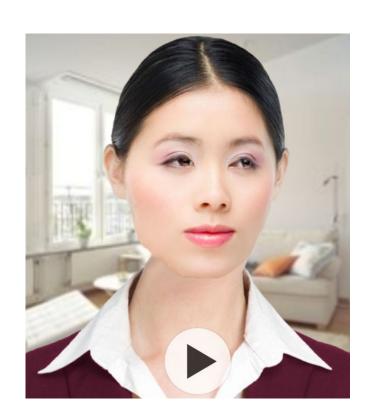
# What makes a Virtual Human Alive?

- Avatar & Autonomous Virtual Humans
   The complexity of expressive movements
   From artificial to real: the uncanny valley
- 4. Motion capture is part of the solution (film)5. Perception of real-time animation
- 6. Core real-time VH believability factors
  7. Exercises & R&D efforts



#### 6. Core real-time VH believability factors (1)

- The first key factor is "animation":
  - from latin word "anima": animal life, breath, soul, mind
  - Hence the Virtual Human **MUST NOT BE STILL** otherwise it appears at best as a statue or worse as a dead body.
  - Movement can be procedurally generated or re-synthetized from captured movement through motion graphs [vW 2010]
  - Many commercial chatterbots, e.g. (USA) => http://sitepal.com/demo







#### 6. Core real-time VH believability factors (2)

- Minimal background animation :
  - Breathe gently: sine wave in the spine at the thorax level
  - Eye blinking (5 to 20 /min)
  - Gentle random head movements, possibly coordinated with gaze
  - Gentle balance swaying if standing, possibly with idle movements
  - Principle of Perlin noise for VH animation [P1995]:
  - Add noise functions with decreasing amplitude as frequency increases:

```
F= 1 Hz, amplitude: 128
+ F= 2 Hz, amplitude: 64
+ F= 4 Hz, amplitude: 32
+ etc..
```

- Smooth/interpolate the result to produce in-between frames at display rate (e.g. 60 Hz)



[SimSensei 2014 ICT]





### 6. Core real-time VH believability factors (3)

- Animation has to be coherent with the second key factor: **interaction**, i.e. being responsive to user input [TVR], including:
  - Plausible **speech understanding & generation** : minimize latency
  - Must be coordinated: facial expressions, head movement and eye gaze
  - Gestures: handle or precompute *transitions* between prerecorded gestures instead of sequences of gestures that always start and end with the same neutral posture
  - continuous flow of **idle movement** when not actively interacting
  - Handle eye contact with care: gaze to express the wish to speak [K2014]
  - Emotion display is application-dependant: happiness, surprise, interest, smile is generally a safe default.
  - If possible, subtle **mimicry** of the user head movement by the virtual human (e.g. with 4s delay) produces social influence but it backfires if detected because considered as a form of deception [Bailenson 2008]



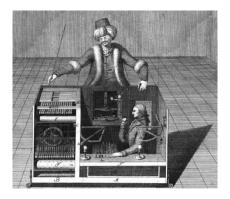
[NEON 2020 Samsung STAR labs]



## 6. Core real-time VH believability factors (4)



- integrate a *hidden operator* when real-time constraint prevent the synthesis of sufficient quality movement or social experience:
  - <u>Performance animation</u> for animating a synthetic character in TV shows or theme parks to interact with the public.



• <u>Mechanical Turk</u> (inspired by a false chess automaton from the XVIII century), e.g. teleoperated realistic puppet of Hiroshi Ishiguro (see uncanny valley slide) for fairs, theme park, etc...



• <u>Wizard of Oz (inspired by the novel from F. Baum)</u>, e.g. for scientific experiments or training of complex social skills: the operator select predefined actions, sentences, behaviors etc based on the instantaneous user input (cf Presence course).





## 6. Core real-time VH believability factors (5)

- Combine with tangible interface if necessary
  - in case a touch or haptic feedback is also needed, the VH should be collocated with a <u>tangible interface</u>, e.g. in [R 2009] a physical mannequin is manipulated by the trained medical doctor (e.g. for a breast exam) while seing a VH patient in a HMD.
- In that specific study, an additional feature of Virtual Social Perspective-taking (VSP) required the medical student user to switch roles with the patient to better understand the patient concerns and show more empathy for future real-world patients.



