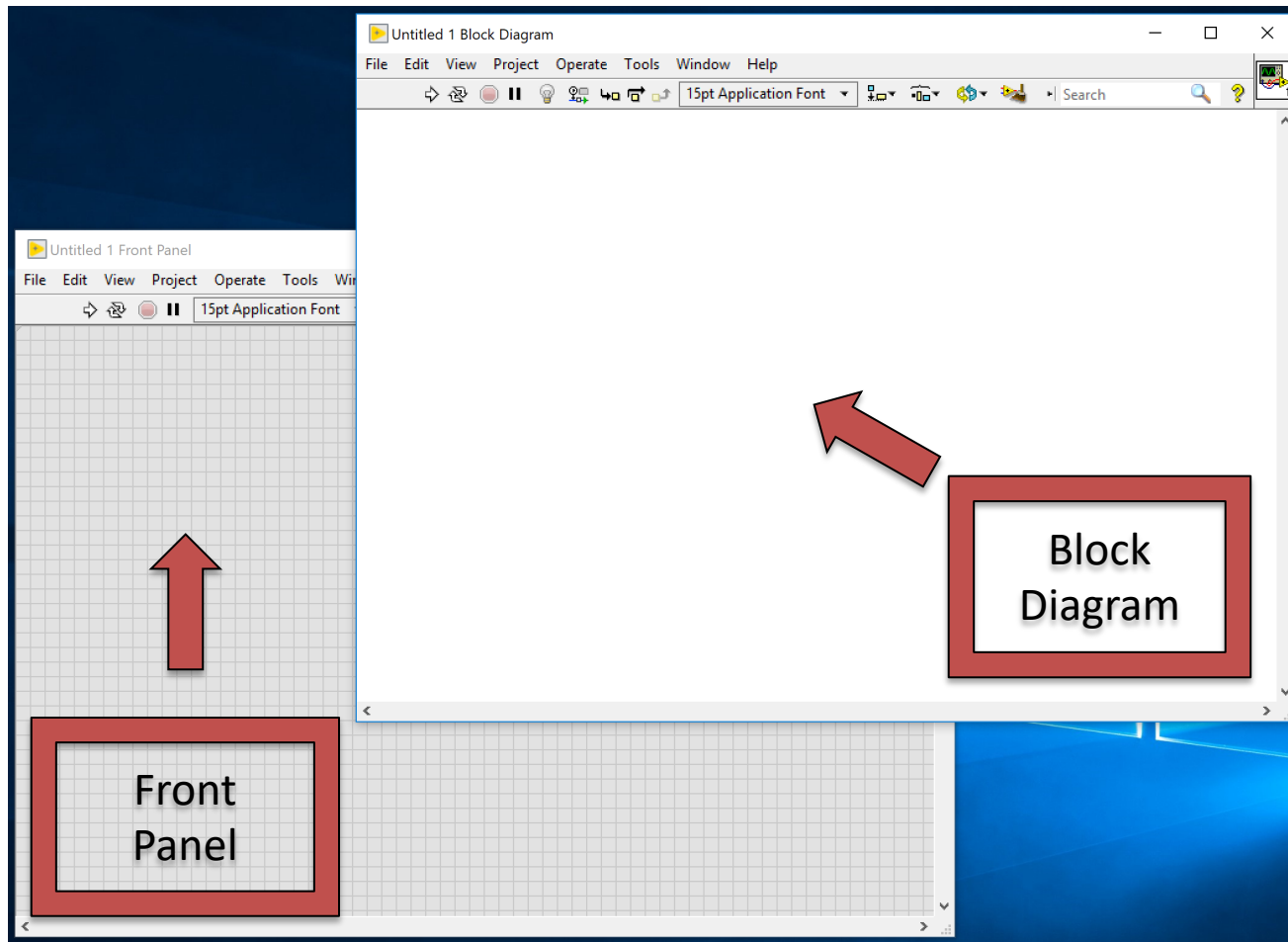
- VI → single file (.vi)
- Project → folder with multiple files (.lvproj)

Open a file:

- Recent files' history



Blank VI



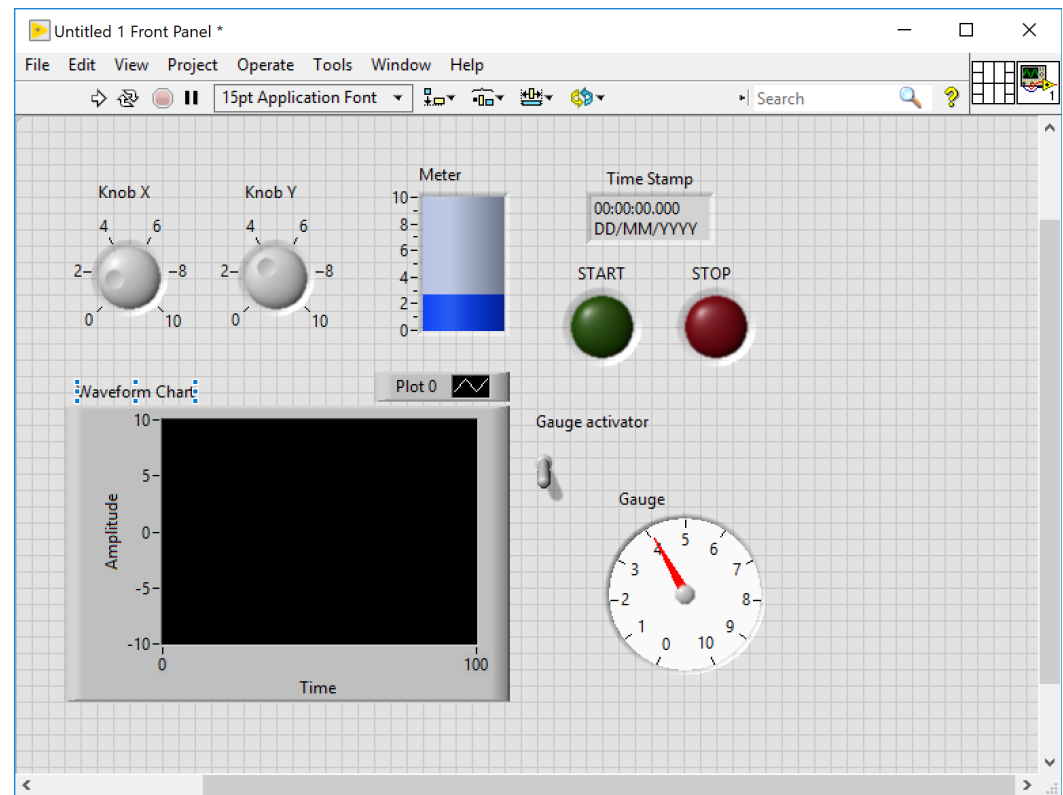
Front Panel

The Front Panel is the user interface of your VI

Once populated with:

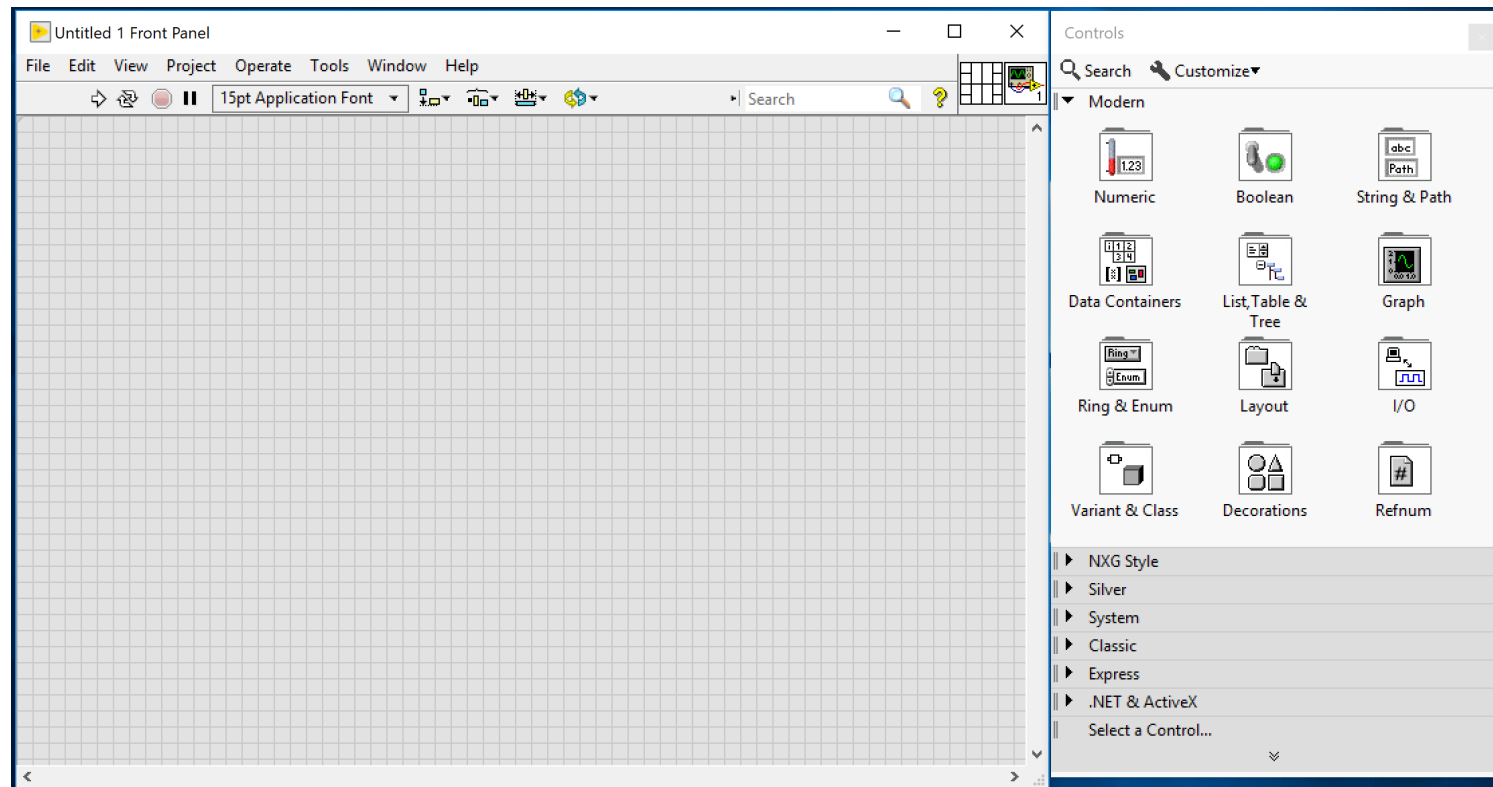
- controls
- indicators
- graphs

it will appear as the front panel of a real instrument

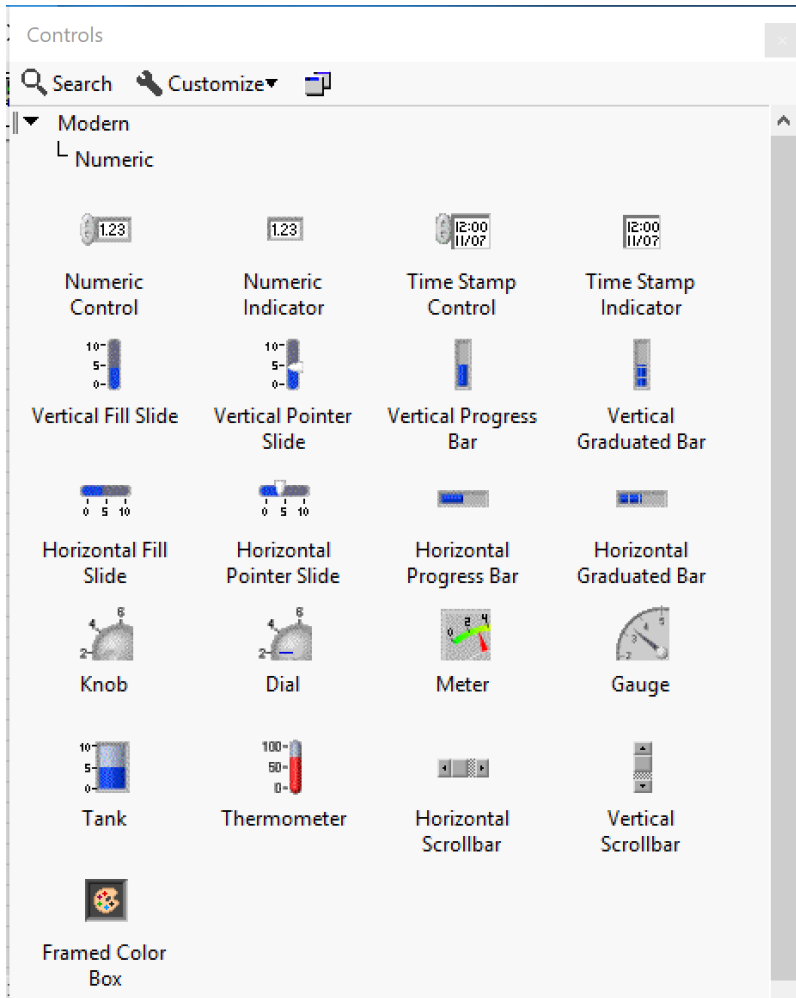


Controls Palette

In order to introduce new controls and switches we can use
View → Controls Palette

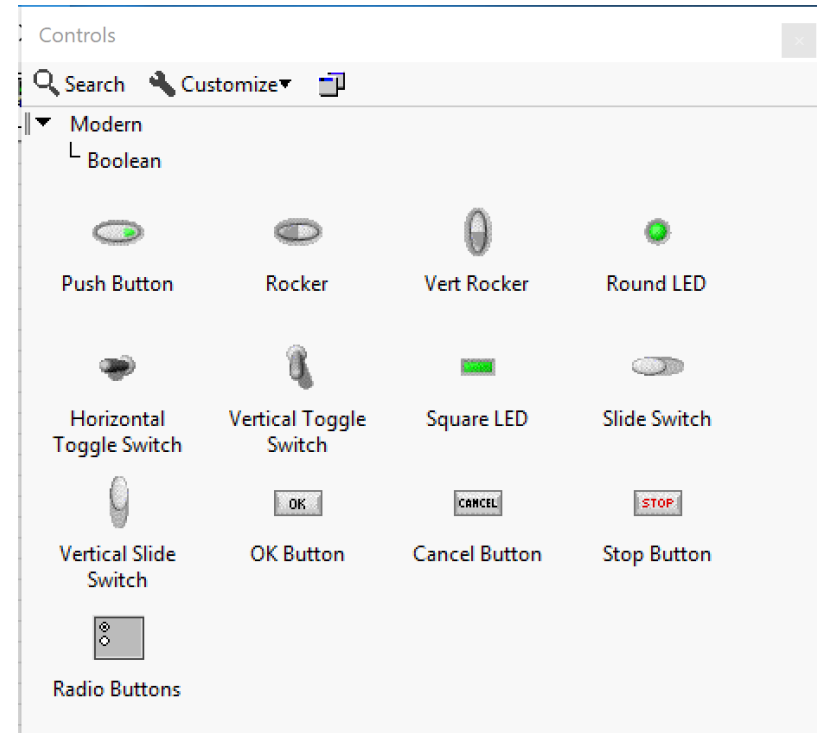


Controls types



← Numeric

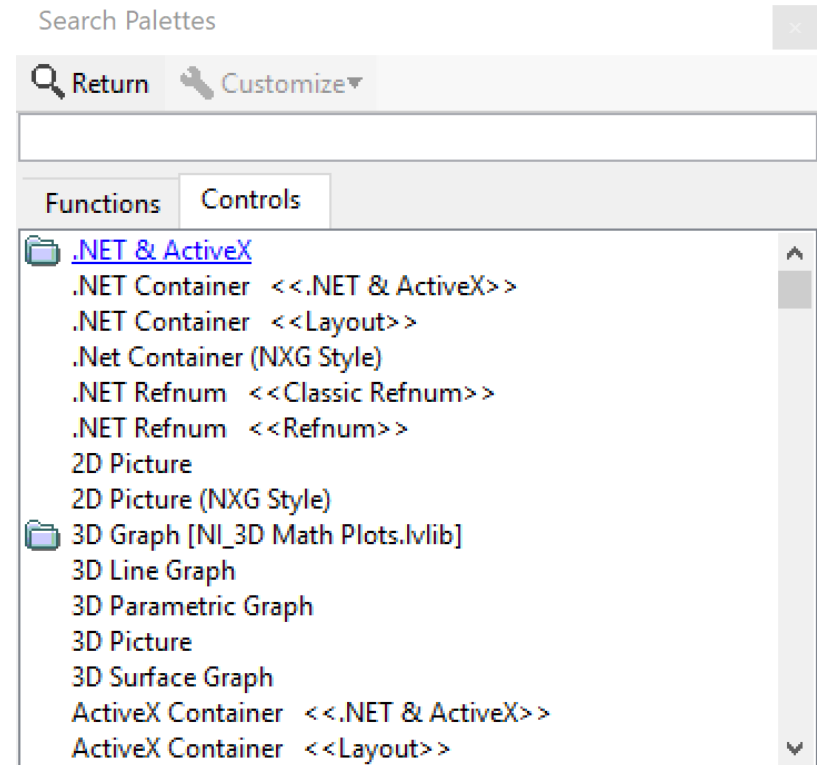
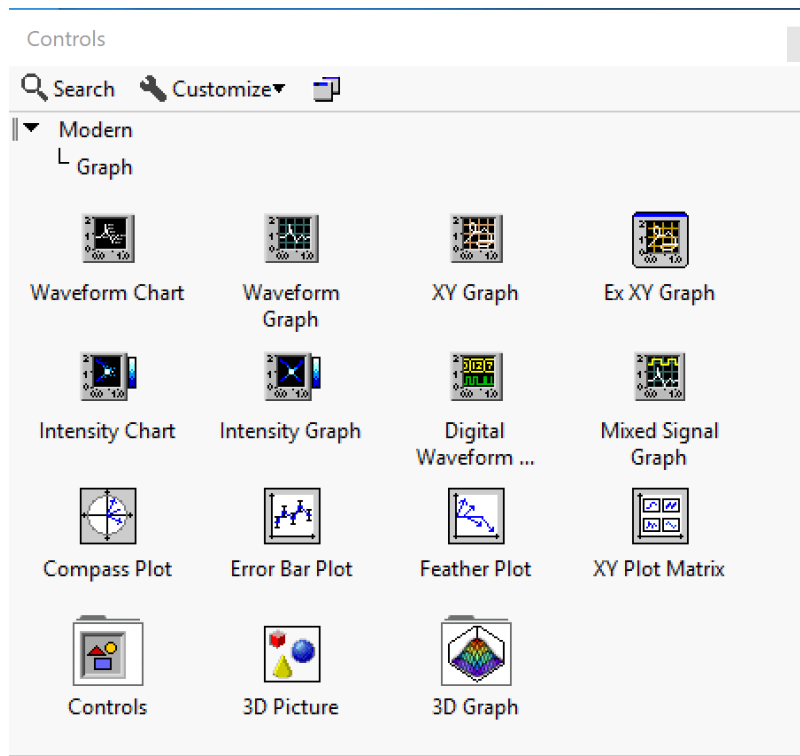
Boolean ↘



Controls types

Graph

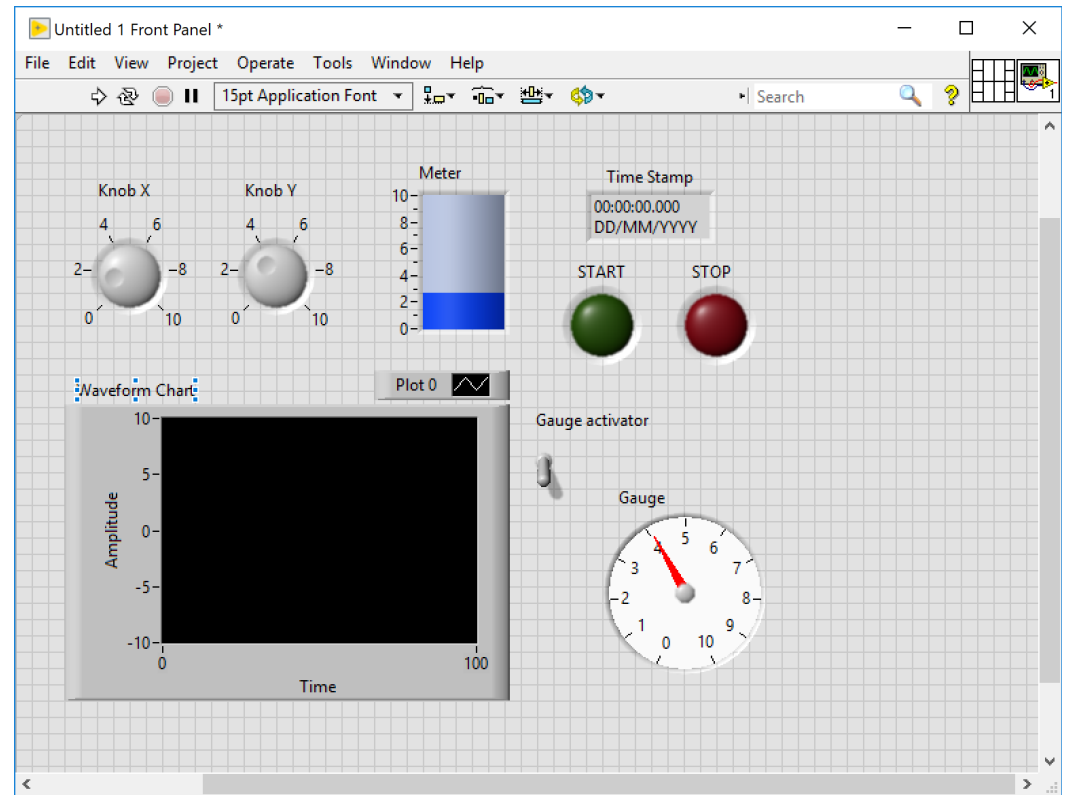
Search into the library



Example

Just by dragging and dropping on the front panel, we get...

