

Potential Theory I

Outlines

Newtonian Mechanics:

- refreshing memory

Potential Theory : general results

- Gravitational field force, gravitational potential
- Poisson Equation
- Gauss Theorem
- Total potential energy

Spherical systems:

- Newton's Theorems
- Circular speed, circular velocity, circular frequency, escape speed, potential energy

Refreshing memory...

Newtonian mechanics

Newtonian mechanics : a very short remainder

point mass : mass m

position \vec{x}

velocity $\vec{v} = \frac{d\vec{x}}{dt}$

momentum $\vec{p} = m \vec{v} = m \frac{d\vec{x}}{dt}$

Newtonian mechanics : a very short remainder

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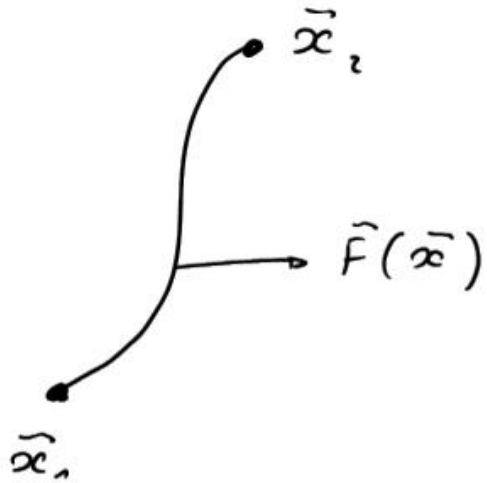
Newton second law

$$\frac{d}{dt}(\vec{p}) = m \frac{d^2\vec{x}}{dt^2} = \vec{F}$$

• \vec{F} : a force

\vec{p} is constant in absence of a force

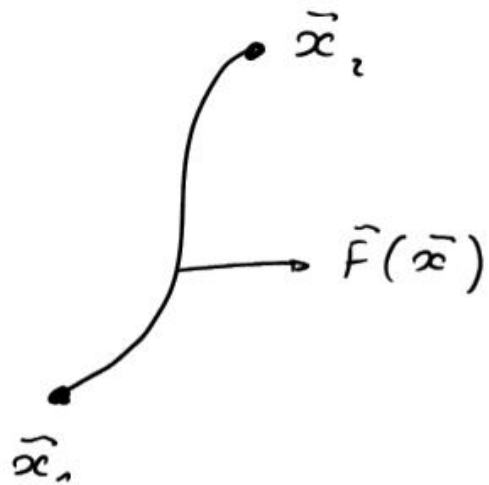
Work : work done by a force in moving the particle
from \vec{x}_1 to \vec{x}_2



$$W_{12} = - \int_{\vec{x}_1}^{\vec{x}_2} \vec{F}(\vec{x}) \cdot d\vec{x}$$

$$[W_{12}] = 9 \frac{\text{cm}^2}{\text{s}^2} \\ = \text{erg}$$

Work : work done by a force in moving the particle from \vec{x}_1 to \vec{x}_2



$$W_{12} = - \int_{\vec{x}_1}^{\vec{x}_2} \vec{F}(\vec{x}) \cdot d\vec{x}$$

$$[W_{12}] = 9 \frac{\text{cm}^2}{\text{s}^2} = \text{erg}$$

Power of a force (energy rate)

$$\frac{\text{erg}}{\text{s}}$$

$$\text{with } \frac{\partial \mathcal{F}(\vec{x})}{\partial x_i} = F_i(\vec{x})$$

$$\frac{d}{dt} W_{12}(x(t)) = - \frac{d}{dt} \int_{\vec{x}_1}^{\vec{x}(t)} \vec{F}(\vec{x}) \cdot d\vec{x} = - \frac{d}{dt} \left(\mathcal{F}(\vec{x}(t)) - \mathcal{F}(\vec{x}_1) \right)$$

$$= - \vec{\nabla}_{\vec{x}} \mathcal{F}(\vec{x}) \cdot \frac{d}{dt} (\vec{x}(t)) = - \vec{F}(\vec{x}) \vec{v}(\vec{x})$$

Kinetic energy

$$W_{12} = - \int_{\vec{x}_1}^{\vec{x}_2} \vec{F}(\vec{x}) \cdot d\vec{x}$$

Integration by part gives

$$= -m \left[\vec{v}^2 \Big|_{\vec{x}_1}^{\vec{x}_2} - \int_{\vec{x}_1}^{\vec{x}_2} \vec{v} \frac{d\vec{v}}{dt} dt \right] = -m \vec{v}_2^2 + m \vec{v}_1^2 + m \underbrace{\int_{\vec{x}_1}^{\vec{x}_2} \vec{v} \frac{d\vec{v}}{dt} dt}_{-W_{12}}$$