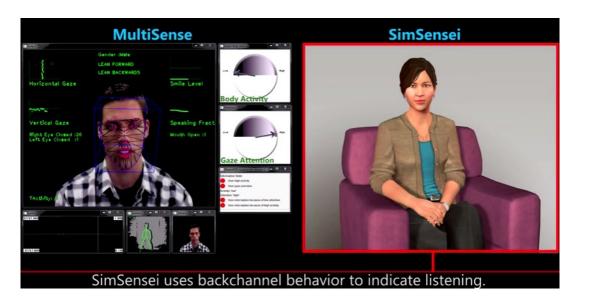






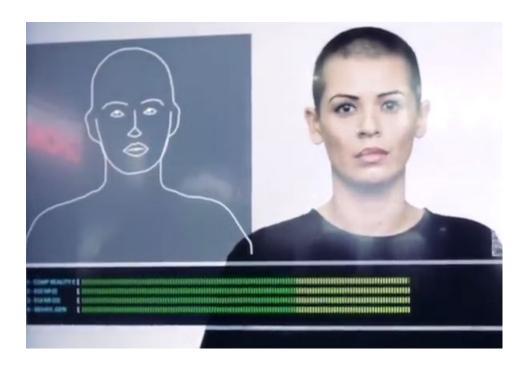
# 7.1 Exercise: spot key believability factors of these demos

2014: S. Rizzo & LP Morency et al MultiSense (emotion tracking) & SimSensei (VH agent)



https://www.youtube.com/watch?v=ejczMs6b1Q4

CES 2020 Cnet discussion of NEO Virtual Humans from /Samsung StarLab



https://www.youtube.com/watch?v=ODucR4xum\_4





# 7.2 Exercise: spot key believability factors of these products

Gallery of chatterbot demos from Sitepal.com http://www.sitepal.com/demo



https://www.youtube.com/watch?v=kPb6cF8rnB8

Commercial Library of full-body 3D characters from Rocketbox studio (2010)

https://www.youtube.com/watch?v=zlqtWivC4Hg





Morph3D => Tafi avatars

Mixamo







#### 7.3 R&D efforts

- Academic groups involved in RT Autonomous VH:
  - ICT (USA): S. Rizzo & LP Morency/ MultiSense (emotion tracking) & SimSensei (VH agent)
  - INRIA-BUNRAKU/ Golaem (FR): normalized postural control, Behavior
  - Paris-Tech (FR): speaking agent GRETA, Catherine Pelachaud
  - Grenoble GIPSA-lab: Prosody & emotions, Gérard Bailly, Rémy Ronfard
  - DFKI (DE): Thomas Rist, Michael Kipp
  - UK teams: Ruth Aylett, Marc Cavazza
  - Other US teams: Justine Cassell, Andrew Cowell, Ari Shapiro
- Industrial solutions: Samsung STAR labs Neon's VH 2020 https://www.neon.life/
  - Numerous full body 3D assets available with UNITY3D (e.g. <u>Mixamo</u>)
  - Web site characters focus on spoken interactions with "chatterbots": often limited to a 2D/3D speaking head/torso
  - Language understanding tools (converging towards google/amazon assistants)
  - <u>Highfidelity.io</u> was a VR-upgrade of <u>Second Life</u>



# [References]

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[W 2009] van Welbergen, H., van Basten, B.J.H., Egges, A., Ruttkay, Z., Overmars, M.H.: Real Time Animation of Virtual Humans: A Trade-off Between Naturalness and Control. In: Eurographics - State of the Art Reports, Eurographics Association, pp. 45–72 (2009)







# [Web References]

Ellie: https://www.youtube.com/watch?v=ejczMs6b1Q4

NEON discussion at CES 2020: <a href="https://www.youtube.com/watch?v=ODucR4xum\_4">https://www.youtube.com/watch?v=ODucR4xum\_4</a>

Demo of the 2010 EU project SEMAINE interacting agent: <a href="https://semaine-db.eu/">https://semaine-db.eu/</a>

Web site of Prof. Ken Perlin: <a href="http://www.mrl.nyu.edu/~perlin/">http://www.mrl.nyu.edu/~perlin/</a>