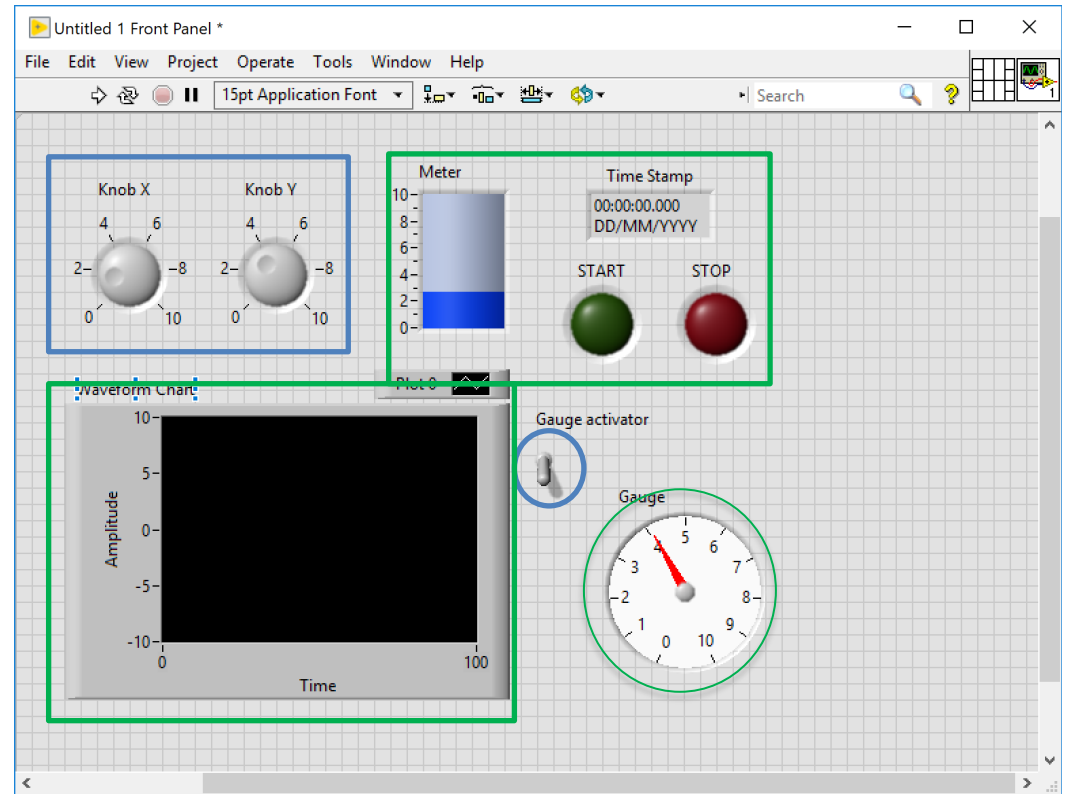
- manual controls
- digital controls
- switches/leds
- gauge/tank meter



Controls vs Indicators

The same difference between function inputs and outputs:

- **Controls (inputs)**
the user can set specific parameters or trigger specific operations
- **Indicators (output)**
the user can visualize the results or the process state through numbers or graphical tools



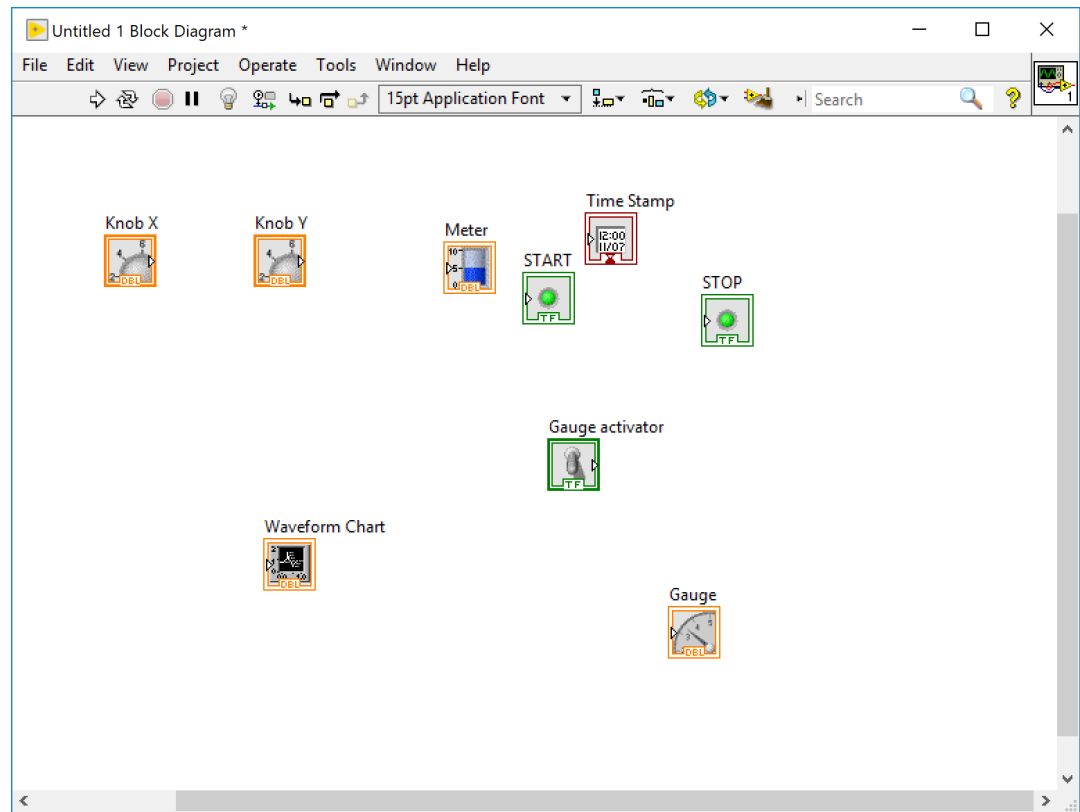
Block Diagram

Every time you drag something on the front panel you have its counterpart on the block diagram, where you can:

- connect them
- move them

NB#1: NO ZOOM

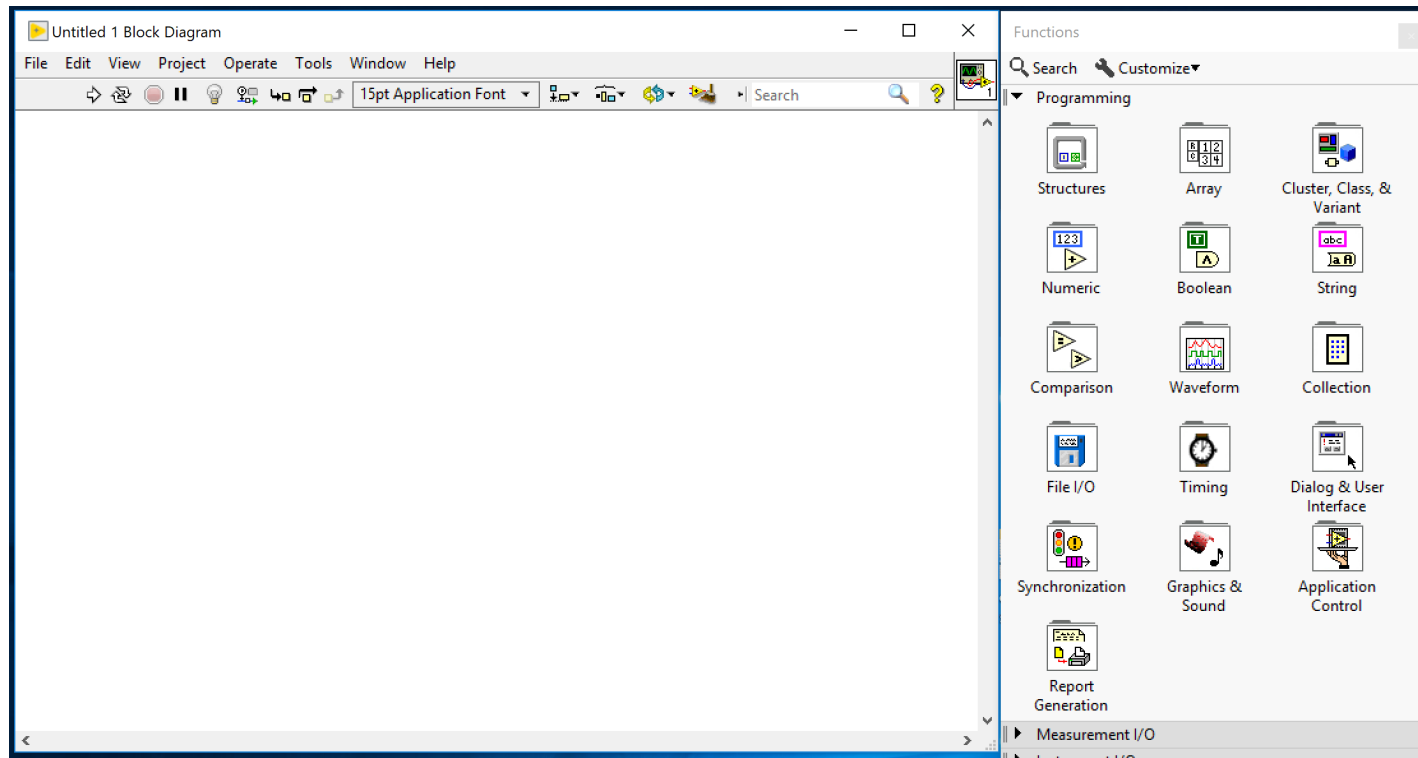
NB#2: if you delete here it will disappear also in the front panel!



Functions Palette

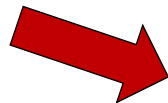
Controls and indicators can be connected in several ways

View → Functions Palette



Numeric

NB: In the block diagram it is also possible to create constants: values that are not modifiable by the user (controls) or by the execution of the program (indicators).







































Functions

Search Customize

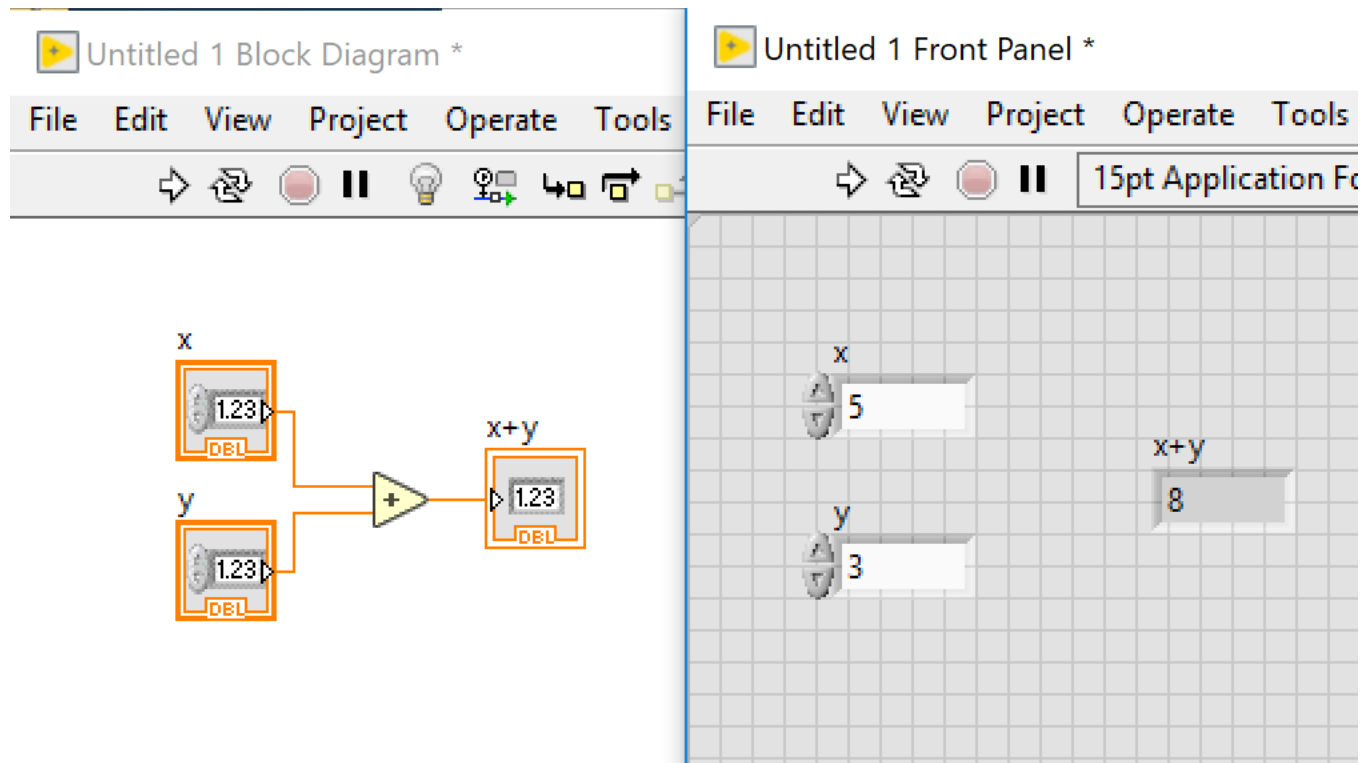
Programming

Numeric

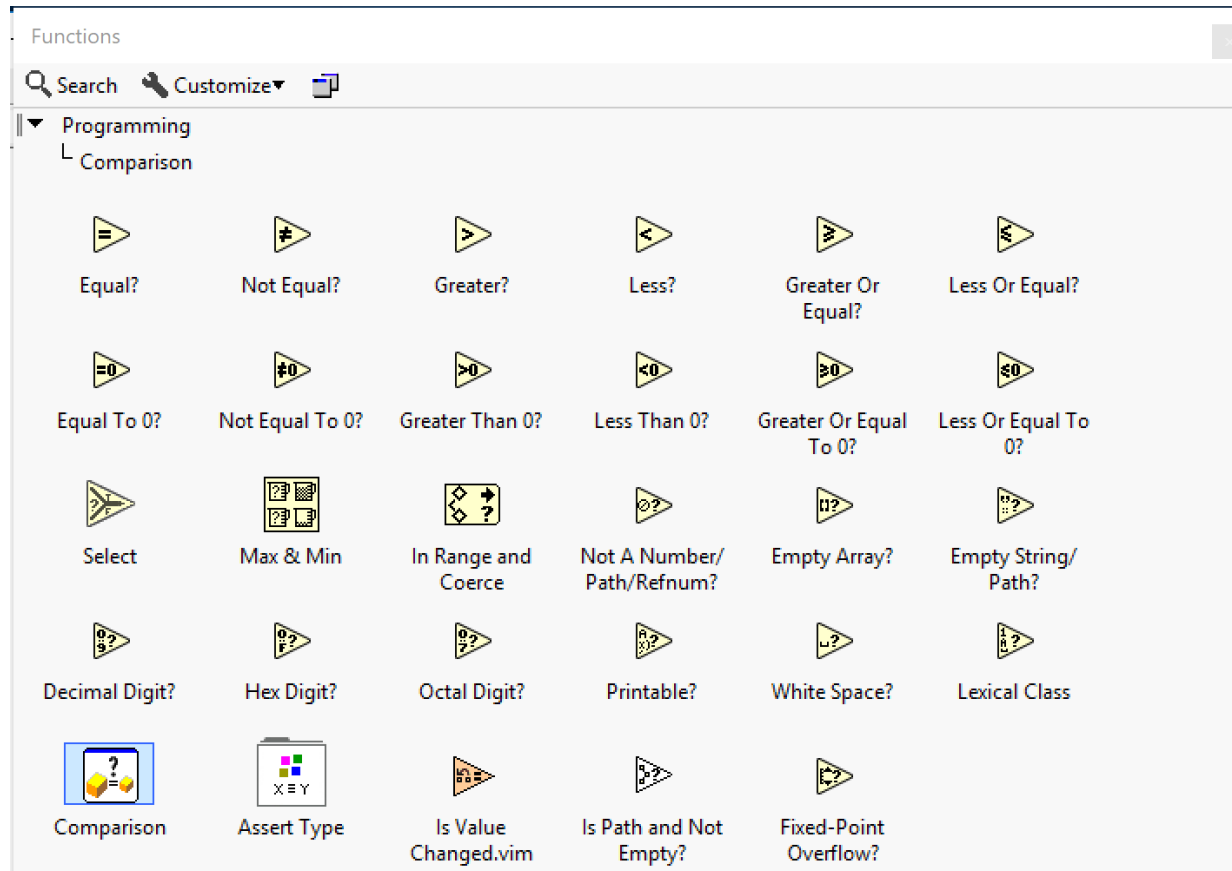
 Add	 Subtract	 Multiply	 Divide	 Quotient & Remainder	 Conversion
 Increment	 Decrement	 Add Array Elements	 Multiply Array Elements	 Compound Arithmetic	 Data Manipulation
 Absolute Value	 Round To Nearest	 Round Toward -Infinity	 Round Toward +Infinity	 Scale By Power Of 2	 Complex
 Square Root	 Square	 Negate	 Reciprocal	 Sign	 Scaling
 Numeric Constant	 Enum Constant	 Ring Constant	 Random Number (0-1)	 Random Number ...	 Fixed-Point
 DBL Numeric Constant	 +Inf	 -Inf	 Machine Epsilon	 Not A Number Constant	 Math Constants

Numeric example

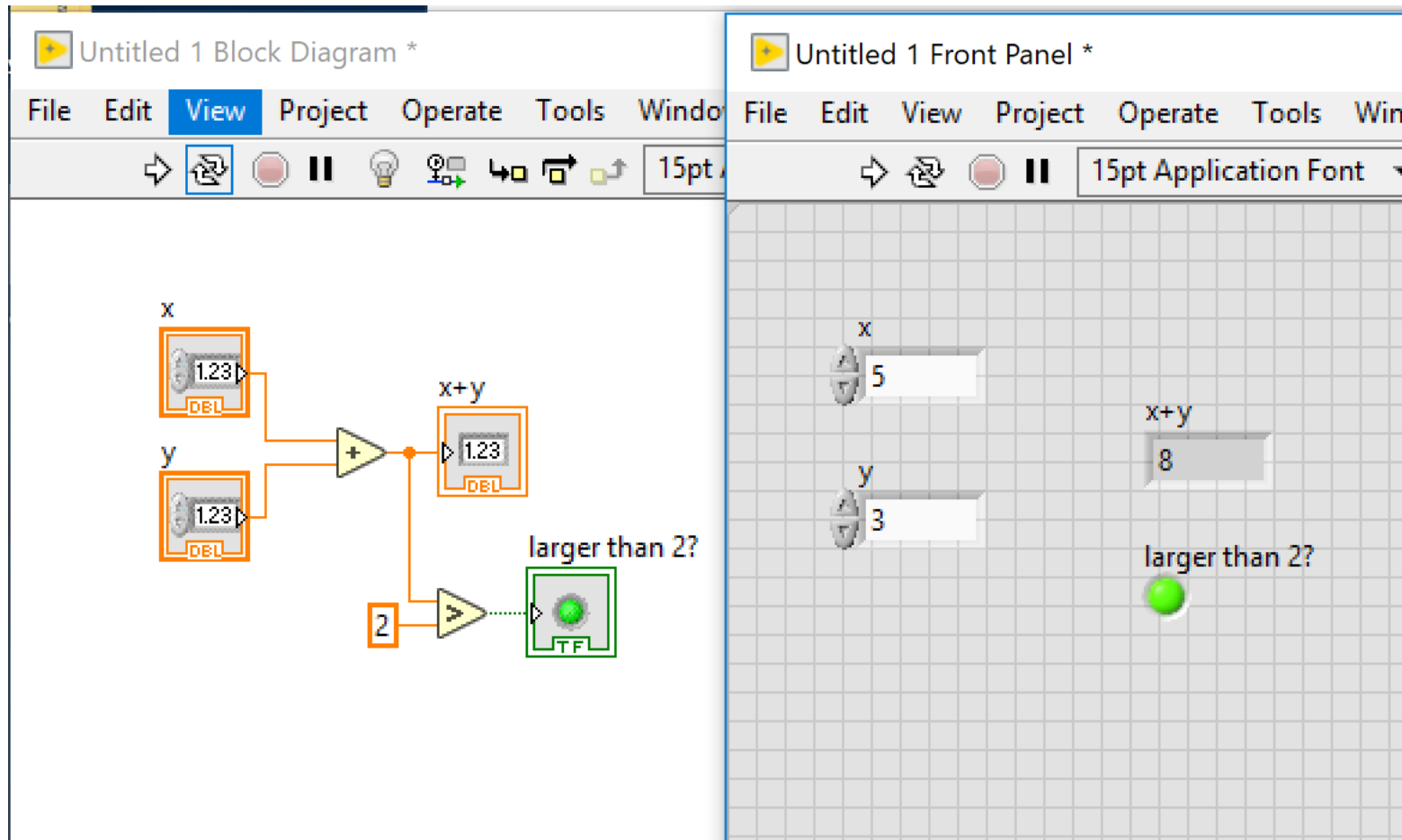
- The sum of two numbers requires two control, a function and one indicator



Comparison



Comparison example



Tools Palette

Since LabVIEW is a graphical programming language it is important to use the mouse and the cursor..

View → Tools Palette



Automatic selection



Operating



Positioning



Labeling



Wiring



Shortcut



Scrolling



Setting a breakpoint



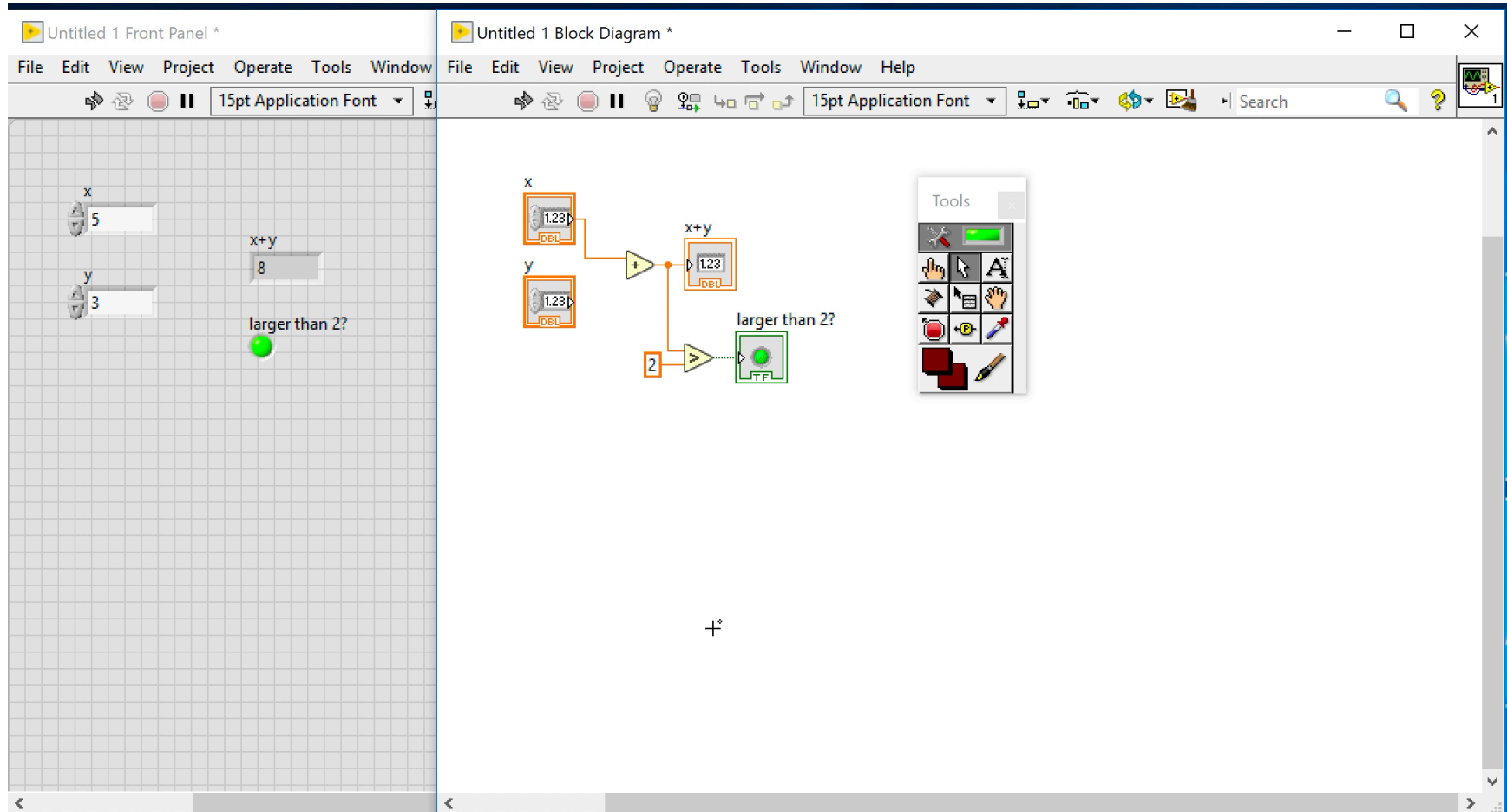
Probing



Picking a color



Tools example



Help

If you don't know what something is, you just ask for help...

The image illustrates how to access help in LabVIEW. It shows a block diagram with an 'Add' function and a 'larger than?' function. A red arrow points from the 'Add' function to a 'Context Help' window. On the right, a 'LabVIEW Help' window is open to the 'Add Function' page, showing a table of contents, a search bar, and detailed documentation for the 'Add' function, including requirements, description, and a note about data type configuration. A red arrow points from the 'Context Help' window to the 'LabVIEW Help' window.

Execution modes

When the code is ready, we can run it!



Run the code once



If there is something wrong in the code, e.g. a block disconnected, the arrow is broken and the code cannot be run.



Run the code iteratively



Abort the execution

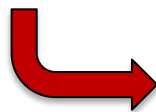
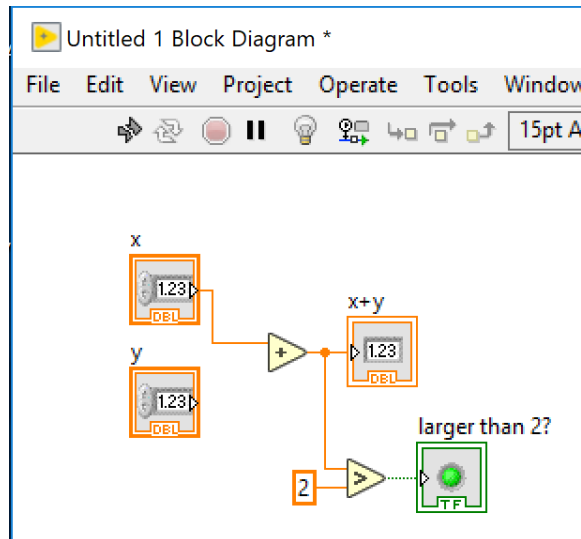


Pause the execution



Run in DEBUG mode

Broken arrow



Untitled 1 Block Diagram *

File Edit View Project Operate Tools Window

15pt A

x

y

x+y

larger than ?