Thus $W_{12} = \frac{1}{2} m \vec{v}_1^2 - \frac{1}{2} m \vec{v}_2^2$

$$W_{12} = K_1 - K_2$$

$$K = \frac{1}{2} m \vec{v}^2 : \text{Kinetic energy}$$

Newton
2nd law

$$= -m \int_{\vec{x}_1}^{\vec{x}_2} \frac{d\vec{v}}{dt} \frac{d\vec{x}}{dt} dt$$
$$= -m \int_{\vec{x}_1}^{\vec{x}_2} \frac{d\vec{v}}{dt} \cdot \vec{v} \cdot dt$$

$$\vec{x} = \vec{x}(t)$$
$$d\vec{x} = \frac{d\vec{x}}{dt} dt$$

Potential energy and conservative forces

A force $\vec{F}(\vec{x})$ is called conservative if the work done by this force in moving the particle from \vec{x}_1 to \vec{x}_2 is independent of the path.

Then, for any given point \vec{x}_0

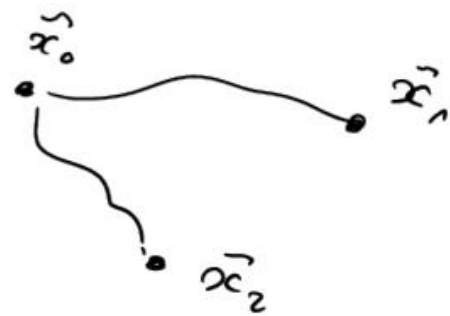
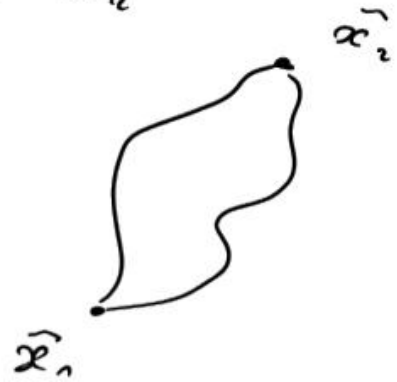
we can define the function (potential) $V_0(\vec{x})$

$$V_0(\vec{x}) := V_{0\vec{x}} = - \int_{\vec{x}_0}^{\vec{x}} \vec{F}(\vec{x}') d\vec{x}'$$

Then $W_{12} = W_{10} + W_{02}$

$W_{12} = V(\vec{x}_2) - V(\vec{x}_1)$

Useful convention : $\vec{x}_0 \rightarrow \infty$ (far away from all interacting bodies)



Gradient of the potential

$$\vec{\nabla}_{\vec{x}} \cdot V(\vec{x}) = -\vec{\nabla}_{\vec{x}} \cdot \left[\int_{\vec{x}_0}^{\vec{x}} \vec{F}(\vec{x}') d\vec{x}' \right] = -\vec{\nabla}_{\vec{x}} \left(\underbrace{F(\vec{x}) - F(\vec{x}_0)}_{\text{ck} \Rightarrow 0} \right) = -\vec{F}(\vec{x})$$

with $\frac{\partial F(\vec{x})}{\partial x_i} = F_i(\vec{x})$

$$\vec{\nabla}_{\vec{x}} \cdot V(\vec{x}) = -\vec{F}(\vec{x})$$

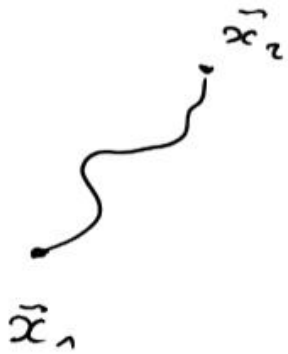
We can represent a conservative force field by its potential

Total Energy E

$$E := K + V = \frac{1}{2} m \vec{v}^2 + V(\vec{x})$$

Theorem

The energy E of a system evolving under conservative forces $\vec{F}(\vec{x})$ (associated to a potential $V(\vec{x})$) is constant.



