

BATCHNORM2D

```
CLASS torch.nn.BatchNorm2d(num_features, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True, device=None, dtype=None) [SOURCE]
```

Applies Batch Normalization over a 4D input (a mini-batch of 2D inputs with additional channel dimension) as described in the paper [Batch Normalization: Accelerating Deep Network Training by Reducing Internal Covariate Shift](#).

$$y = \frac{x - \mathbb{E}[x]}{\sqrt{\text{Var}[x] + \epsilon}} * \gamma + \beta$$

The mean and standard-deviation are calculated per-dimension over the mini-batches and γ and β are learnable parameter vectors of size C (where C is the input size). By default, the elements of γ are set to 1 and the elements of β are set to 0. The standard-deviation is calculated via the biased estimator, equivalent to `torch.var(input, unbiased=False)`.

Also by default, during training this layer keeps running estimates of its computed mean and variance, which are then used for normalization during evaluation. The running estimates are kept with a default `momentum` of 0.1.

If `track_running_stats` is set to `False`, this layer then does not keep running estimates, and batch statistics are instead used during evaluation time as well.

• NOTE

This `momentum` argument is different from one used in optimizer classes and the conventional notion of momentum. Mathematically, the update rule for running statistics here is $\hat{x}_{\text{new}} = (1 - \text{momentum}) \times \hat{x} + \text{momentum} \times x_t$, where \hat{x} is the estimated statistic and x_t is the new observed value.

Because the Batch Normalization is done over the C dimension, computing statistics on (N, H, W) slices, it’s common terminology to call this Spatial Batch Normalization.

| Parameters |
|--|
| <ul style="list-style-type: none">num_features – C from an expected input of size (N, C, H, W)eps – a value added to the denominator for numerical stability. Default: 1e-5momentum – the value used for the running_mean and running_var computation. Can be set to <code>None</code> for cumulative moving average (i.e. simple average). Default: 0.1affine – a boolean value that when set to <code>True</code>, this module has learnable affine parameters. Default: <code>True</code>track_running_stats – a boolean value that when set to <code>True</code>, this module tracks the running mean and variance, and when set to <code>False</code>, this module does not track such statistics, and initializes statistics buffers <code>running_mean</code> and <code>running_var</code> as <code>None</code>. When these buffers are <code>None</code>, this module always uses batch statistics. in both training and eval modes. Default: <code>True</code> |

| Shape: |
|--|
| <ul style="list-style-type: none">Input: (N, C, H, W)Output: (N, C, H, W) (same shape as input) |

Examples:

```
>>> # With Learnable Parameters
>>> m = nn.BatchNorm2d(100)
>>> # Without Learnable Parameters
>>> m = nn.BatchNorm2d(100, affine=False)
>>> input = torch.randn(20, 100, 35, 45)
>>> output = m(input)
```

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