2

Error list

Items with errors

✖ Untitled 1

1 errors and warnings Show Warnings

● Block Diagram Errors

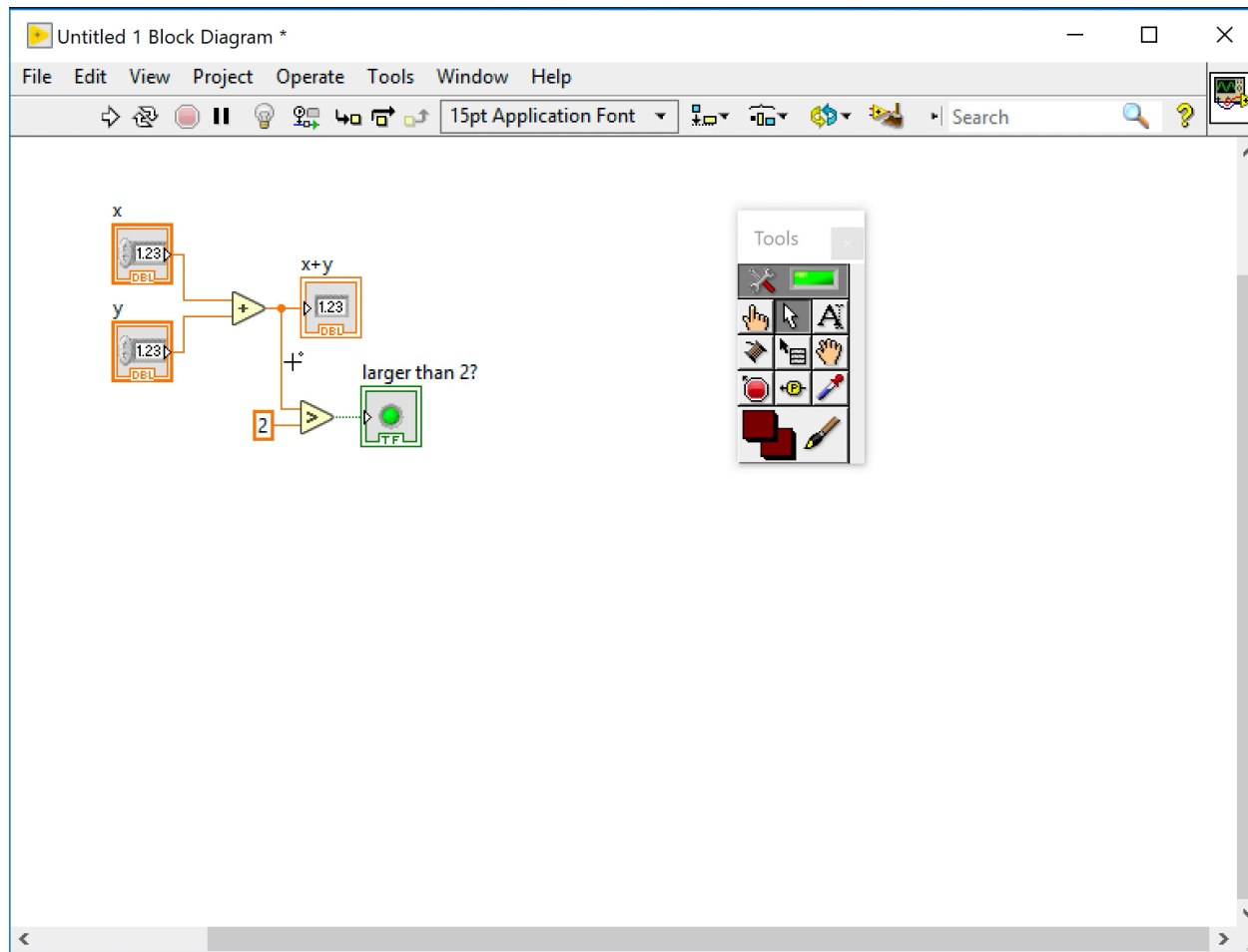
Add: Contains unwired or bad terminal

Details

One or more required inputs to this function are not wired or are wired incorrectly. Show the Context Help window to see what the connections to this function should be.

Close Show Error Help

Debug example



Recap: was everything clear?

- What's the difference between block diagram and front panel?
- What's the difference between a control, a constant and an indicator?
- What are the main tools in LabVIEW?

Data types & Structures

- Data Types
- Structures

Data Types

In LabVIEW we can deal with several types of data:

- String
- Numeric
- Boolean
- Enumerated
- Array
- Cluster

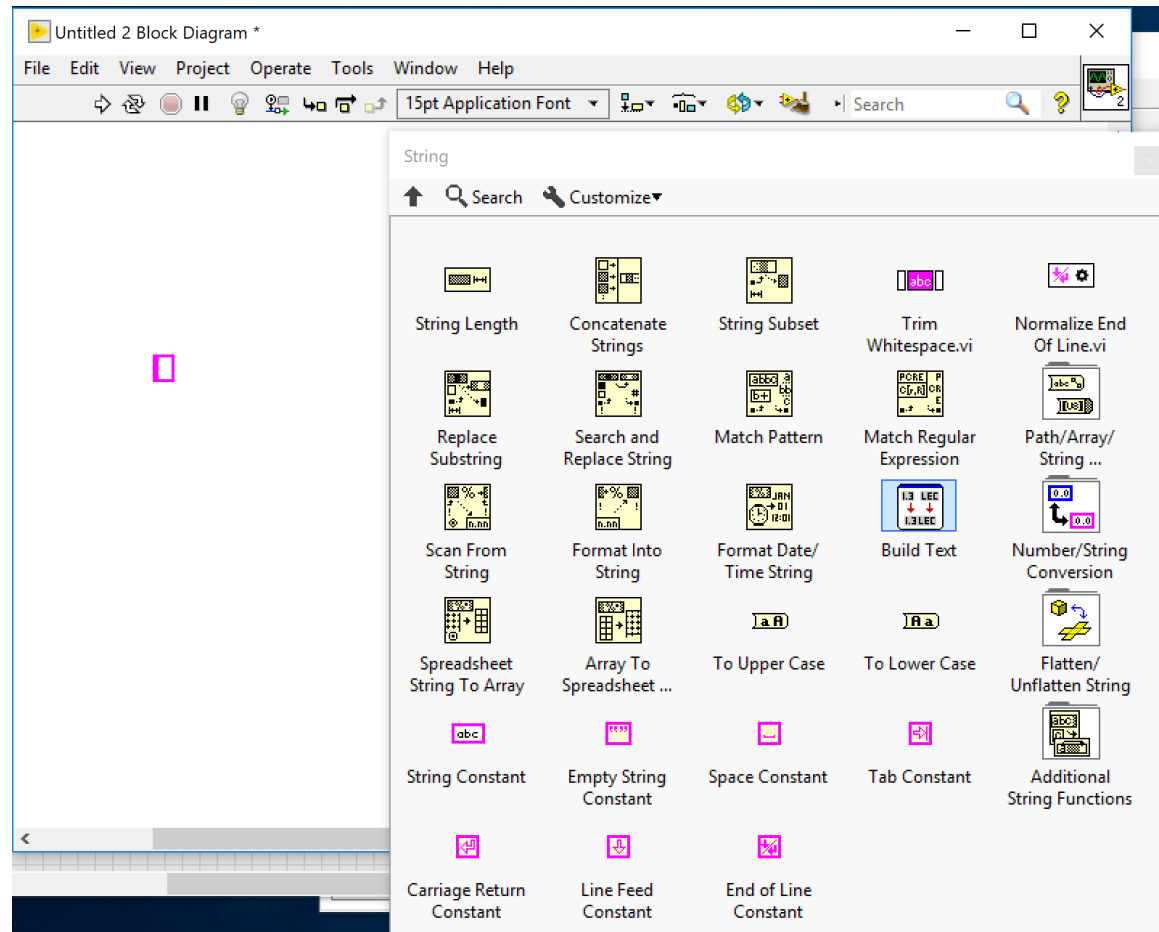
Each one is associated to a **specific color** in order to make it easy to distinguish them in the block diagram.

String

A string is just a sequence of ASCII characters.

In LabVIEW, it has to be delimited by a double “ ”.

The string colour is **PINK**.



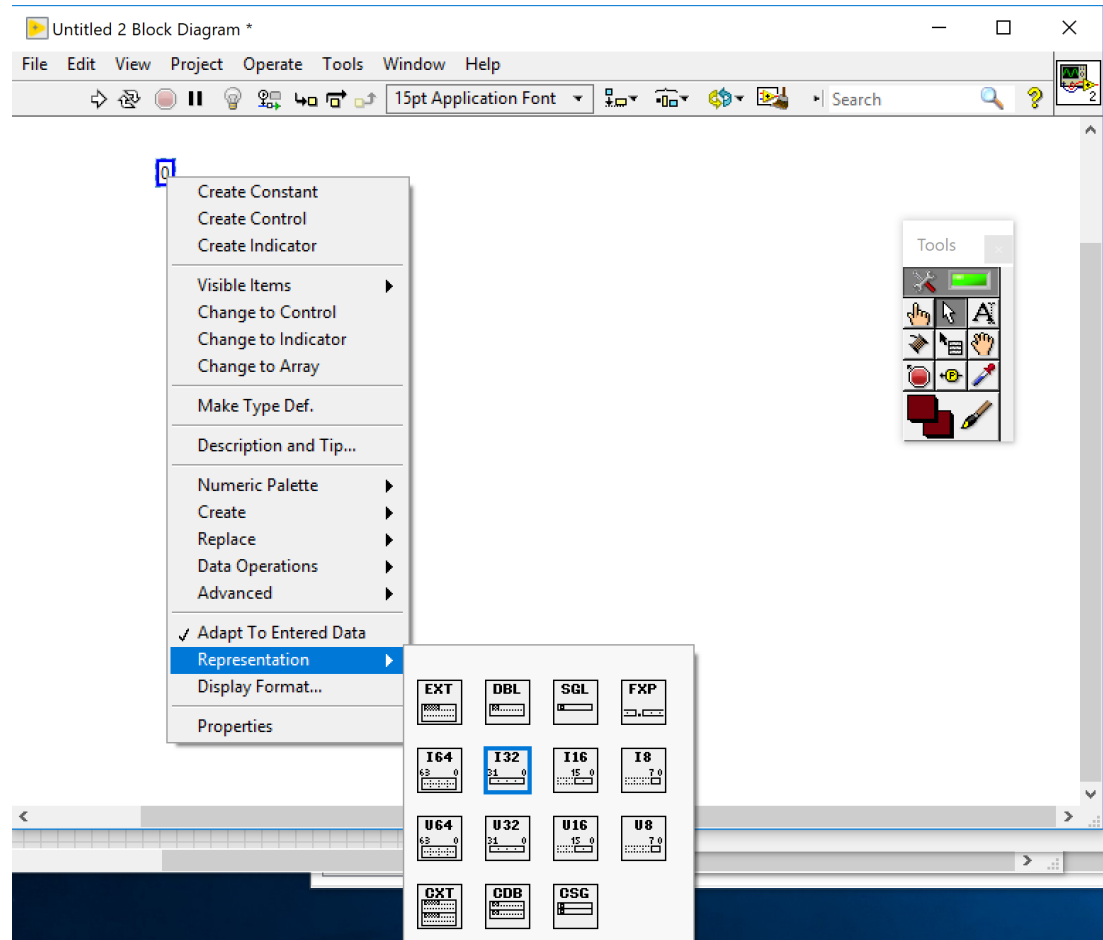
Numeric

In Labview there are several formats for numeric data:

- (un-)signed
- floating point
- fixed point
- extended

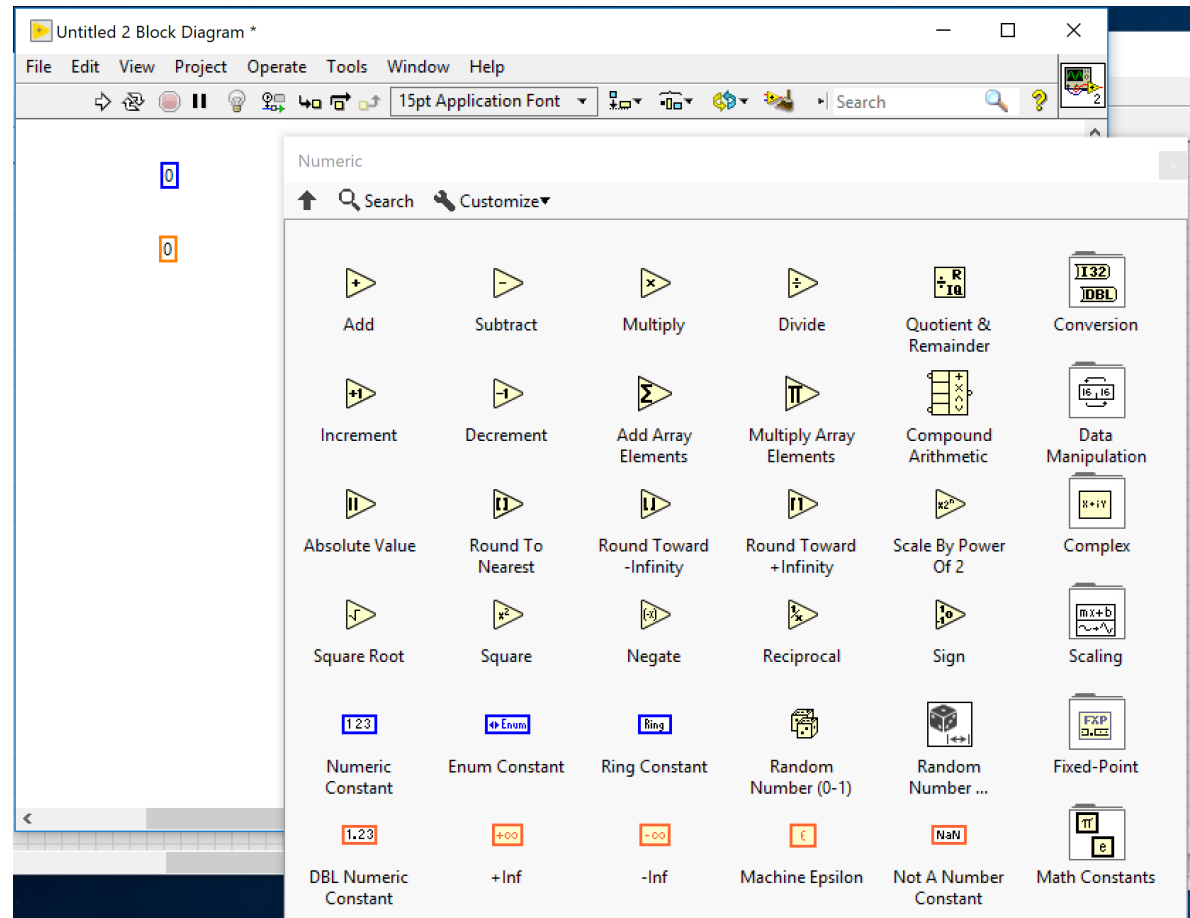
and resolutions:

- 8 bit
- 16 bit
- 32 bit



Numeric

The main numeric data types are:
 integer (**BLUE**)
 double (**ORANGE**)



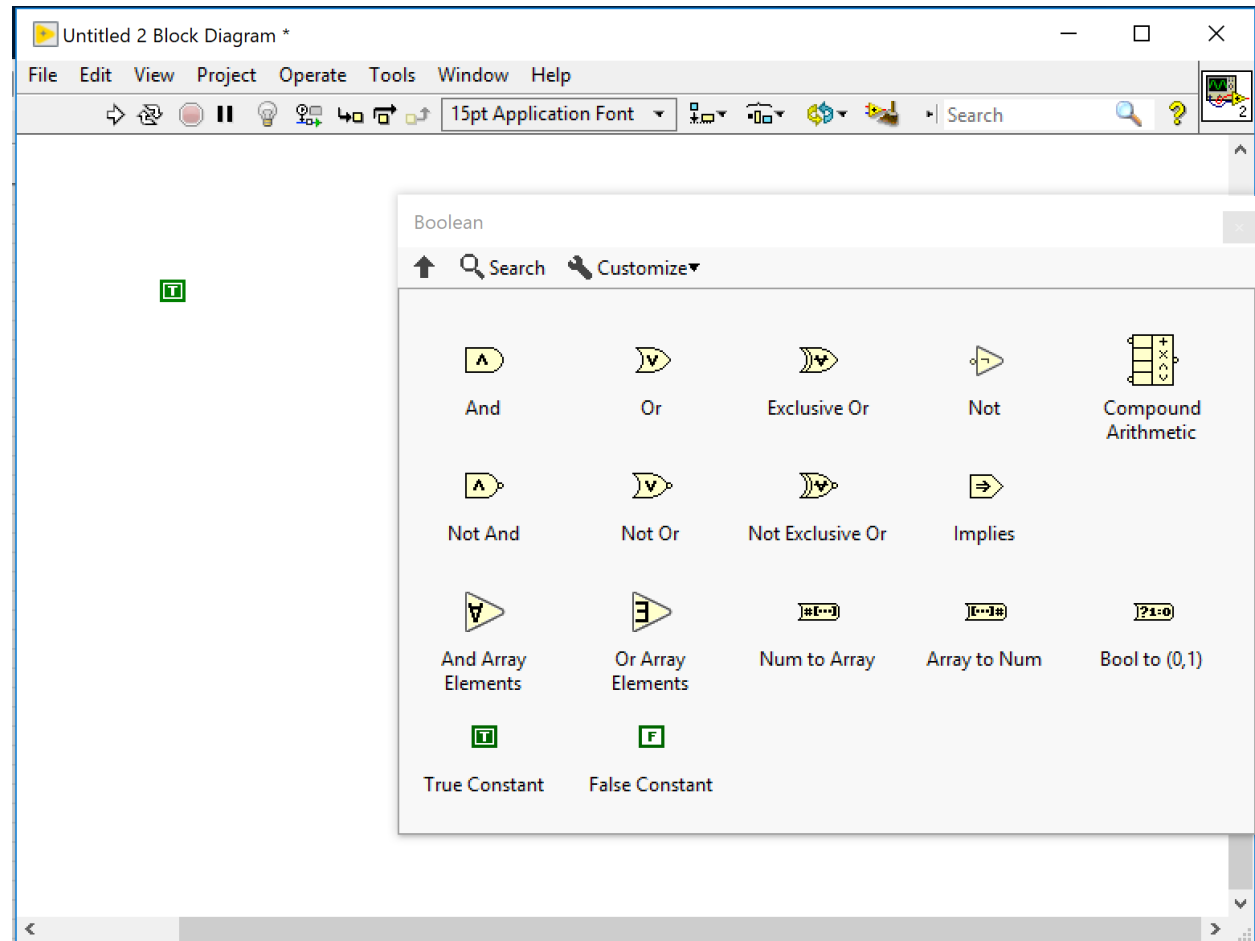
Boolean

Labview stores
Boolean in 8-bit
U8 constants:

0 → FALSE

1 → TRUE

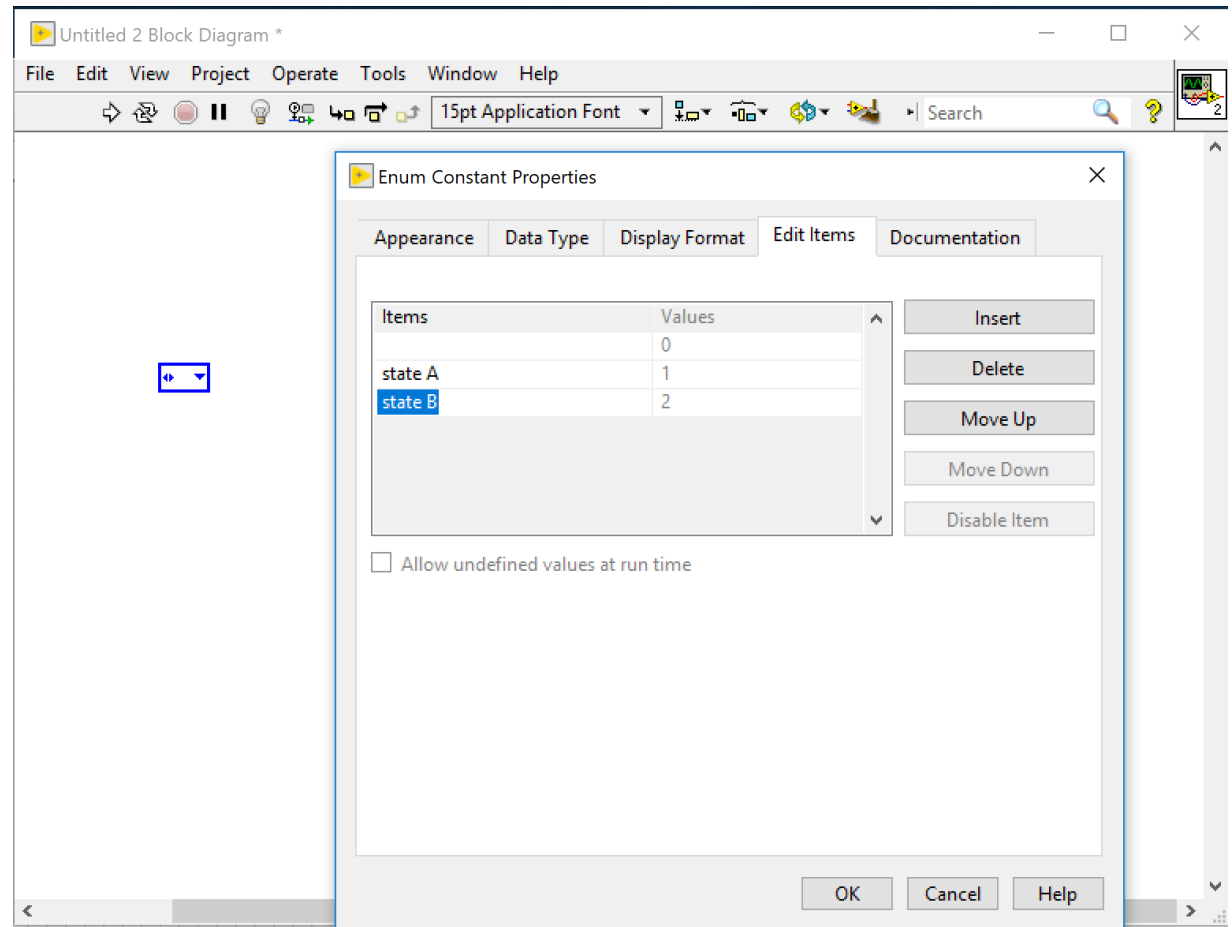
Boolean color
is **GREEN**.



Enumerated

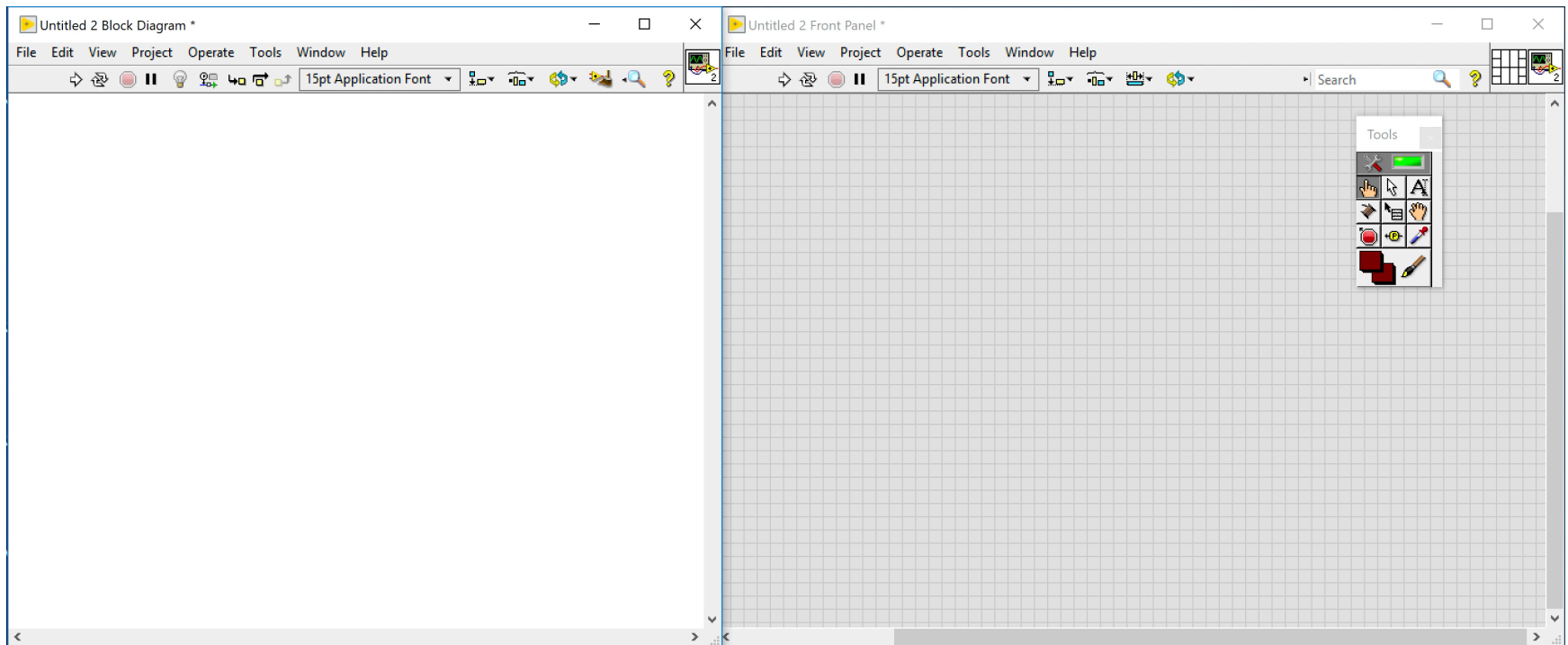
When you deal with a list of states, you can use an ENUM variable, i.e. an ordered list of strings.