$$E_1 = E(\vec{x}_1) = \frac{1}{2} m v_1^2 + V(\vec{x}_1)$$

$$E_2 = E(\vec{x}_2) = \frac{1}{2} m v_2^2 + V(\vec{x}_2)$$

$$E_1 - E_2 = \underbrace{K_1 - K_2}_{W_{12}} + \underbrace{V(\vec{x}_1) - V(\vec{x}_2)}_{-W_{12}}$$

$$= 0$$

#

Angular momentum and Torque

Angular momentum $\vec{L} = \vec{x} \times \vec{p}$

Torque $\vec{N} = \vec{x} \times \vec{F}$

$$\begin{aligned}\frac{d\vec{L}}{dt} &= \frac{d\vec{x}}{dt} \times \vec{p} + \vec{x} \times \frac{d\vec{p}}{dt} \\ &= \underbrace{\vec{v} \times \vec{p}}_{=0} + \underbrace{\vec{x} \times \vec{F}}_{\vec{N}}\end{aligned}$$

$$\frac{d\vec{L}}{dt} = \vec{N}$$

Potential Theory

Potential theory : general results

Goal : compute the gravitational potential / forces
due to a large number of stars (point masses)

$N \sim 10^{11}$ for a Milky Way like galaxy

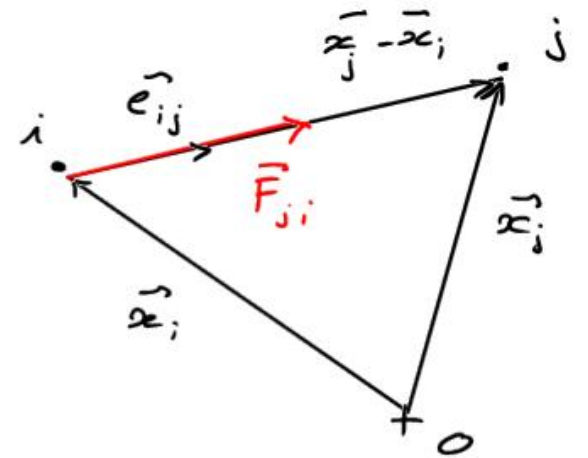
As the relaxation time of such system is very
large (\gg the age of the Universe) we can describe
the system with a smooth analytical potential / density.

Newton Law

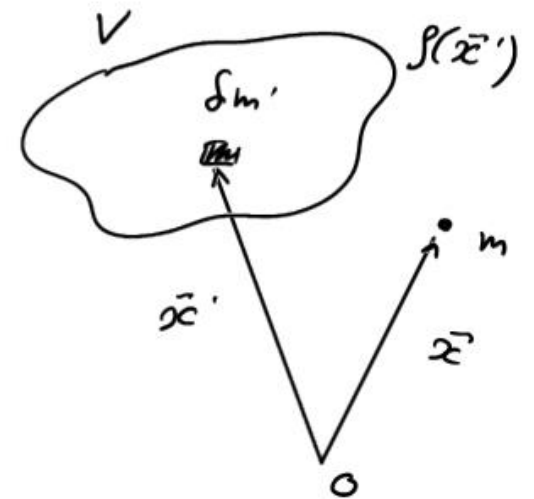
$$\vec{F}_{ji} = \frac{G m_i m_j}{|\vec{x}_j - \vec{x}_i|^2} \vec{e}_{ij} = \frac{G m_i m_j}{|\vec{x}_{ij}|^3} \vec{x}_{ij}$$

Force on a particle of mass m in \vec{x}
due to a distribution of mass $\rho(\vec{x})$

$$\begin{aligned} \delta \vec{F}(\vec{x}) &= \frac{G m \delta m'}{|\vec{x}' - \vec{x}|^3} (\vec{x}' - \vec{x}) \\ &= \frac{G m \rho(\vec{x}') d^3 \vec{x}'}{|\vec{x}' - \vec{x}|^3} (\vec{x}' - \vec{x}) \end{aligned}$$



$$\vec{x}_{ij} = \vec{x}_j - \vec{x}_i$$



So, the total force writes :

$$\vec{F}(\vec{x}) = \int_V \frac{G m \rho(\vec{x}')}{|\vec{x}' - \vec{x}|^3} (\vec{x}' - \vec{x}) d^3\vec{x}'$$

$$= m \underbrace{G \int_V \frac{\rho(\vec{x}')}{|\vec{x}' - \vec{x}|^3} (\vec{x}' - \vec{x}) d^3\vec{x}'}_{\vec{g}(\vec{x})}$$