Enum color is **DARK BLUE** (as an U8).



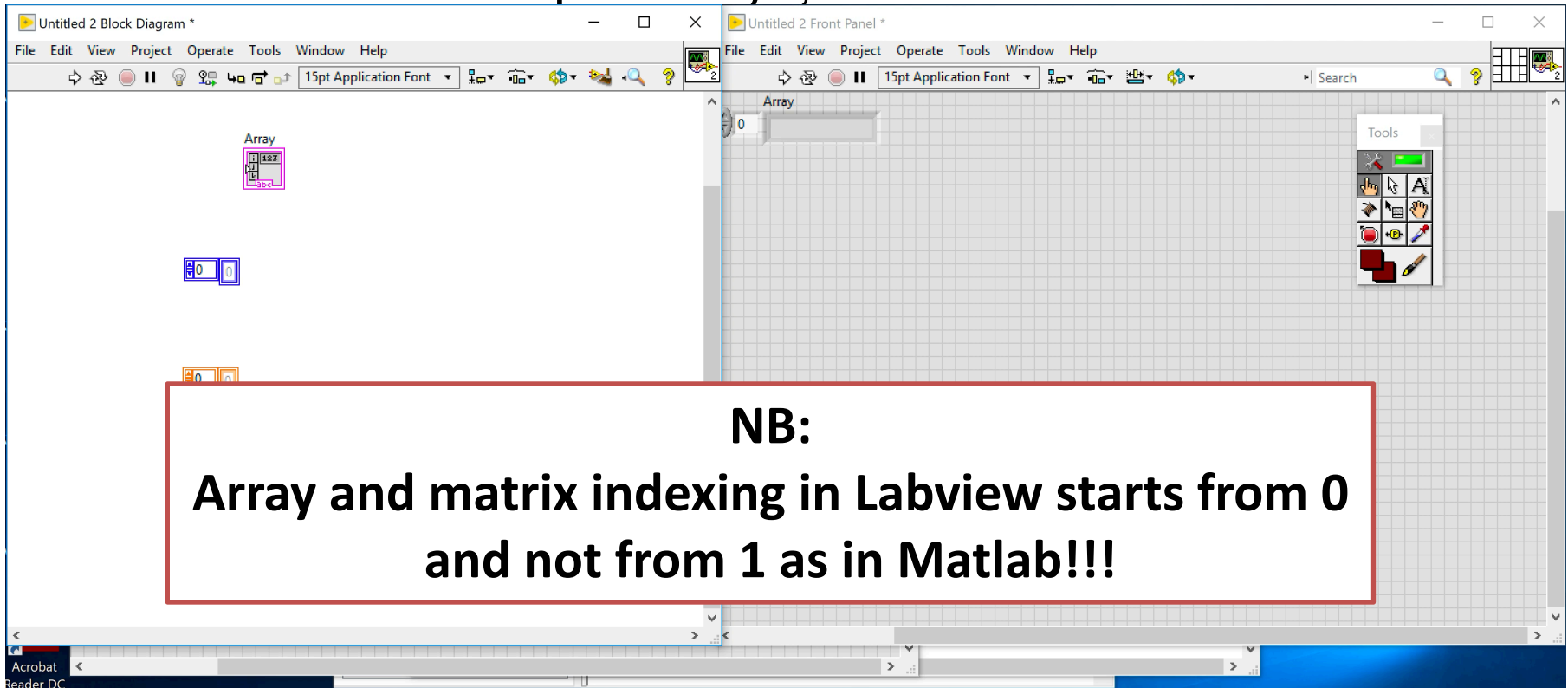
Arrays

If we need to store multiple values of the same data type:



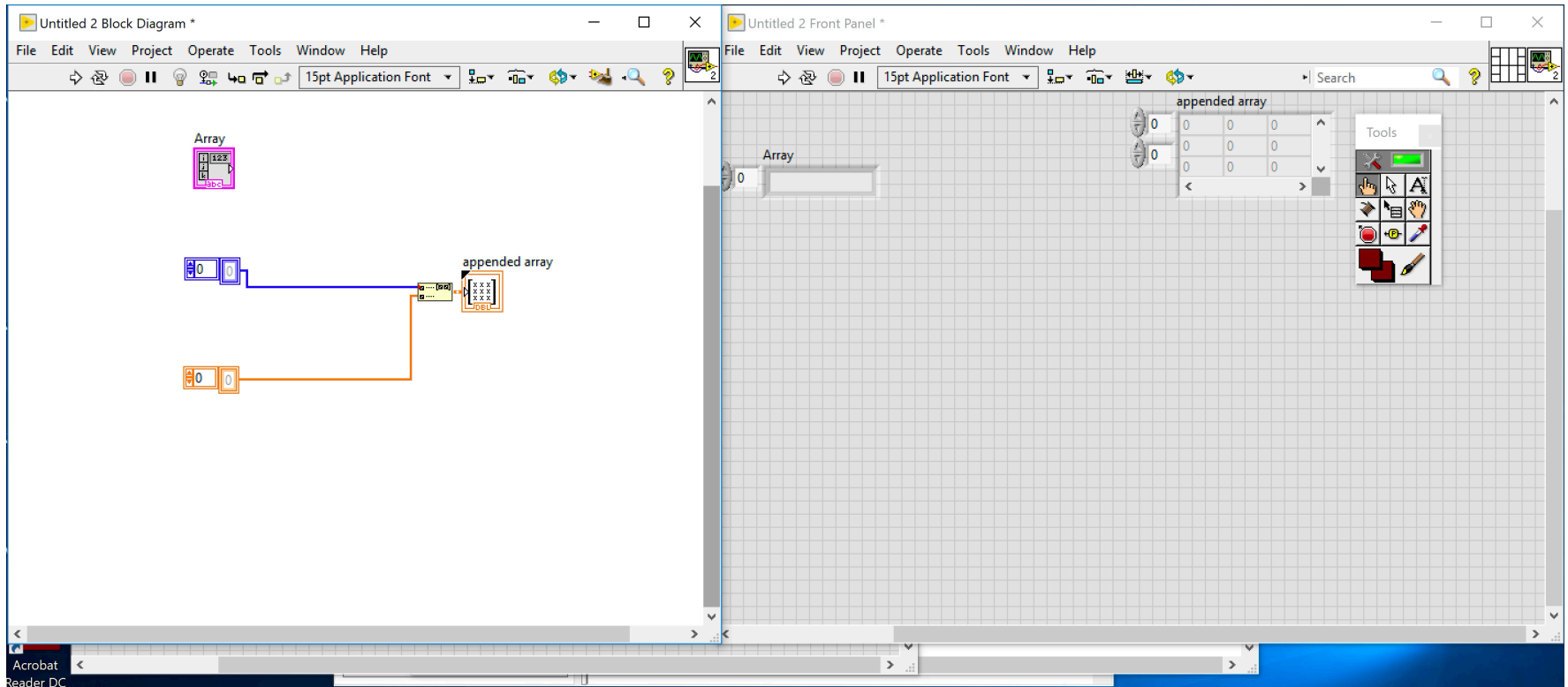
Matrices

When we have multiple arrays, we can build matrices



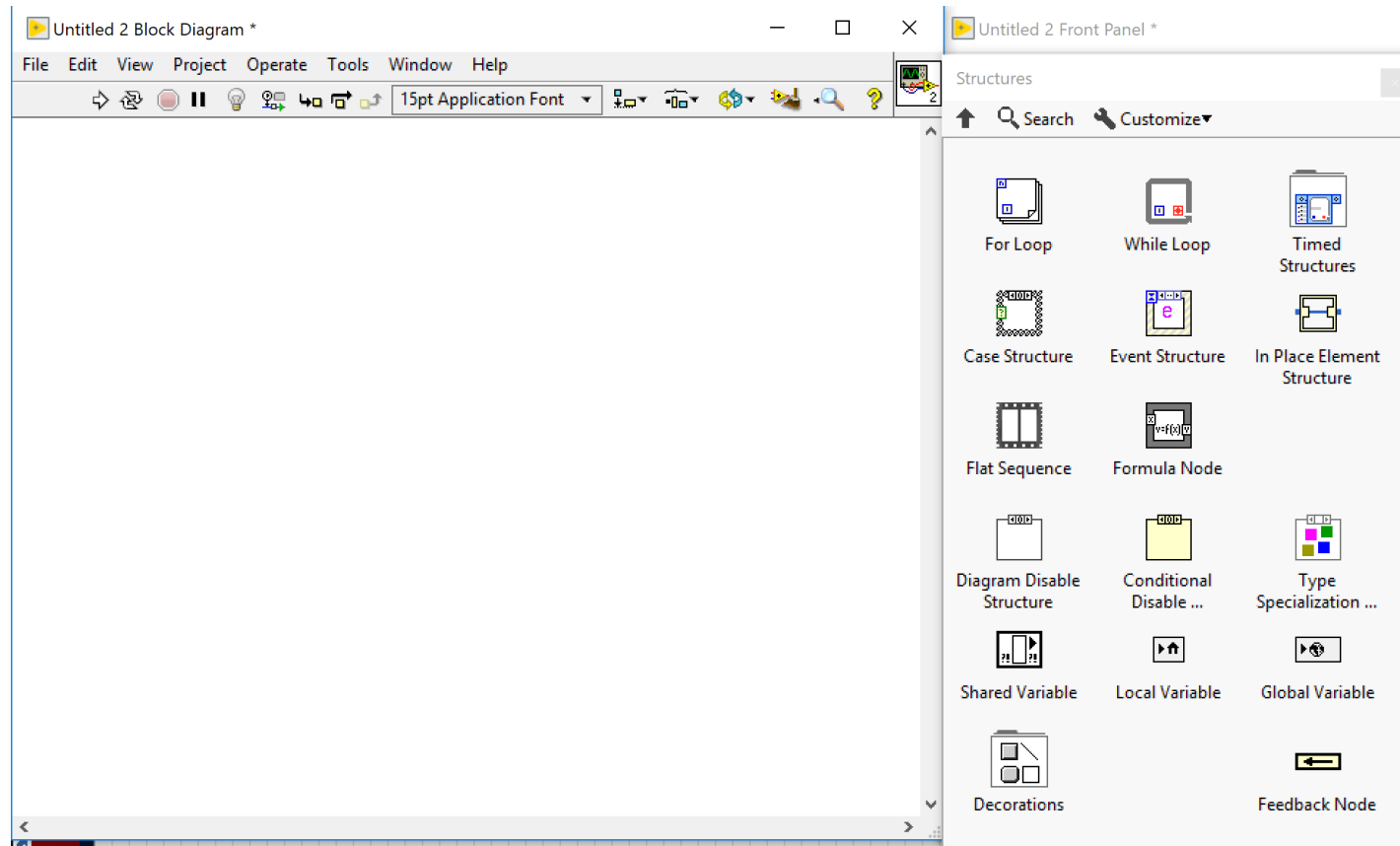
Clusters

If we need to store together different data types:



Structures

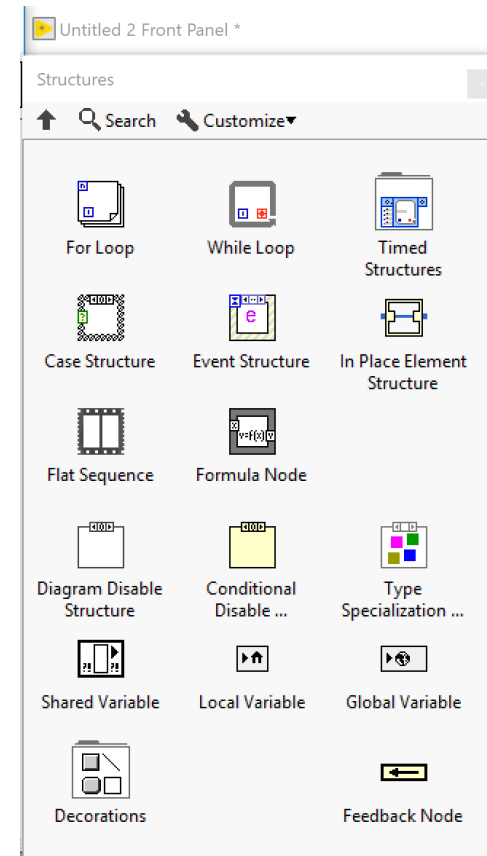
In a block diagram we can set loops and repetitions:



Structures

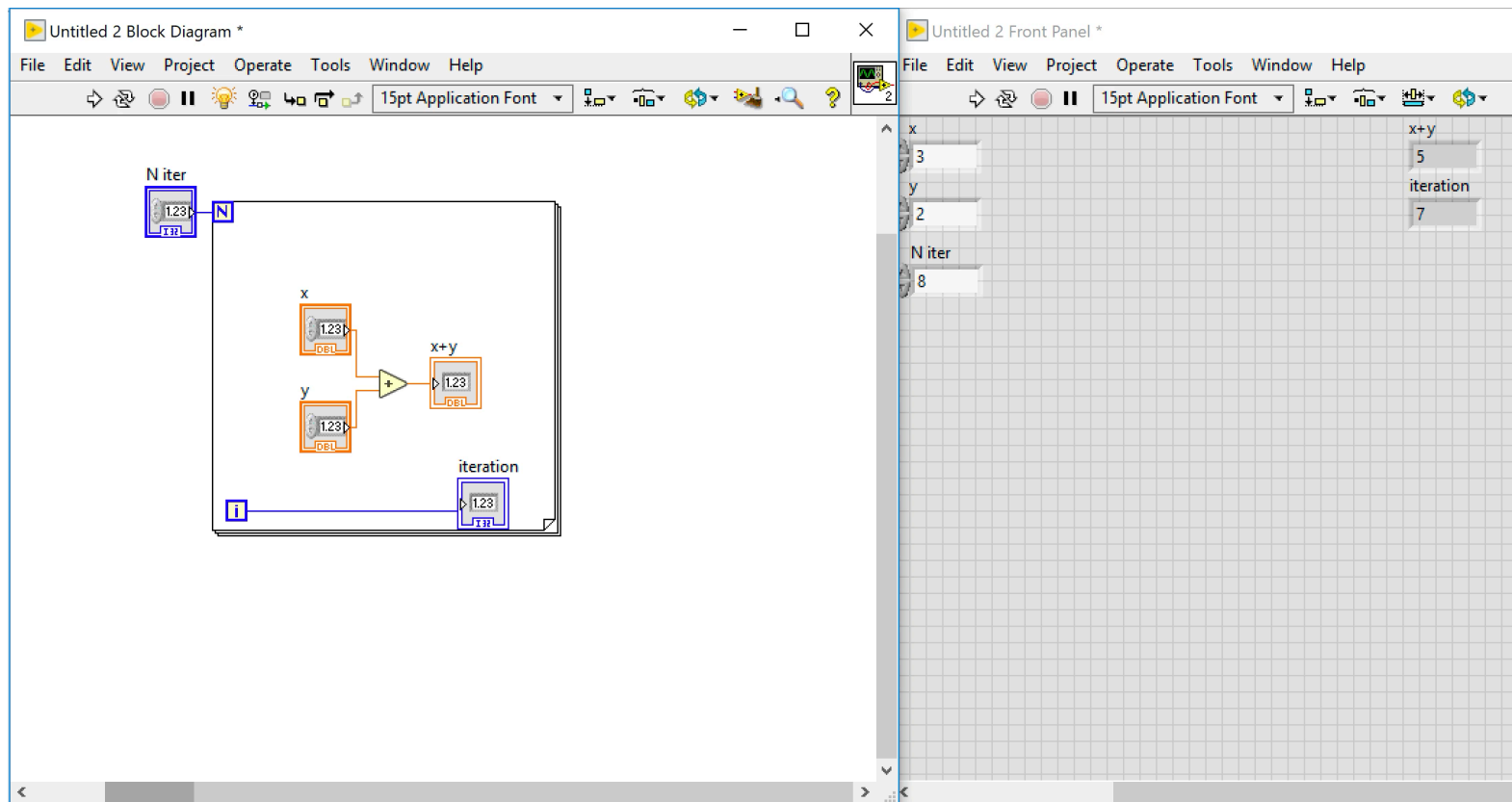
In LabVIEW the main structures that we can use are:

- For Loop
- While Loop
- Disable Structure
- Case Structure



For Loop

Whatever is within the loop is repeated iteratively N times



Tunneling options

Sometimes, we are interested in outputting some of the results computed within the loop.

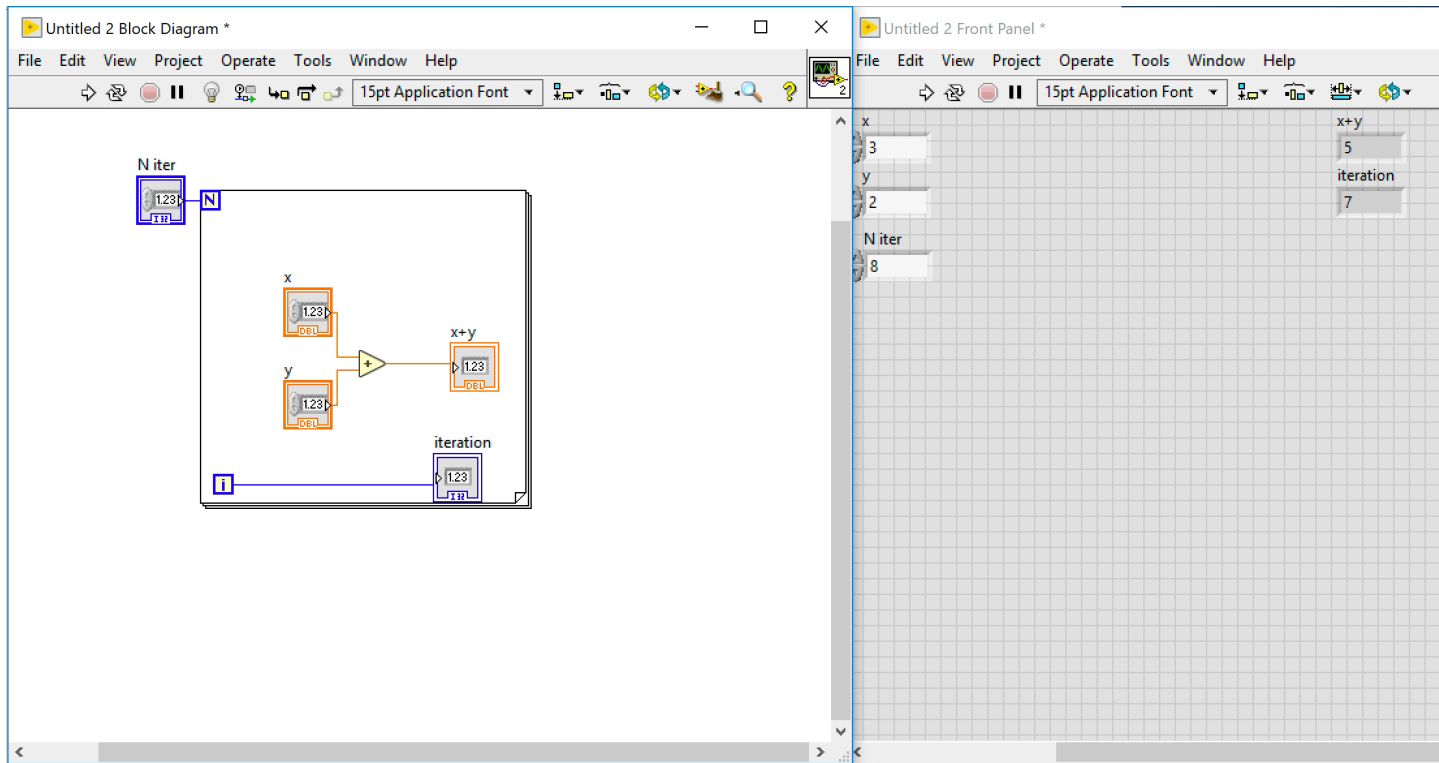
We have to create a sort of tunnel between the loop and the outer block diagram.

There are several tunneling options:

- Last value
- Indexing (concatenating for arrays)
- Conditional
- Shift register

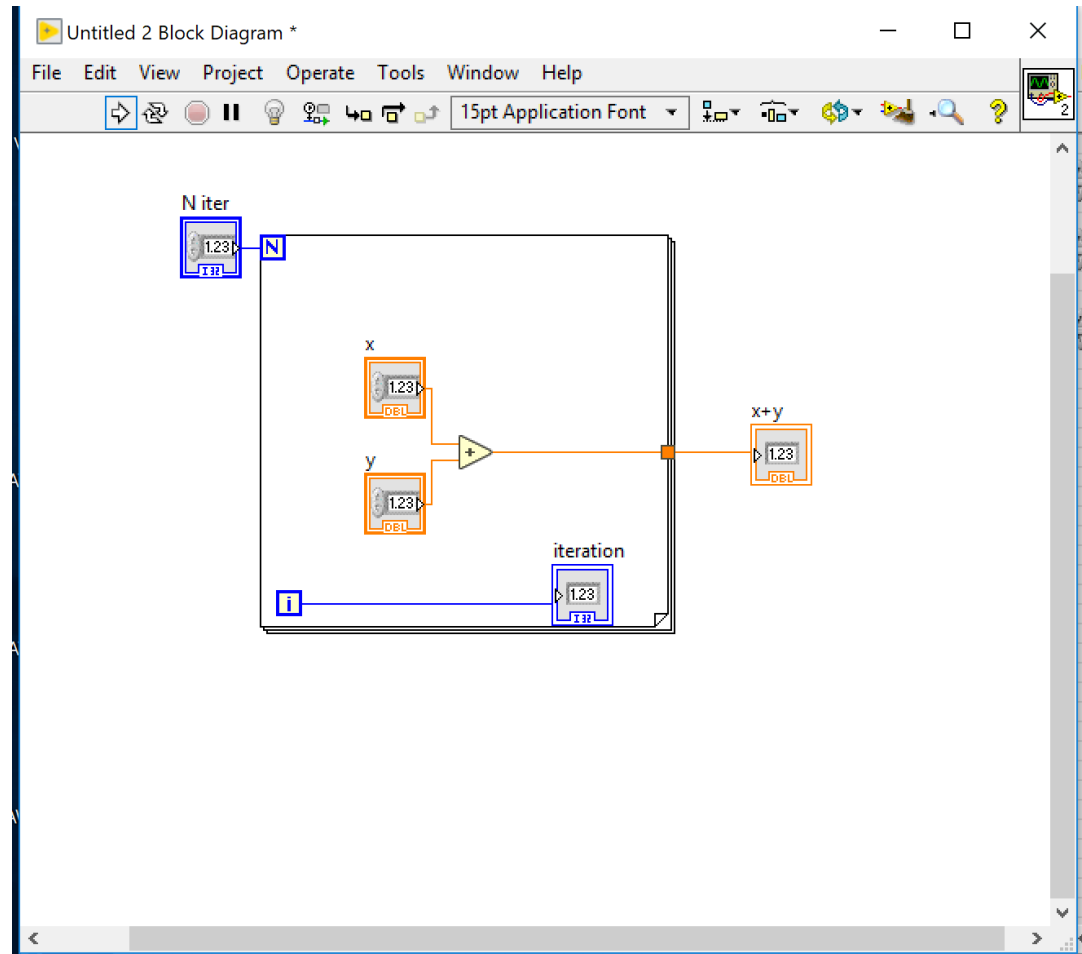
Tunneling options

Right click on the tunnel point:



Last value

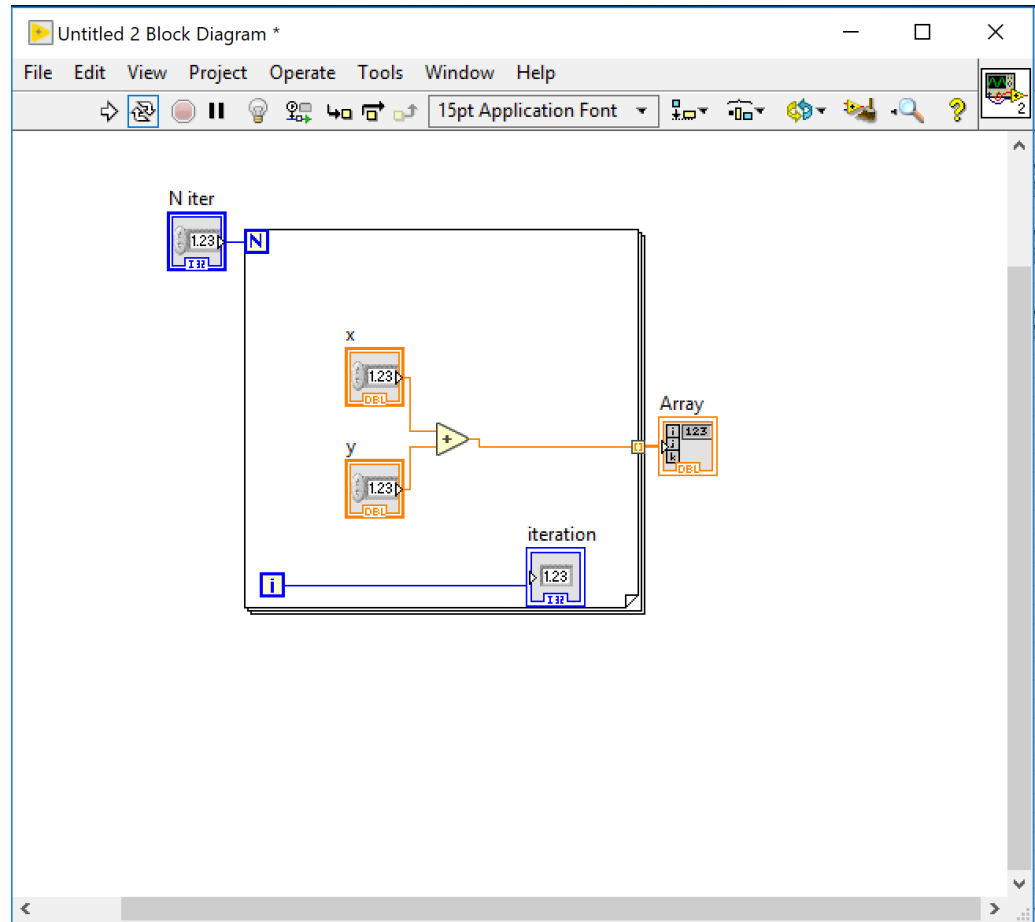
Only the value of the last iteration is saved in the output.



Indexing

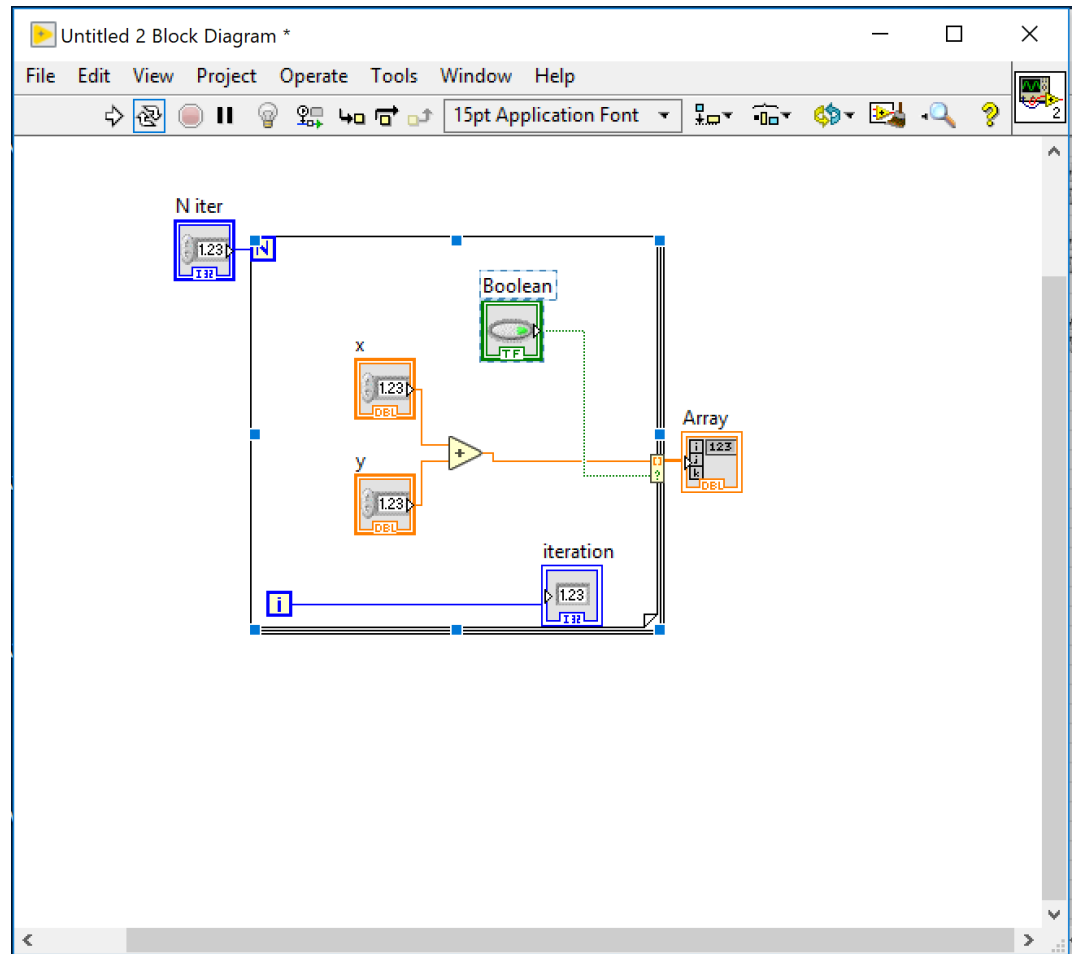
The result of each iteration is an entry of the output array.

If we are working with arrays, the option Concatenating produce a matrix.



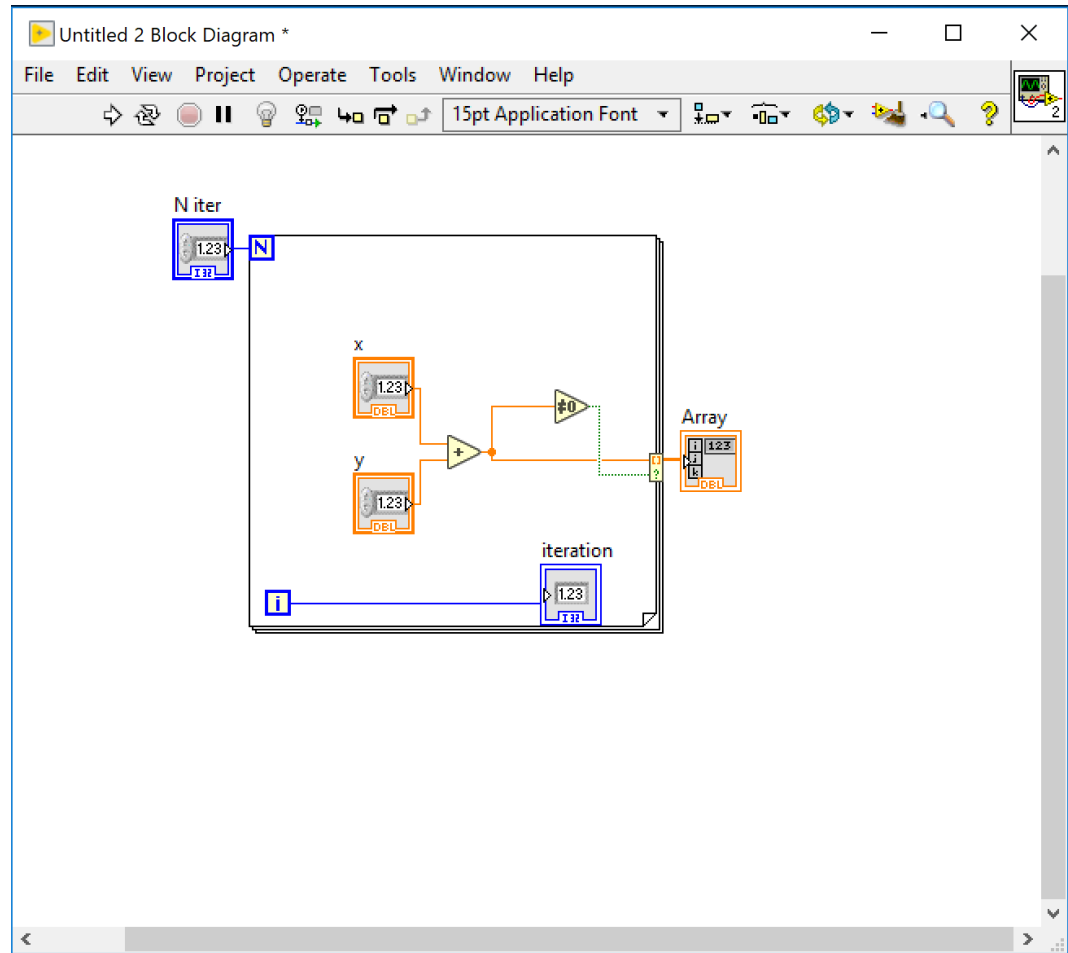
Conditional

In this case, the output is saved only if the Boolean control is set equal to TRUE.



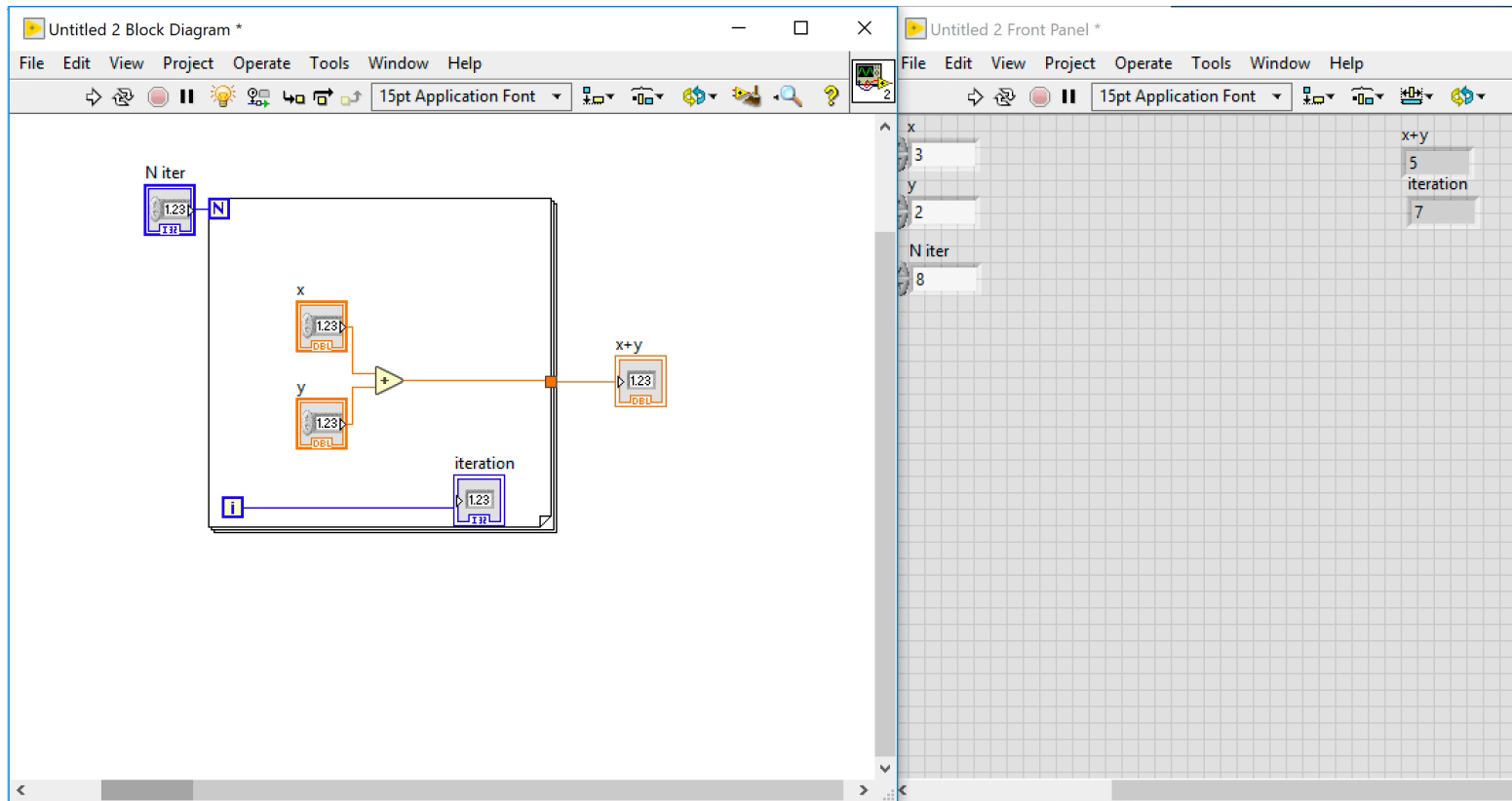
Conditional

... or a condition given by a Boolean variable.



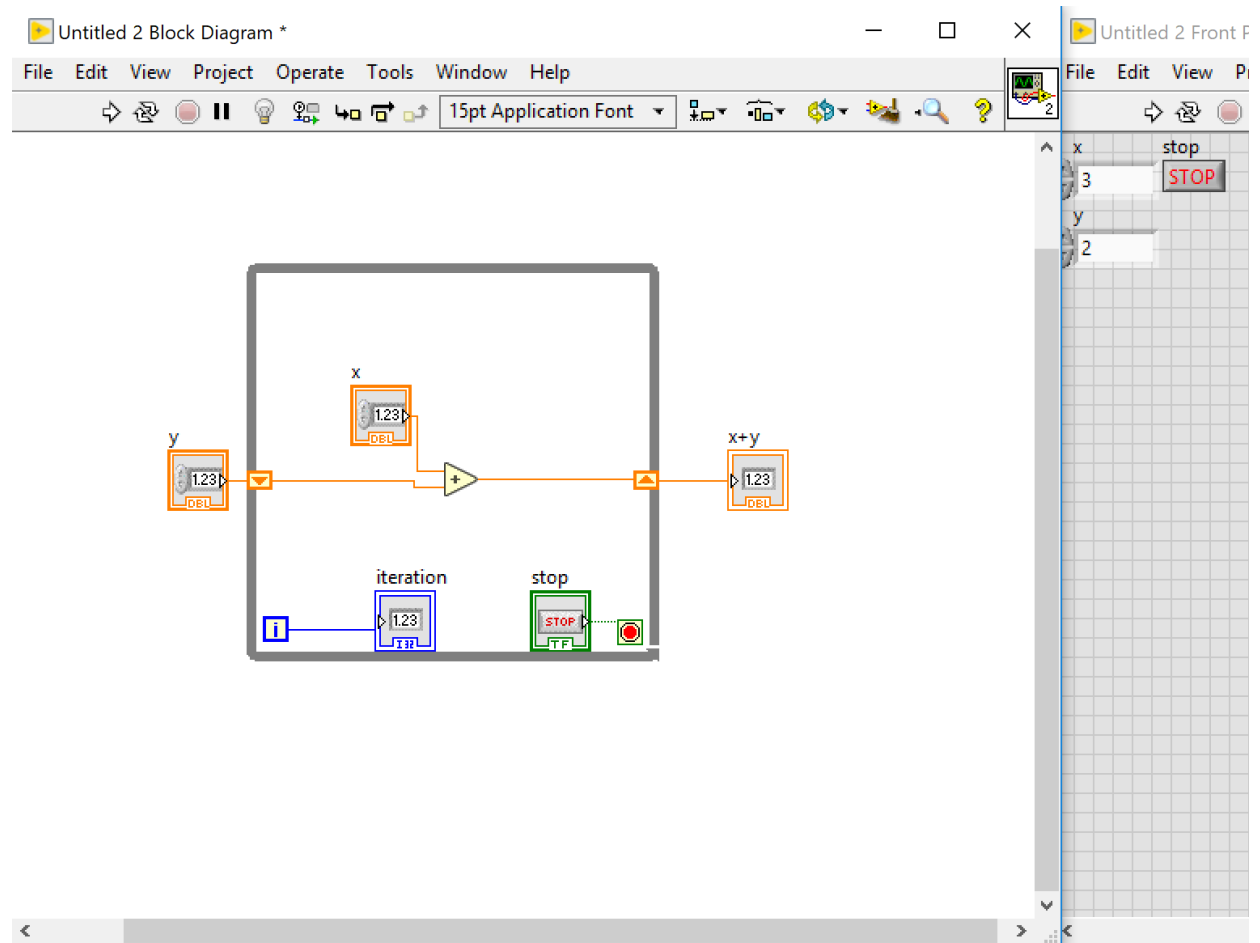
Shift register

Sometimes, we need to update the previous iteration result.



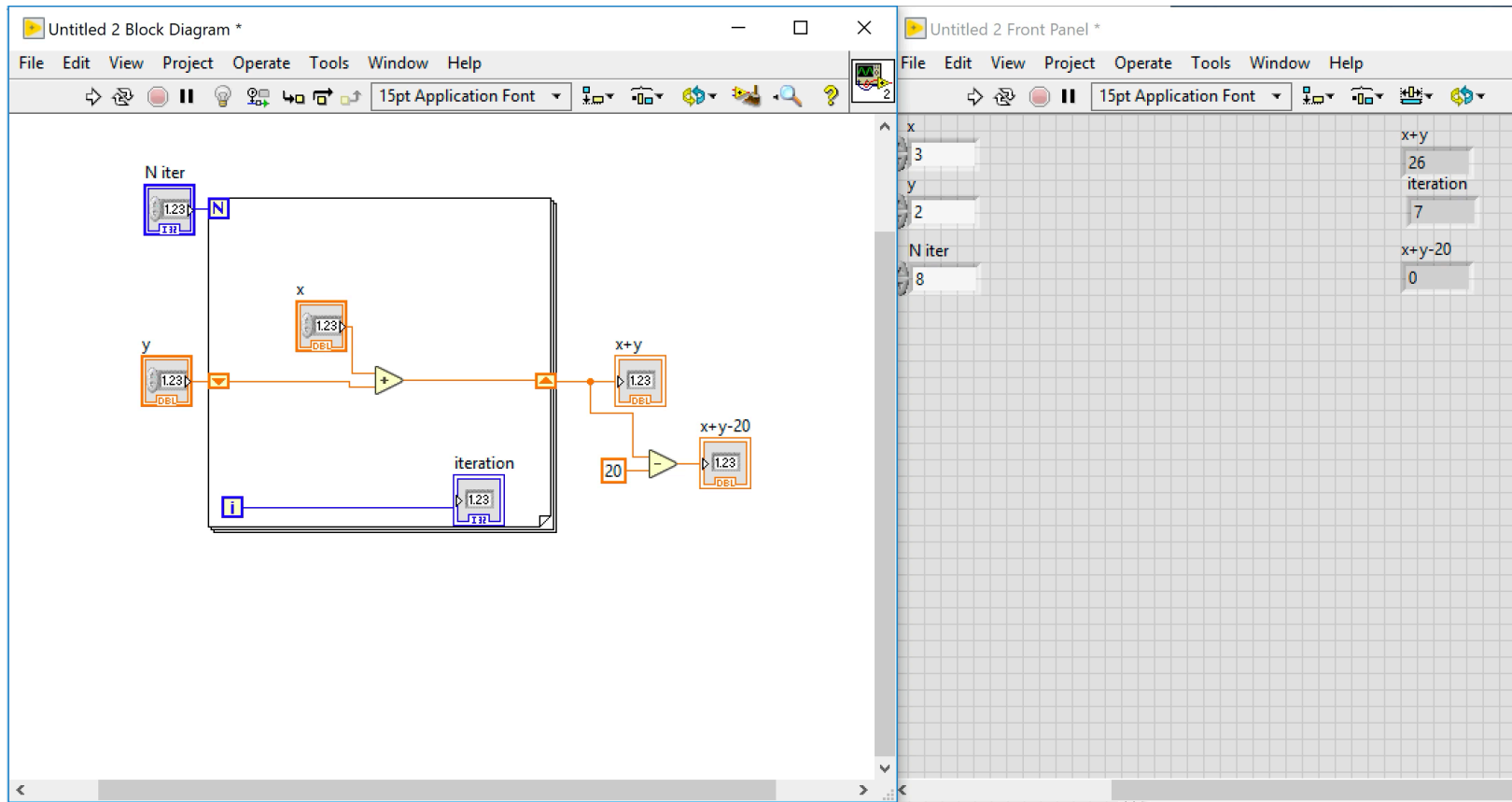
While Loop

The difference with the For Loop is just the stop criterion that is now ruled by a Boolean variable.



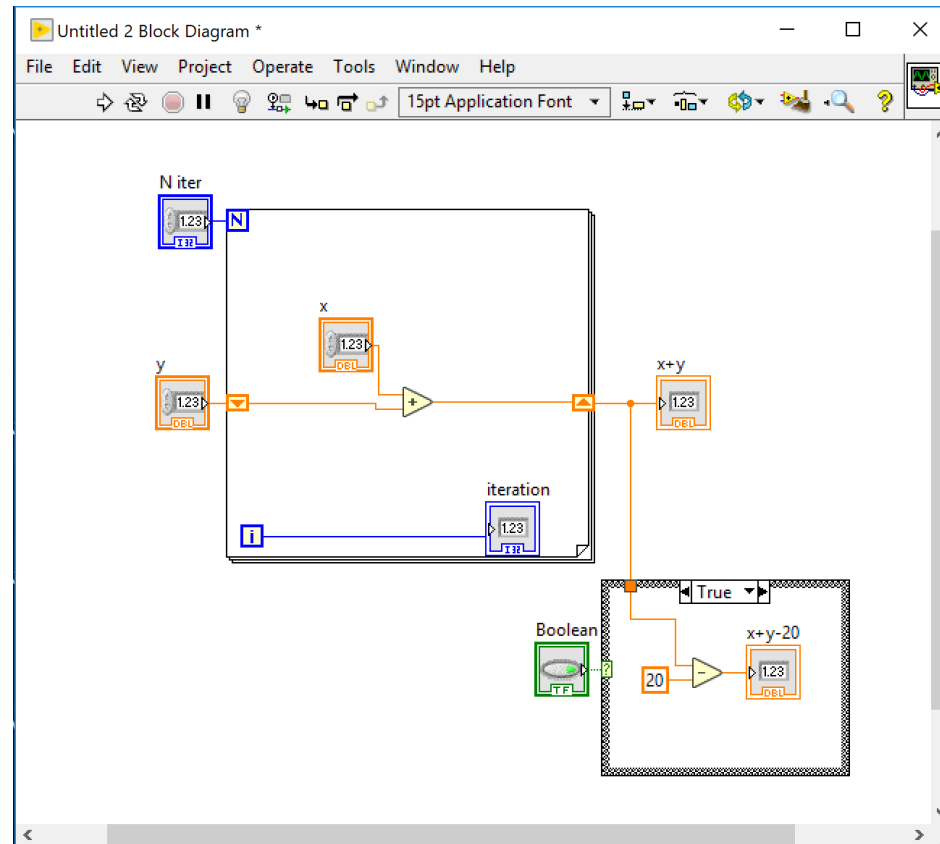
Disable structure

The Disable structure is like the comment in Matlab.