$\vec{g}(\vec{x})$: gravitational field

$$[\vec{g}] = \frac{\text{cm}}{\text{s}^2} = \frac{\text{erg}}{\text{g}} \frac{1}{\text{cm}}$$

Gravitational Potential

It is easy to see that the function

$$\Delta V(\vec{x}) = - \frac{G m \delta m}{|\vec{x}' - \vec{x}|} \quad \text{is such that}$$

$$\vec{\nabla} \Delta V(\vec{x}) = - \frac{G m \delta m}{|\vec{x}' - \vec{x}|^2} \frac{(\vec{x}' - \vec{x})}{|\vec{x}' - \vec{x}|} = - \Delta \vec{F}(\vec{x})$$

so, by defining

$$V(\vec{x}) = - G \int_V \frac{m \rho(\vec{x}')}{|\vec{x}' - \vec{x}|} d^3\vec{x}'$$

we ensure that

$$\vec{\nabla} V(\vec{x}) = - \vec{F}(\vec{x})$$

We define the specific potential

$$\phi(\bar{x}) = \frac{V(\bar{x})}{m}$$

which writes

$$\phi(\bar{x}) = -G \int_V \frac{\rho(\bar{x}')}{|\bar{x}' - \bar{x}|} d^3\bar{x}'$$

$$[\phi] = \frac{\text{erg}}{g}$$

\equiv specific energy

The gravitational field writes:

$$\vec{g}(\bar{x}) = -\vec{\nabla} \phi(\bar{x})$$

Notes

- The gravity is a conservative force
- $\phi(\vec{x})$: scalar field
 $\vec{g}(\vec{x})$: vector field } contain the same information
- we will always use "specific" quantities

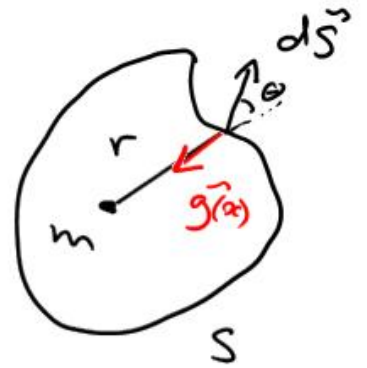
$$V(\vec{x}) \quad \rightarrow \quad \phi(\vec{x})$$

$$K = \frac{1}{2} m \vec{v}^2 \quad \rightarrow \quad \frac{1}{2} \vec{v}^2$$

$$\frac{1}{2} v^2 + \phi(\vec{x}) = \text{specific energy (conserved quantity)}$$

The Gauss's Law

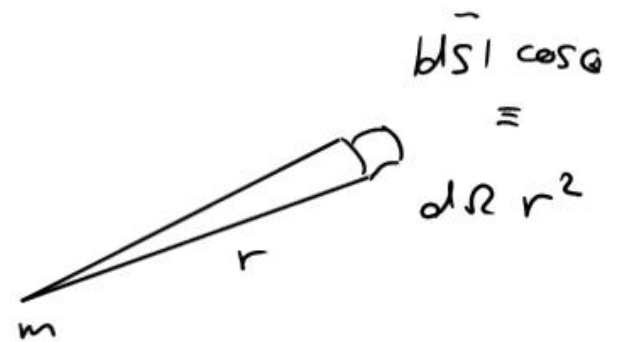
- Consider :
- a single point mass m
 - a surface S around this point
 - a point \vec{x} on the surface at a distance r
 - $\vec{g}(\vec{x})$ the gravitational field
 - $d\vec{S}$, the normal at the surface
 - θ the angle between $\vec{g}(\vec{x})$ and $d\vec{S}$



$$\vec{g}(\vec{x}) \cdot d\vec{S} = -\vec{g}(\vec{x}) \cdot |d\vec{S}| \cos \theta$$

But $|d\vec{S}| \cos \theta = r^2 d\Omega$

$$|\vec{g}(\vec{x})| = \frac{Gm}{r^2}$$



$$\vec{g}(\vec{x}) \cdot d\vec{S} = -Gm d\Omega$$

integrating over any surface

$$\int_S \vec{g}(\vec{x}) \cdot d\vec{S} = \begin{cases} -4\pi G m \\ 0 \end{cases}$$

if m inside S
instead

For multiple masses m_i :

$$\int_S \vec{g}(\vec{x}) \cdot d\vec{S} = -4\pi G \sum_{i \text{ in } S} m_i$$

For a continuous mass distribution $\rho(\vec{x})$

$$\int_S \vec{g}(\vec{x}) \cdot d\vec{S} = -4\pi G \int_V \rho(\vec{x}) d\vec{x} = -4\pi G M$$