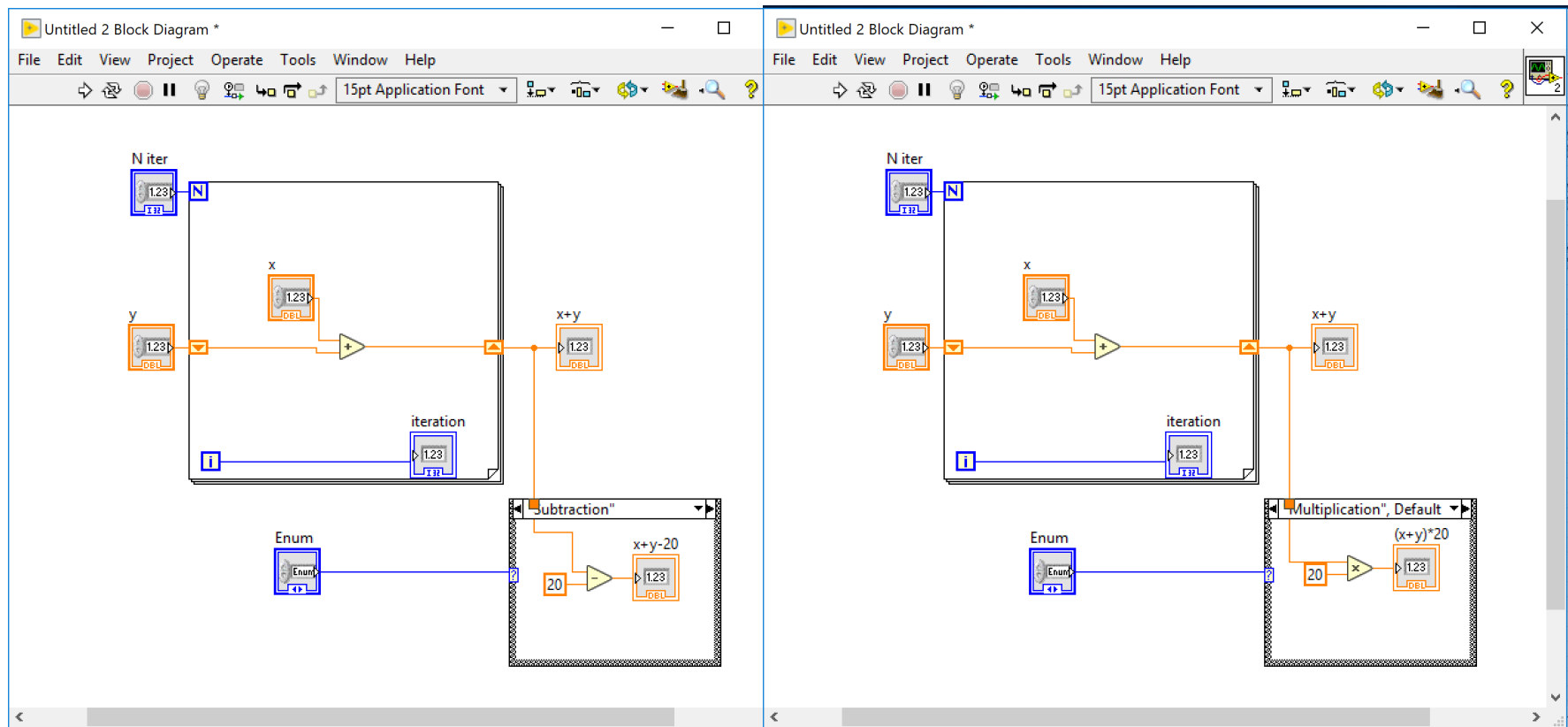
Case structure

The Case structure is like the if ... else ... end in Matlab.



Case structure

The Case structure is like the if ... else ... end in Matlab.



Recap: was everything clear?

- What are the main data types in LabVIEW?
- What are the main structures in LabVIEW?
- What are the possible tunnel options in an iterative cycle (e.g. For & While loop)?

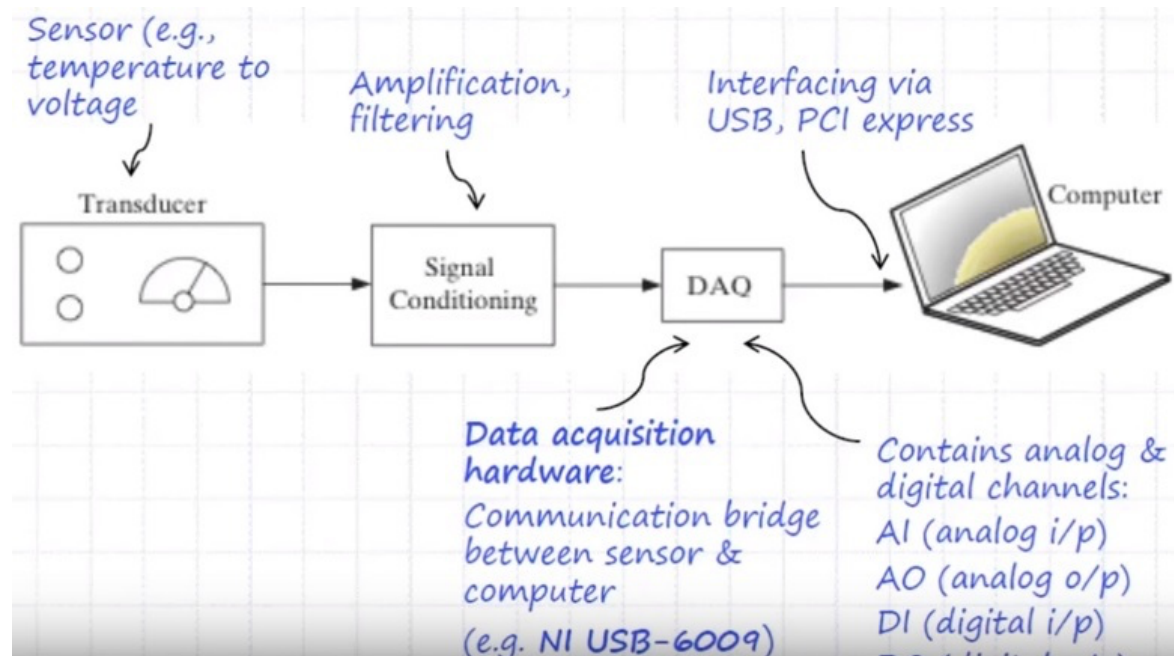
DAQmx

- Data acquisition
- DAQmx library
- Example

DAQ system

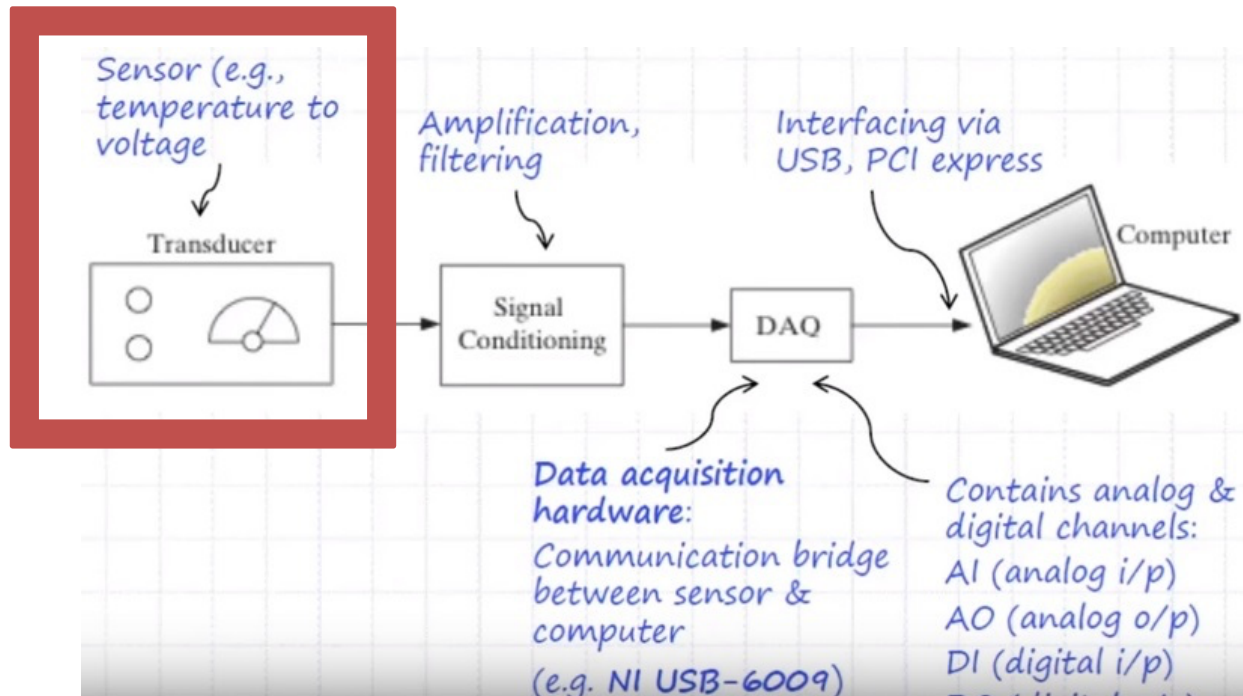
Data acquisition is a process that

1. gathers (analogue) signals from measurement sources;
2. digitizes the signals to store, analyse, and plot on PC.



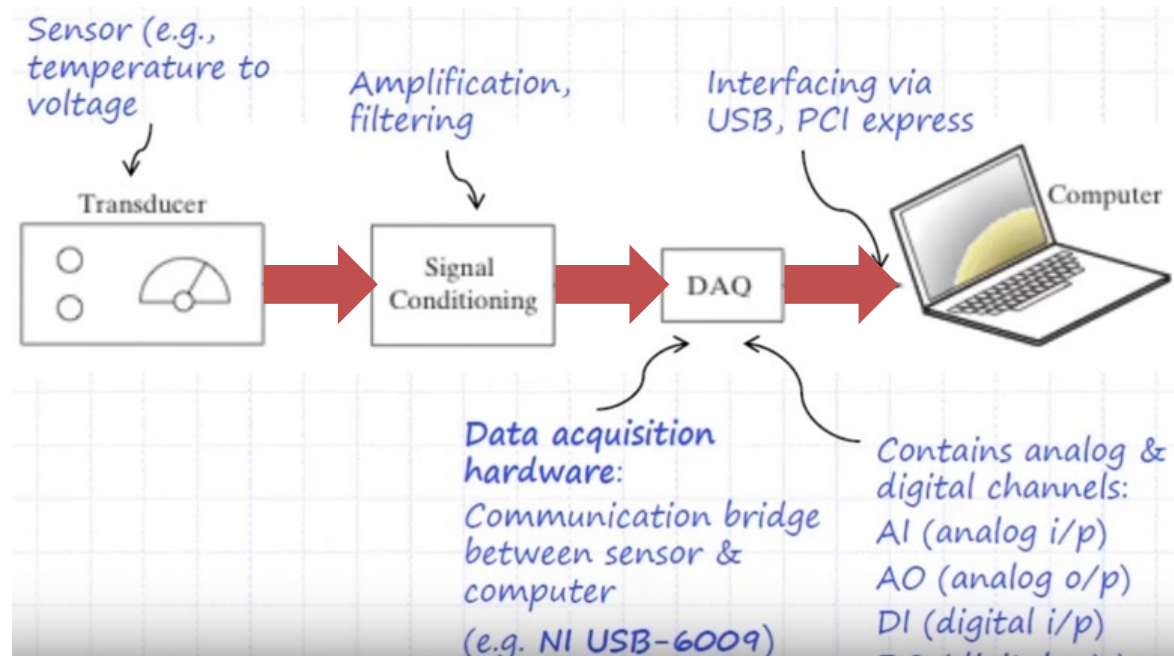
Transducer

Transducer: a device that converts a physical phenomenon into a measurable electrical signal, i.e. voltage or current.



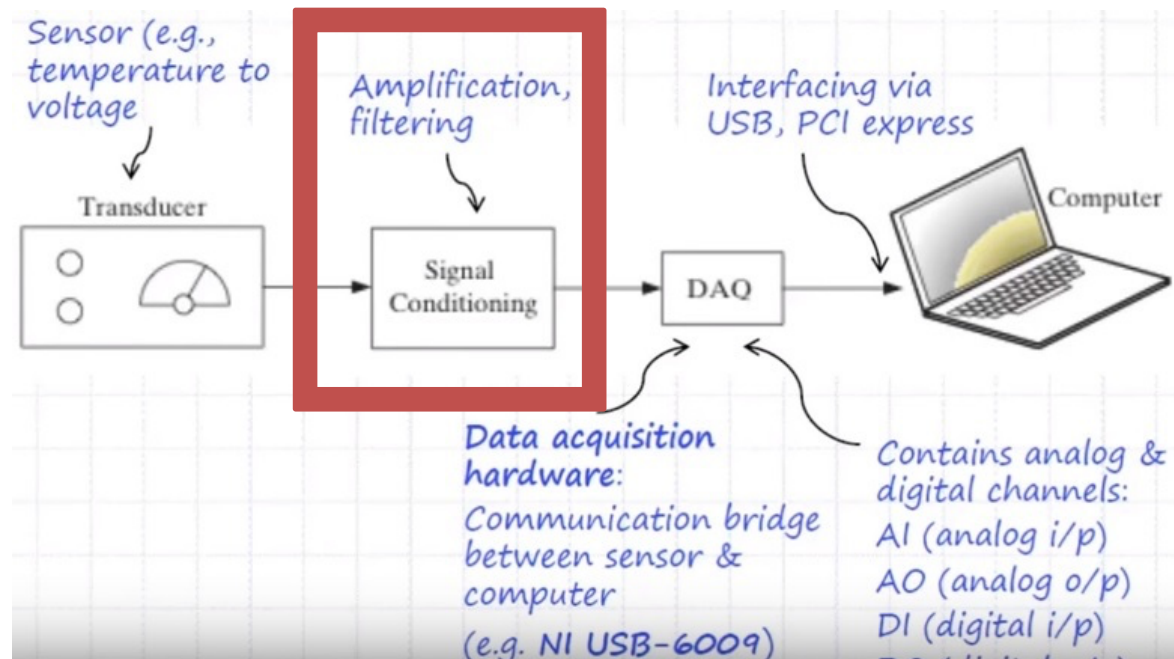
Signal

Signal: a detectable physical quantity or impulse (such as a voltage, current, or magnetic field strength) by which messages or information can be transmitted.



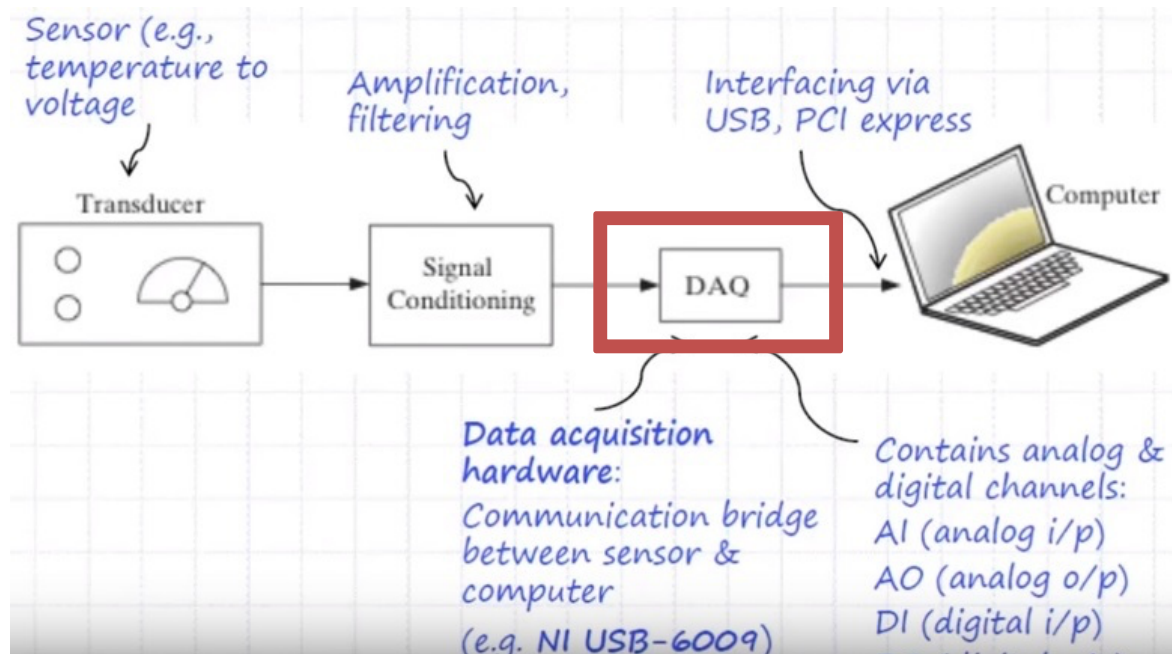
Signal conditioning

Signal conditioning: a set of operations that maximizes the accuracy of a system, allows sensors to operate properly, and guarantees safety (e.g. attenuation, isolation)



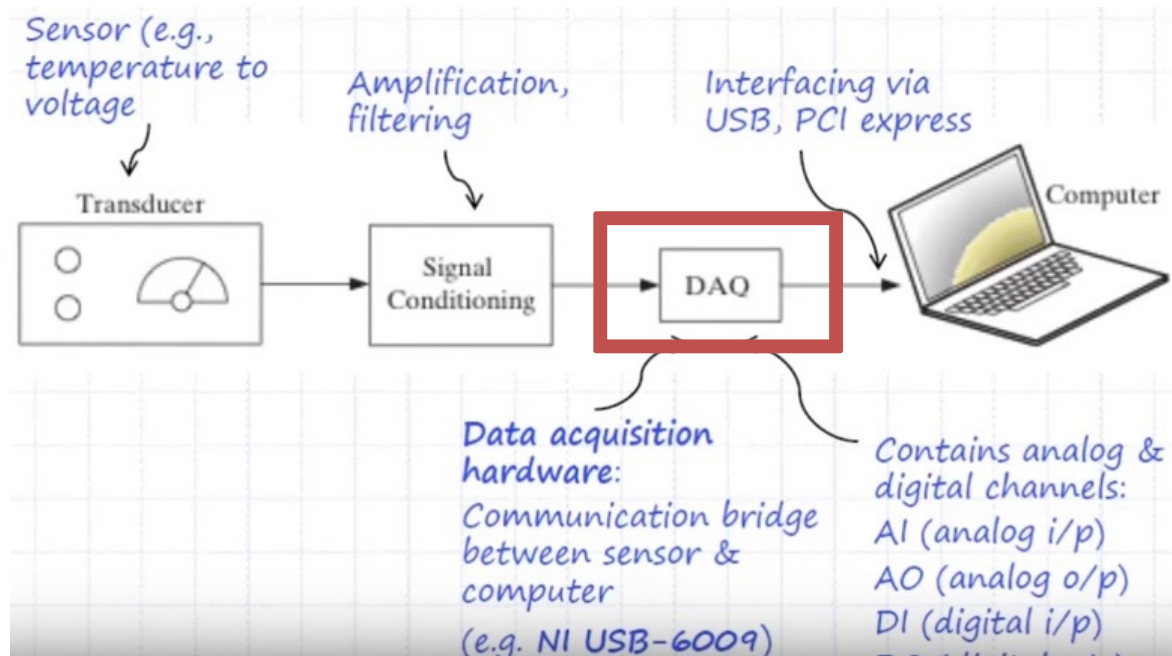
DAQ Hardware

Data acquisition hardware: a device that digitizes incoming analog signals so that the computer can interpret them.



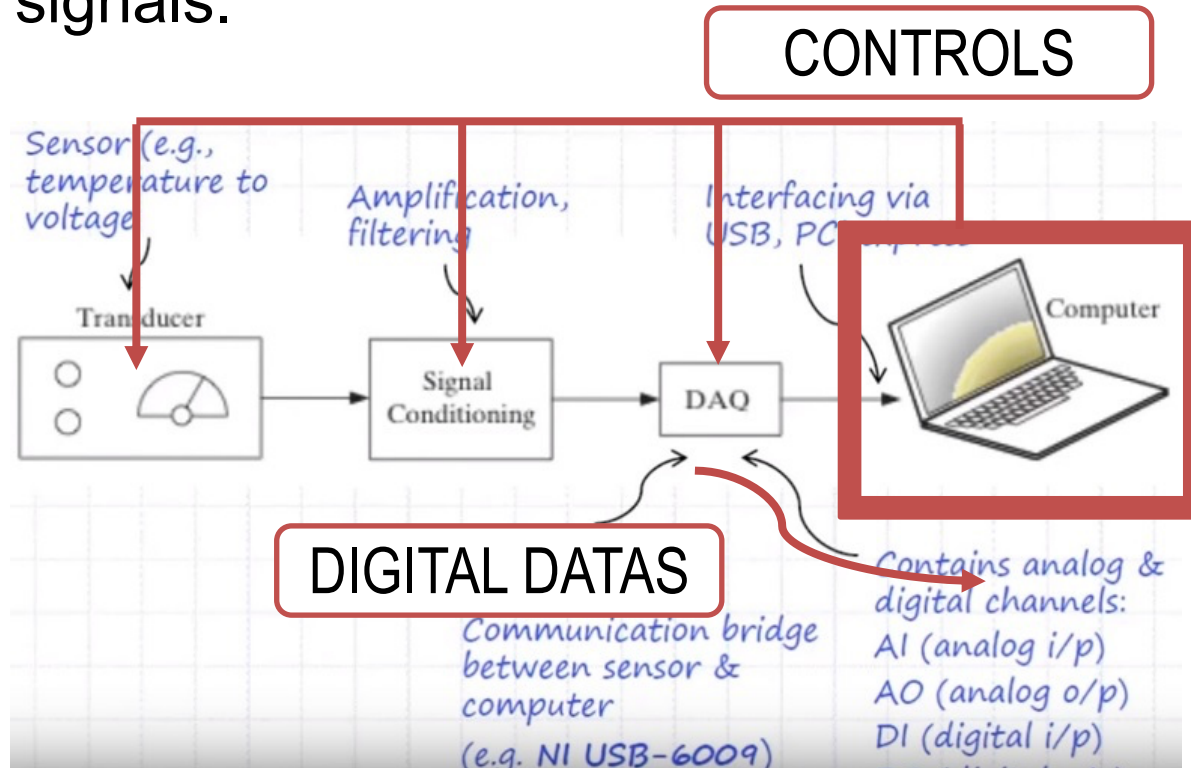
DAQ Software

Data acquisition software: transforms the PC and the data acquisition hardware into a self- tool for data acquisition, analysis, and display.



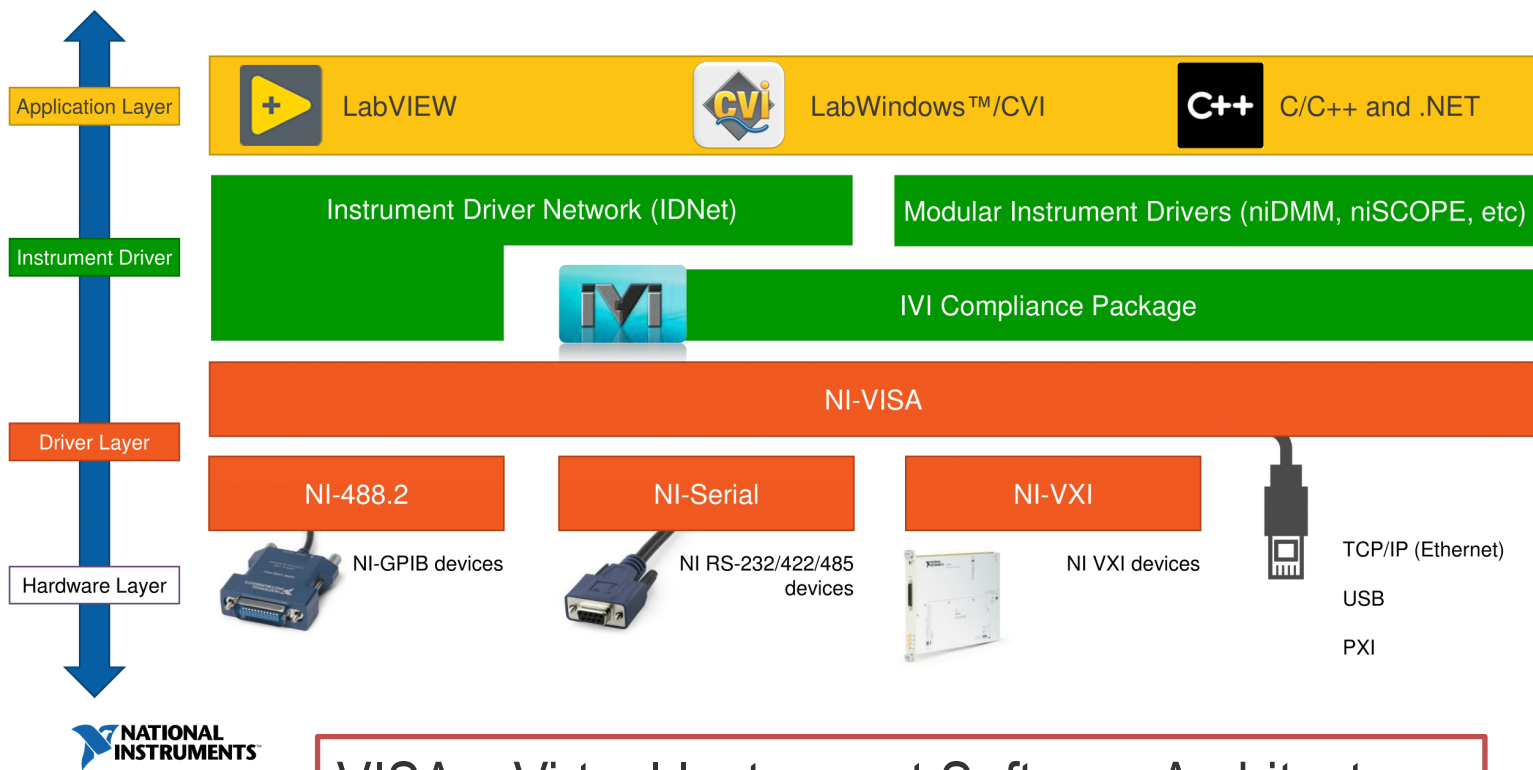
Computer Interface

Computer interface: a computer that controls and triggers the acquisition system, and stores / processes the digitally acquired signals.



Instrument control

Instrument Control Layers



VISA = Virtual Instrument Software Architecture

Drivers

- **Instrument drivers**
a library for a specific class of instruments, typically specific for a given vendor or model
EXAMPLE: Lecroy Oscilloscope HDO4034
- **Driver Layer**
acts as an interface between the application software and the DAQ hardware, and prevents a programmer from having to do register-level programming or complicated commands.
EXAMPLE: NI DAQmx

NI DAQmx

NI DAQmx is the driver software you use to communicate with and control your NI data acquisition (DAQ) devices.

NB: NI DAQmx is explicitly for NI hardware, other vendors instrumentation may require specific libraries.

It includes an extensive library of functions and VIs you can call from LabVIEW to program your devices, plus:

- Measurement & Automation eXplorer (MAX)
- DAQ Assistant

NI MAX

MAX is an application that informs other programs which devices are connected and how they are configured.

Main functionalities:

- view devices and instruments connected to your system
- configure the NI hardware and software
- create and edit channels, tasks, interfaces, scales, and virtual instruments
- execute system diagnostics
- update your National Instruments software

Example



NI MAX console

My System - Measurement & Automation Explorer

File Edit View Tools Help

Save Refresh

Network Adapters

Intel(R) Ethernet Connection (2) I219-LM

Adapter Mode	TCP/IP Network
MAC Address	84:43:09:77
Configure IPv4 Address	Static
IPv4 Address	128.178.26.68
Subnet Mask	255.255.255.0
Gateway	128.178.26.1
DNS Server	128.178.15.227

Intel(R) Ethernet Server Adapter I350-T2

Adapter Mode	TCP/IP Network
MAC Address	00:1B:21:DB:48:C8
Configure IPv4 Address	DHCP or Link Local
IPv4 Address	0.0.0.0
Subnet Mask	0.0.0.0

Intel(R) Ethernet I210-T1 GbE NIC

Adapter Mode	TCP/IP Network
MAC Address	68:05:CA:64:6C:77
Configure IPv4 Address	Static
IPv4 Address	100.100.100.10
Subnet Mask	255.255.255.0

My System

- Data Neighborhood
- Devices and Interfaces
 - ASRL1::INSTR "COM1"
 - ASRL3::INSTR "COM3"
 - Network Devices
- Scales
- Software
- Remote Systems
 - ELD040-cRIO-13
 - Devices and Interfaces
 - ASRL1::INSTR
 - ASRL2::INSTR
 - NI cRIO-9030 "RIO0"
 - Network Devices
 - Software

Network devices

HDO4034 "TCPIP0::100.100.100.100::inst0::INSTR" - Measurement & Automation Explorer

File Edit View Tools Help

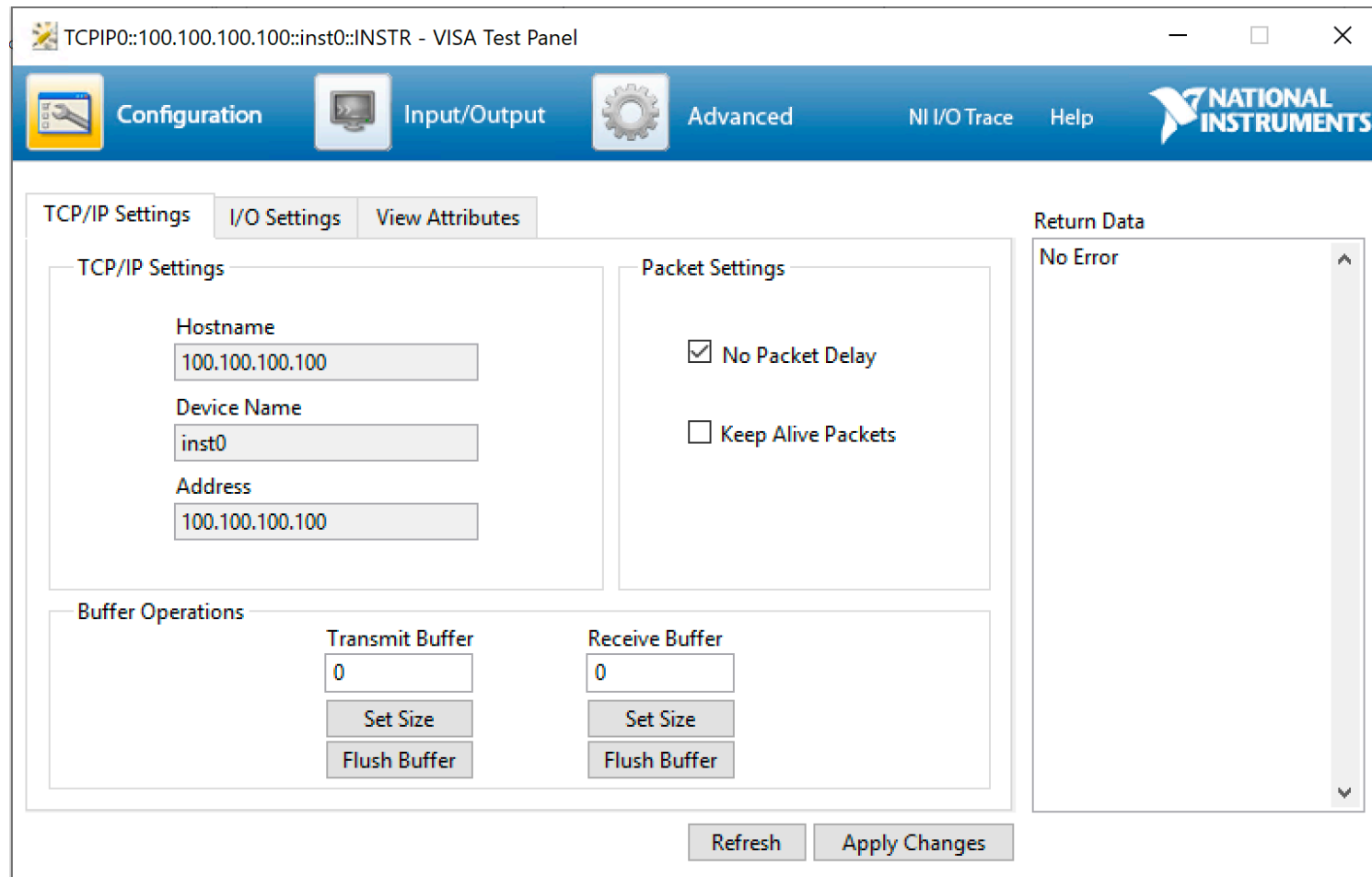
Save Refresh Open VISA Test Panel

- My System
 - Data Neighborhood
 - Devices and Interfaces
 - ASRL1::INSTR "COM1"
 - ASRL3::INSTR "COM3"
 - Network Devices
 - HDO4034 "TCPIP0::100.100.100.100::inst0::INSTR"
 - Scales
 - Software
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 - ELD040-cRIO-13
 - Devices and Interfaces
 - ASRL1::INSTR
 - ASRL2::INSTR
 - NI cRIO-9030 "RIO0"
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 - Software

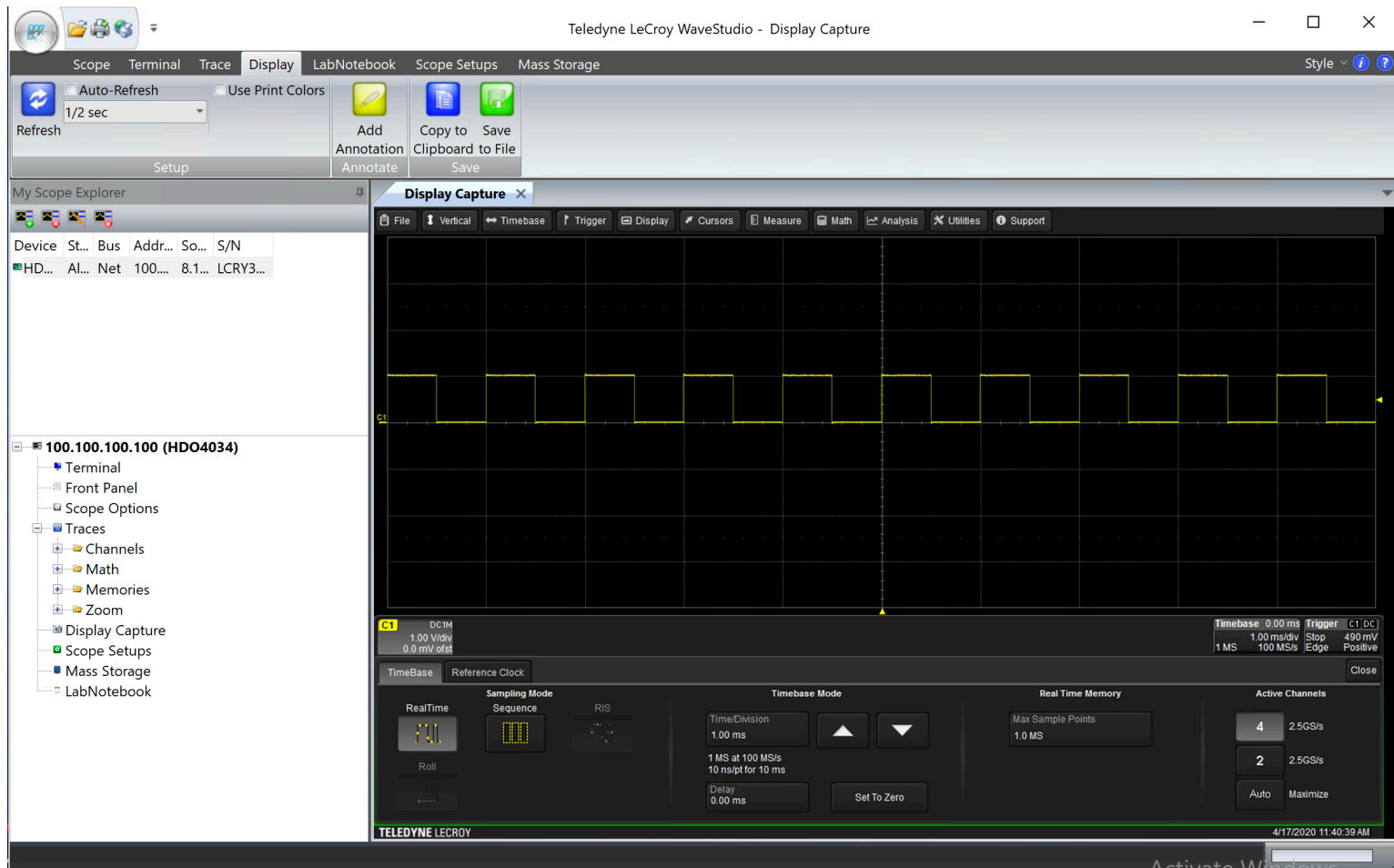
Settings

Name	<input type="text"/>
Hostname	<input type="text" value="100.100.100.100"/>
IPv4 Address	100.100.100.100
Vendor	LECROY
Model	HDO4034
Serial Number	LCRY3513N19423
Firmware Version	8.1.0
Status	Present
LAN Device Name	<input type="text" value="inst0"/>
VISA Resource Name	TCPIP0::100.100.100.100::inst0::INSTR

VISA test panel



Dedicated software

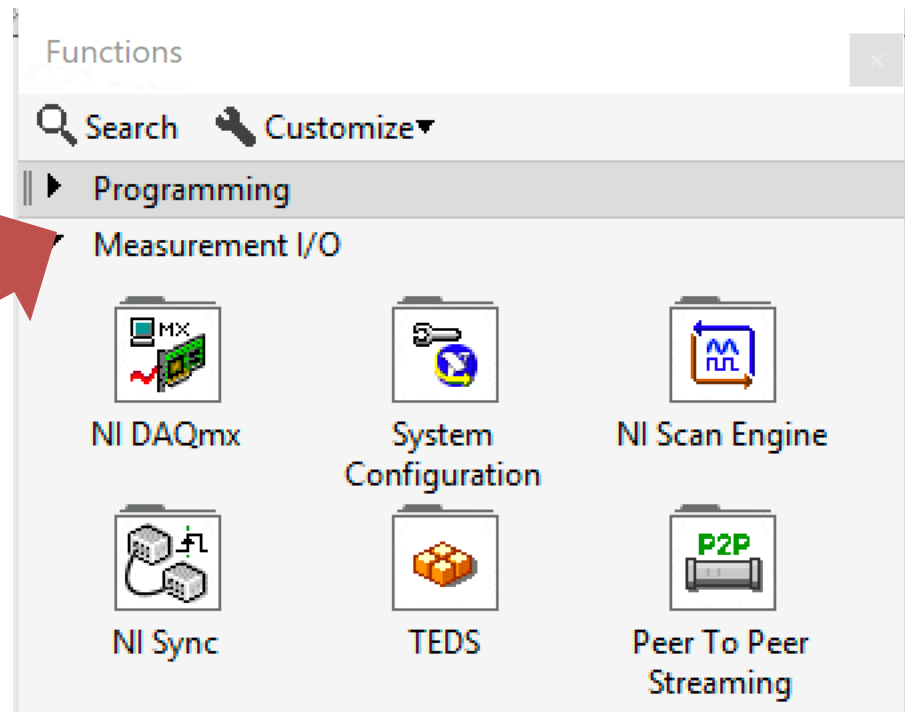
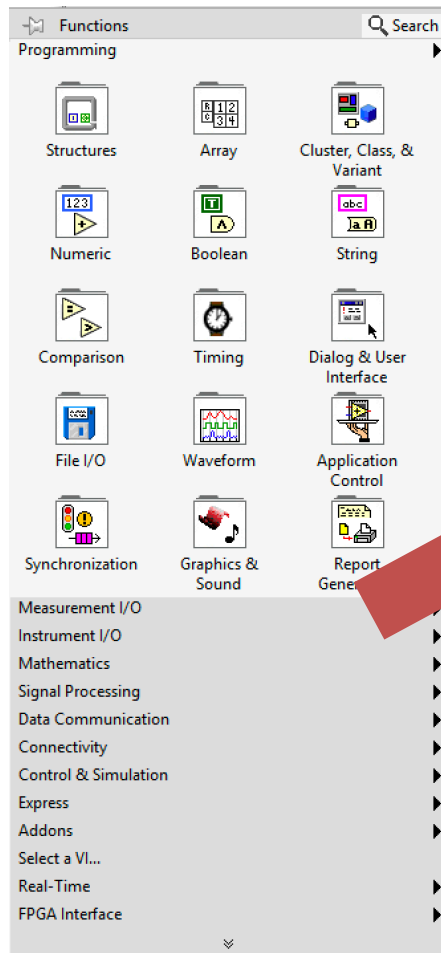


LabVIEW solution

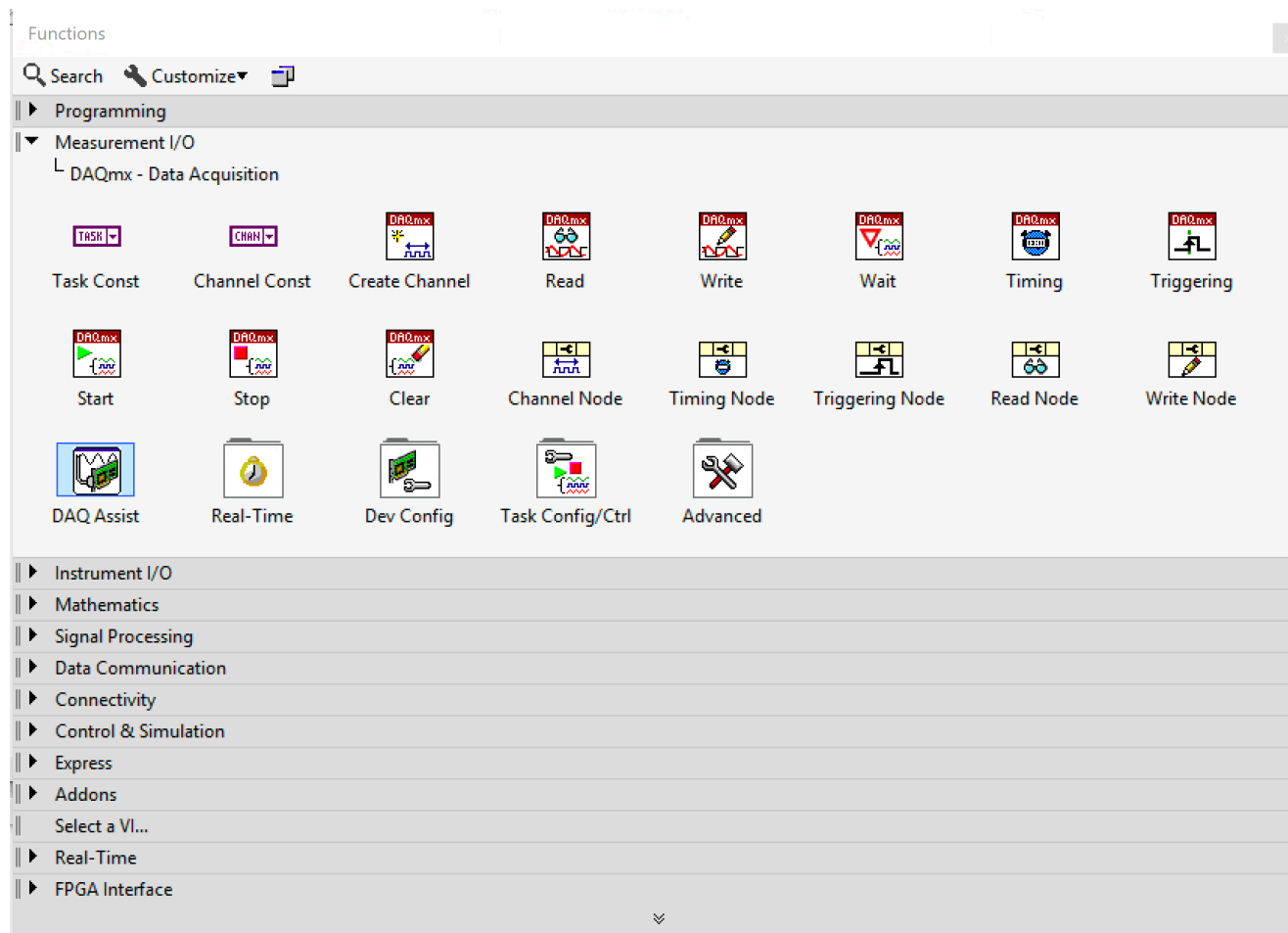
In order to control the instrument from LabVIEW, we need to check two things:

- if the instrument is supported (mostly, just NI hardware) we can use the library NI DAQmx in the palette called Measurement I/O;
- if the instrument is not supported (third part hardware) we have to install the specific library (see next lesson).

Measurement I/O

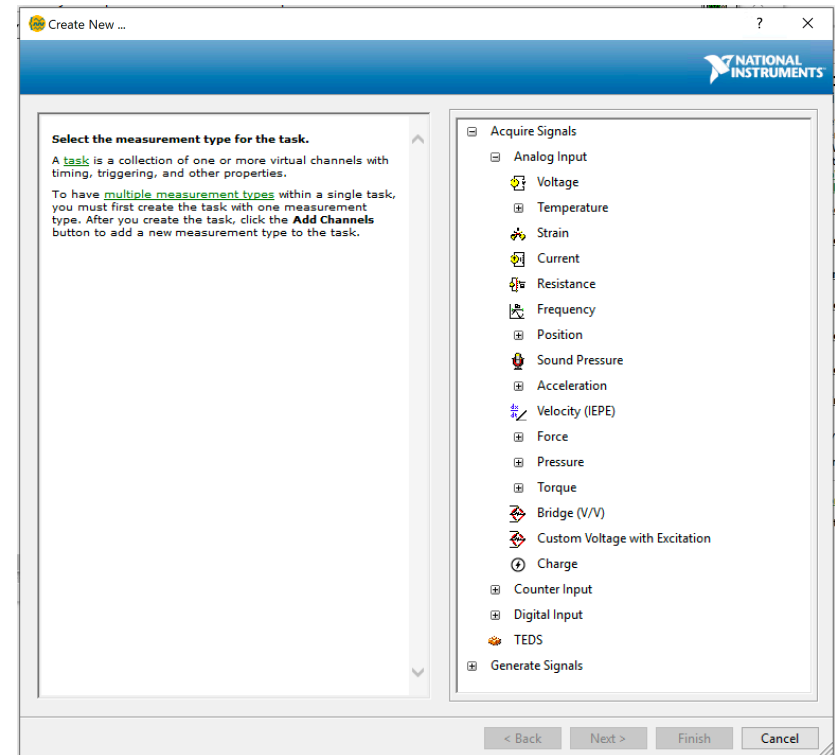
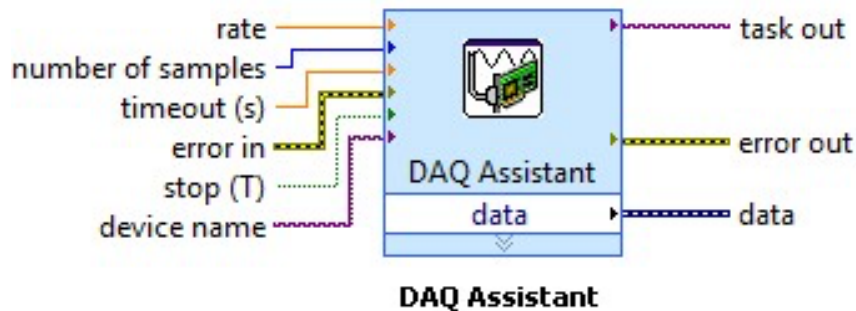


NI DAQmx library



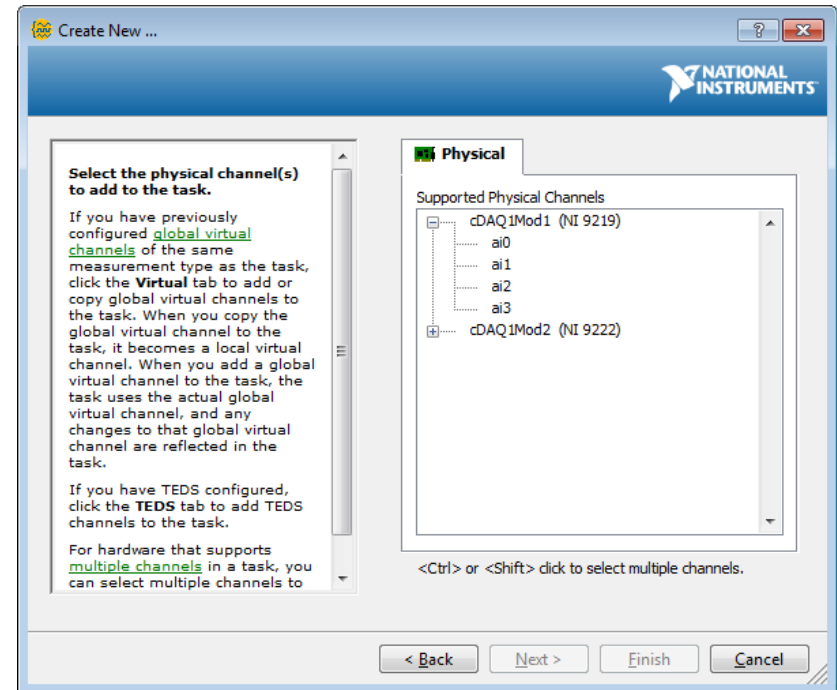
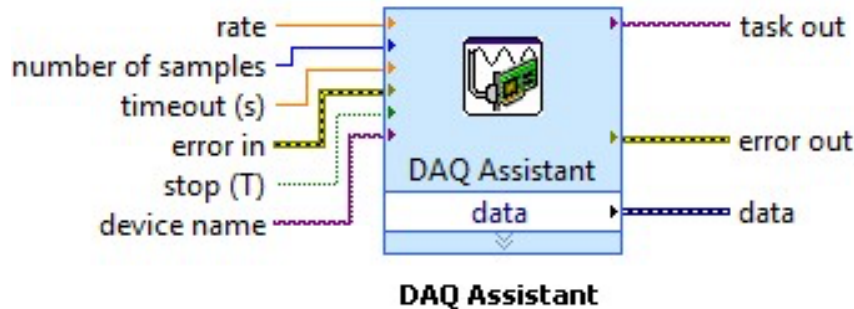
DAQ Assistant

The easiest solution is to use the DAQ assistant that can be easily customized through a multi-step procedure...



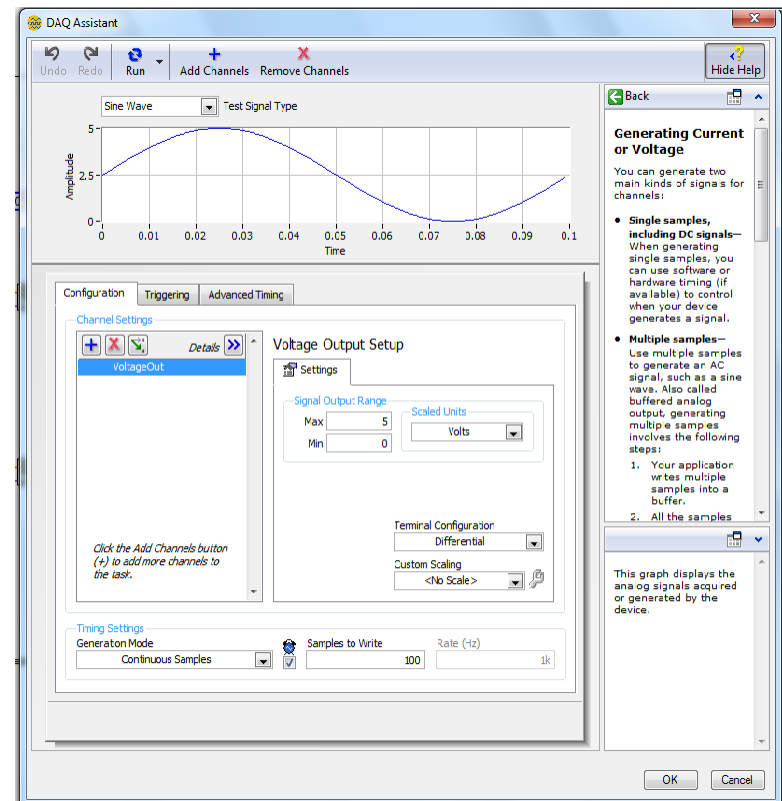
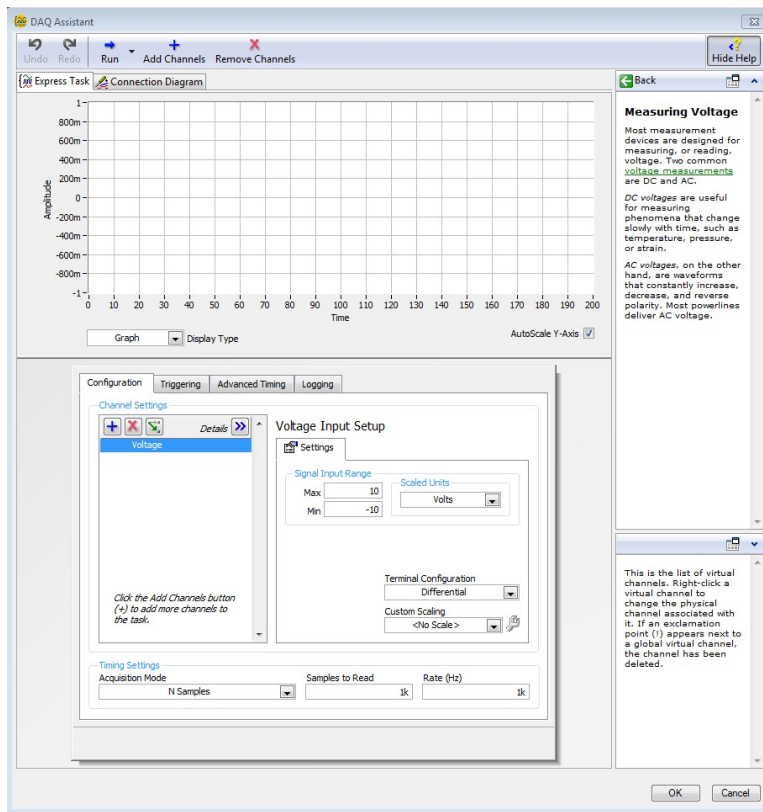
DAQ Assistant

... where Labview asks to select the instrument as well as the physical channels we want to control...



DAQ Assistant

... and, once set up, provides an intuitive GUI:



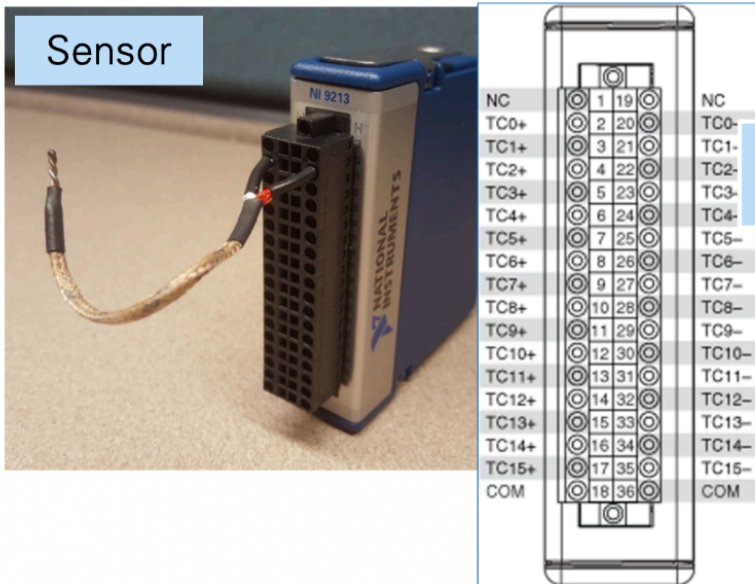
Organization of the code

But – if we don't want or can't use the DAQ assistant – we have to structure our code in a precise and repeatable way:

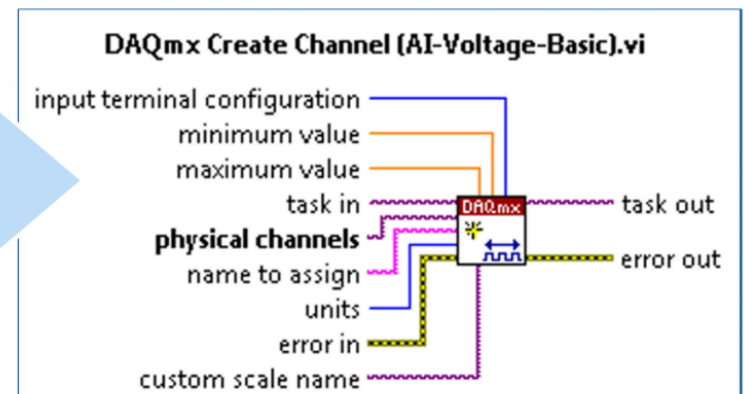
- we have to convert the instrument physical channels in Labview virtual channels;
- we define which task (experiment) we want to carry out;
- we define the specific parameters of our measurements (e.g. resolution, sampling rate, trigger) that are controlled by specific functions in the palette.

Virtual channel

Physical Channel/Pins



Virtual Channel



WARNING !!!

A lot of inputs and outputs comparing to a simple mathematics operation

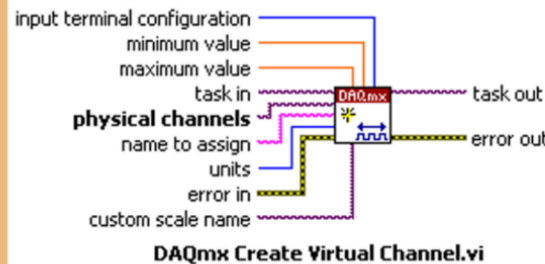
Tasks and functions

Task

Channels

Sensors,
scaling, and
data format

Channel
configuration



Timing, triggering

Signal routing

Buffer configuration

Hardware settings

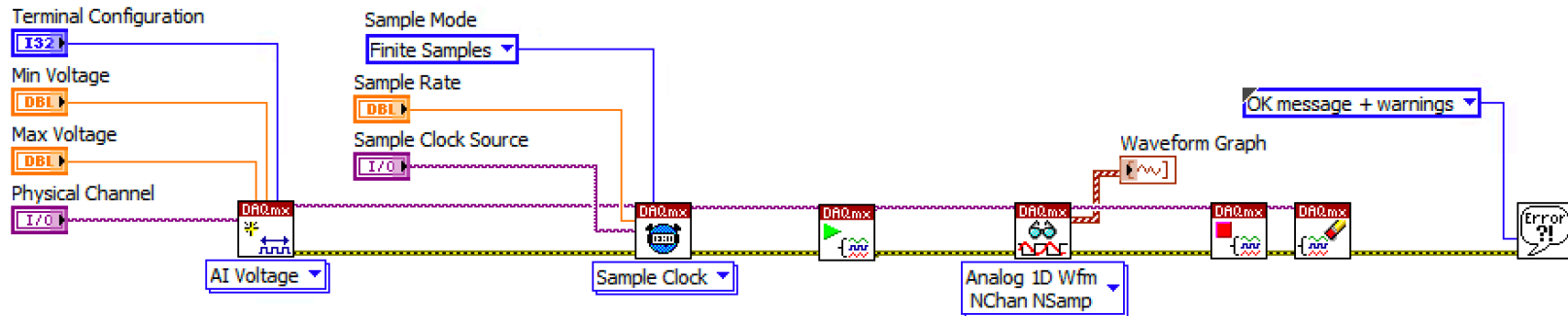
Code organization

We MUST structure the code according to this order:



1. create the task (which kind of measurement)
2. configure the task (set the instrument parameters)
3. start the task (run the experiment)
4. read/write data (acquire or generate data)
NB: it might be repeated iteratively with a for or a while loop
5. stop the task (end the experiment)
6. clear the task (set the virtual channels free for other tasks)

Coding example



Recap: was everything clear?

- What are the main components of a DAQ system?
- What does NI DAQmx enable us to do?
- Why is NI MAX important?

Teaching lab introduction

- Digital oscilloscope
- Library installation
- Coding example

Digital oscilloscope

A digital oscilloscope is an indispensable tool to solve most measurement challenges quickly and accurately.

The full denomination is digital storage oscilloscope (DSO) as it stores and analyses the signals digitally rather than using analog techniques, with advanced functionalities:

- save point-on-wave data;
- different trigger settings;
- channel-specific scales;
- processing routines (e.g. DFT).

HDO4034a

Teledyne Lecroy HDO4034a (high definition) specs

- 4 input channels (± 10 V)
- 350 MHz bandwidth
- 12-bit ADC resolution
- 10 GHz sample rate
- HD4096 12.1" monitor
- 12.5 Mpts per channel
- i3-6100 quad core 3.7 GHz
- 8 GB RAM, Windows 10



HDO4034a

It is provided with several measurement and math tools...

Measurement Tools		Math Tools	
Measurement Functionality	Display up to 8 measurement parameters together with statistics, including mean, minimum, maximum, standard deviation, and total number. Each occurrence of each parameter is measured and added to the statistics table. Histograms provide a fast, dynamic view of parameters and waveshape characteristics. Parameter gates define the location for measurement on the source waveform.	Math Functionality	Display up to 2 math functions traces (F1-F2). The easy-to-use graphical interface simplifies setup of up to two operations on each function trace, and function traces can be chained together to perform math-on-math.
Measurement Parameters - Horizontal + Jitter	Delay (from trigger, 50%), Duty Cycle (50%, @level), Edges (@level), Fall Time (90-10, 20-80), Frequency (50%, @level), Period (50%, @level), Δ Period (@level), Phase (@level), Rise Time (10-90, 20-80), Skew, Time (@level), Δ Time (@level), Width+, Width-	Math Operators - Basic Math	Average (summed), Average (continuous), Difference (-), Envelope, Floor, Invert (negate), Product (x), Ratio (/), Reciprocal, Rescale (with units), Roof, Sum (+).
Measurement Parameters - Vertical	Amplitude, Base, Maximum, Mean, Minimum, Peak-to-Peak, RMS, Std. Deviation, Top.	Math Operators - Filters	Enhanced resolution (to 15 bits vertical)
Measurement Parameters - Pulse	Area, Base, Fall Time (90-10, 80-20), Overshoot (positive, negative), Rise Time (10-90, 80-20), Top, Width+, Width-	Math Operators - Frequency Analysis	FFT (power spectrum, magnitude), up to full record length. Select from Rectangular, VonHann, Hamming, FlatTop and Blackman Harris windows.
		Math Operators - Functions	Absolute value, Derivative, Integral, Invert (negate), Reciprocal, Rescale (with units), Square, Square root, Zoom (identity).

... that makes it not only a waveform display but an actual processor for measurements.

HDO4034a

In terms of connectivity, the feasible options are:

Connectivity	
Ethernet Port	Supports 2 10/100/1000BaseT Ethernet interface (RJ45 ports)
USB Host Ports	4 side USB 3.1 Gen1 ports and 1 front USB 2.0 port support Windows compatible devices
USB Device Port	1 USBTMC port
GPIB Port (optional)	Supports IEEE - 488.2 (External)
External Monitor Port	HDMI 1.4 (Qty. 1) and DisplayPort 1.2 (Qty. 1) to support customer-supplied external monitor. Includes support for extended desktop operation with UHD 3840 x 2160 pixel resolution and split-grid capability on external monitor. Supports touch screen integration of external monitor (Note: external display can not use a Fujitsu touch-screen driver).
Remote Control	Via Windows Automation, or via LeCroy Remote Command Set

... and Labview is not contemplated, so we need to find a way to establish the connection.

Drivers library

<https://teledynelecroy.com/support/softwaredownload/labview.aspx>

where we need to download:

- VICP Passport plug-in
NB: Windows only
- NI X-Stream library
NB: NI-VISA included in your Labview version

■ X-Stream DSOs

Type: LabVIEW™ driver

Follow this link to National Instrument's page for LabVIEW Plug and Play drivers: [NI X-Stream LabVIEW Drivers](#). NI has developed a "traditional" driver as well as a "project-style" driver for use in LabVIEW 8.0 and above.

Installation instructions can be found in an HTML readme file that is within the ZIP file containing the driver download. Read this first to avoid installation issues. Also contained in the readme file are instructions for finding Example programs.

Designed for:

- WaveMaster 8 Zi Oscilloscopes
- SDA 8 Zi Oscilloscopes
- DDA 8 Zi Oscilloscopes
- SDA Oscilloscopes
- SDA 7 Zi Oscilloscopes
- DDA Oscilloscopes
- DDA 7 Zi Oscilloscopes
- WaveMaster 8000(a) Oscilloscopes
- WavePro 7 Zi Oscilloscopes
- WavePro 7000(a) Oscilloscopes
- WaveRunner 6000(a) Oscilloscopes
- WaveRunner Xi/MXi(-A) Oscilloscopes
- HDO6000 Oscilloscopes
- HDO4000 Oscilloscopes
- WaveSurfer 3000
- WaveSurfer Xs/MXs(-A) Oscilloscopes
- WaveSurfer 400 Oscilloscopes

Software requirements

- LabVIEW 7.0 or higher
- NI-VISA 3.0 or higher
- [Latest Teledyne LeCroy VICP Passport](#) (for VICP connections only; not required for GPIB or LXI)

Drivers installation

The Teledyne LeCroy VICP Passport is a plug-in passport for National Instruments' VISA and is needed if we wish to communicate with the DSO via TCP/IP (ethernet).

VICP Passport: download → install → DONE!

For the Labview instrument drivers, we have to be careful!

They are plug & play drivers but they have to be stored in a specific folder in order to be recognized by Labview.

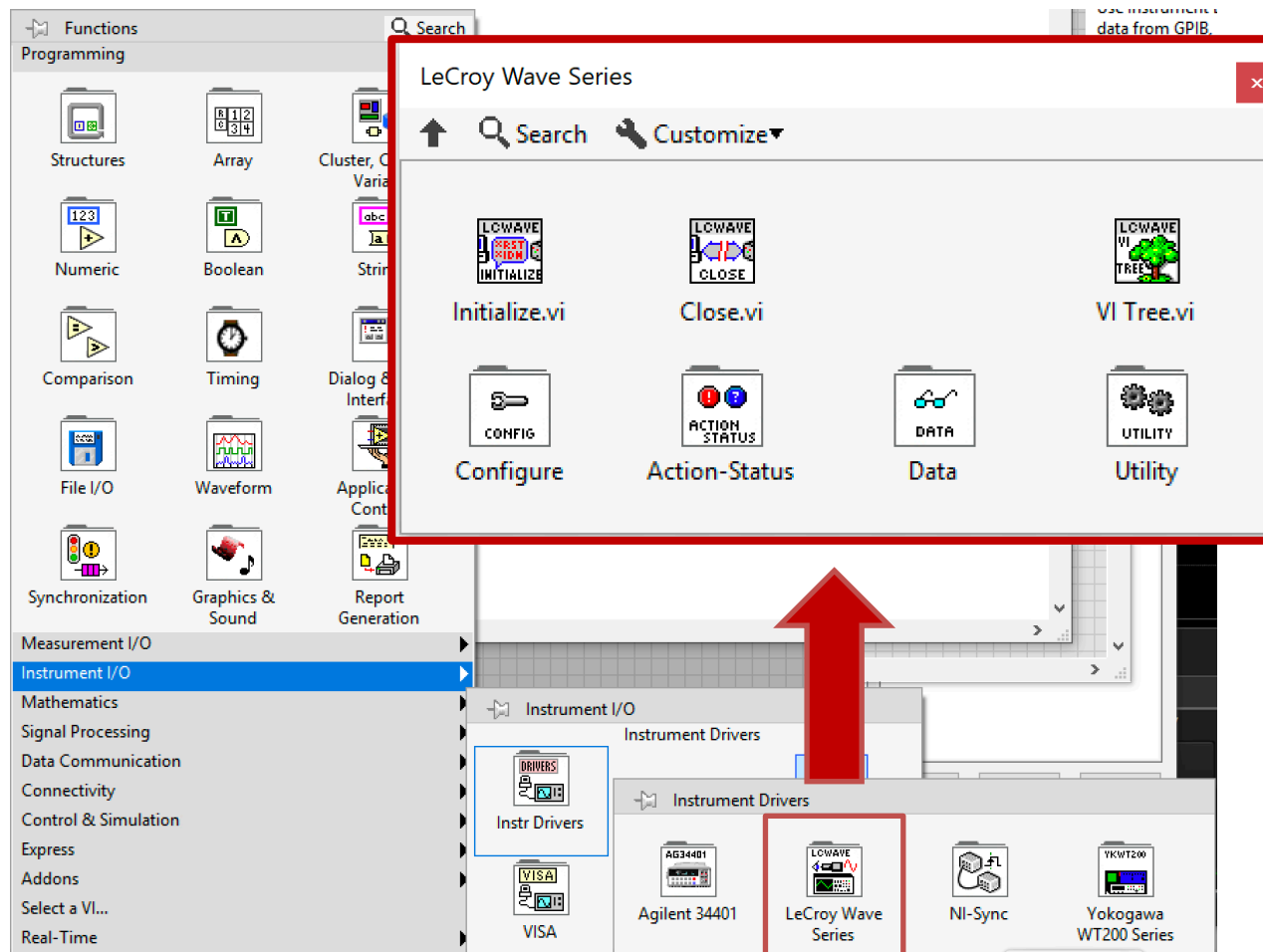
Installation procedure

This procedure is valid for most third part drivers:

1. download the driver package (compressed folder)
2. uncompress the folder (typically, a .zip archive)
3. move the folder to <LabVIEW>\instr.lib directory
4. restart Labview and open a new blank VI

NI X-Stream: download → unzip → move to instr.lib

New library



Main functions



Initialize.vi

initialization, i.e. create task



Read Data.vi

read data, i.e. start task



Close.vi

close, i.e. end task

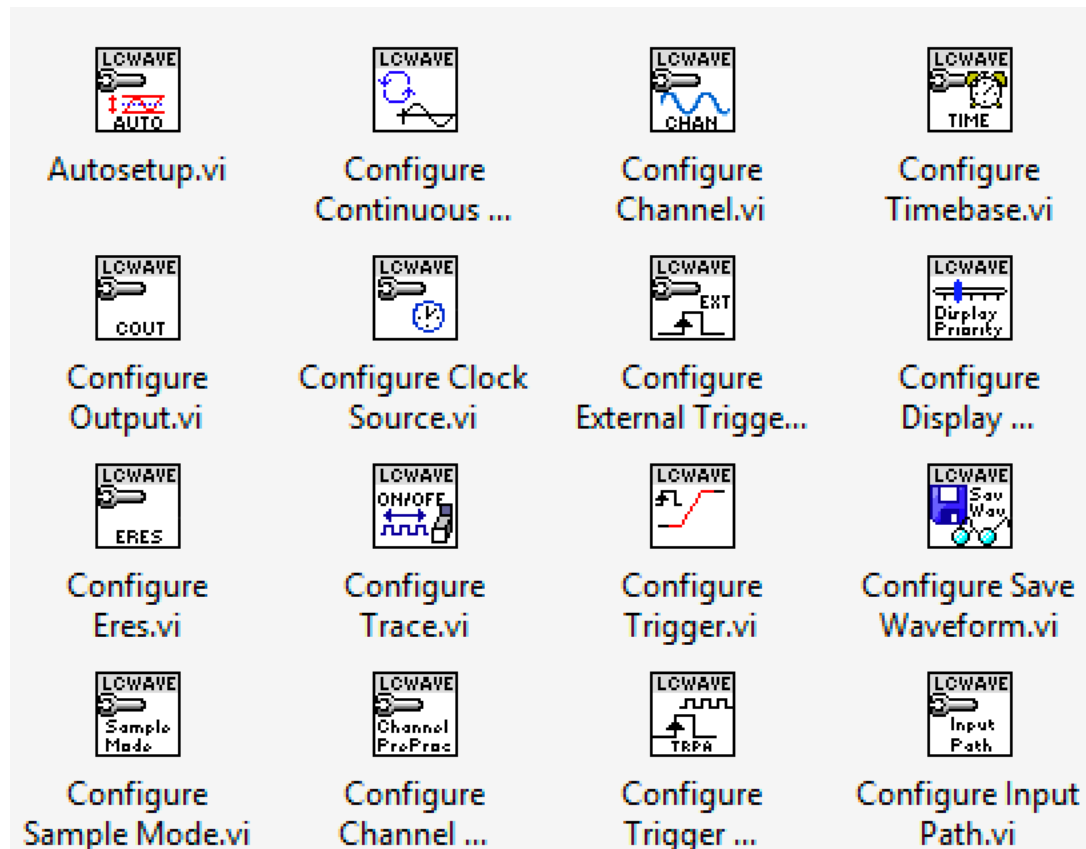


Configure.vi

configure, i.e. configure task

Configure menu

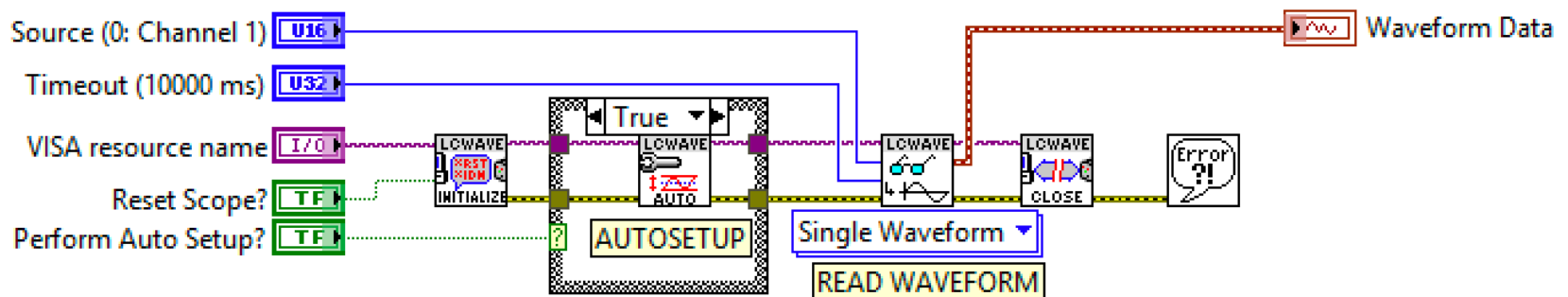
It is possible to configure almost every DSO parameter...



Coding example

Sequence of operations:

- initialization
- configuration
- data acquisition
- task closing



Recap: was everything clear?

- What is a digital oscilloscope, i.e. a DSO?
- Where has a driver library to be stored?
- What is the proper series of commands for the DSO?