Gauss's Law

Divergence of the specific force

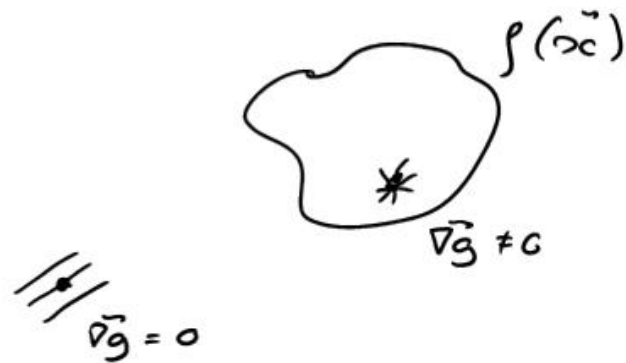
(A)

$$\vec{\nabla}_x \cdot \vec{g}(\vec{x})$$

$$\int_V \vec{\nabla} \cdot \vec{g}(\vec{x}) d^3\vec{x} \stackrel{\text{div. theorem}}{=} \int_S \vec{g}(\vec{x}) d\vec{S}$$

$$\stackrel{\text{Gauss's Law}}{=} -4\pi G \int_V \rho(\vec{x}) d\vec{x}$$

$$\boxed{\vec{\nabla}_x \cdot \vec{g}(\vec{x}) = -4\pi G \rho(\vec{x})}$$



Divergence of the specific force (B) $\vec{\nabla}_{\vec{x}} \cdot \vec{g}(\vec{x})$

$$\vec{g}(\vec{x}) = G \int_V \frac{\rho(\vec{x}')}{|\vec{x}' - \vec{x}|^3} (\vec{x}' - \vec{x}) d^3\vec{x}'$$

$$\vec{\nabla}_{\vec{x}} \cdot \vec{g}(\vec{x}) = G \int_V \vec{\nabla}_{\vec{x}} \cdot \left(\frac{\rho(\vec{x}')}{|\vec{x}' - \vec{x}|^3} (\vec{x}' - \vec{x}) \right) d^3\vec{x}'$$

$$\begin{aligned} \cdot \vec{\nabla}_{\vec{x}} \cdot \left(\frac{\vec{x}' - \vec{x}}{|\vec{x}' - \vec{x}|^3} \right) &= \frac{d}{dx_1} \left(\frac{\vec{x}' - \vec{x}}{|\vec{x}' - \vec{x}|^3} \right) + \frac{d}{dx_2} \left(\frac{\vec{x}' - \vec{x}}{|\vec{x}' - \vec{x}|^3} \right) + \frac{d}{dx_3} \left(\frac{\vec{x}' - \vec{x}}{|\vec{x}' - \vec{x}|^3} \right) \\ &= -\frac{3}{|\vec{x}' - \vec{x}|^3} + \frac{3(\vec{x}' - \vec{x}) \cdot (\vec{x}' - \vec{x})}{|\vec{x}' - \vec{x}|^5} \\ &= \underline{\underline{0}} \quad \text{if} \quad \vec{x}' \neq \vec{x} \end{aligned}$$

$$\vec{\nabla}_{\vec{x}} \cdot \vec{g}(\vec{x}) = G \int_V \vec{\nabla}_{\vec{x}} \cdot \left(\frac{\rho(\vec{x}')}{|\vec{x}' - \vec{x}|^3} (\vec{x}' - \vec{x}) \right) d^3 \vec{x}'$$

$$= G \rho(\vec{x}) \int_{|\vec{x}' - \vec{x}| \leq h} \vec{\nabla}_{\vec{x}} \cdot \left(\frac{\vec{x}' - \vec{x}}{|\vec{x}' - \vec{x}|^3} \right) d^3 \vec{x}'$$

$$= -G \rho(\vec{x}) \int_{|\vec{x}' - \vec{x}| \leq h} \vec{\nabla}_{\vec{x}'} \cdot \left(\frac{\vec{x}' - \vec{x}}{|\vec{x}' - \vec{x}|^3} \right) d^3 \vec{x}'$$

$$= -G \rho(\vec{x}) \int_{|\vec{x}' - \vec{x}| = h} \frac{\vec{x}' - \vec{x}}{|\vec{x}' - \vec{x}|^3} d^2 S'$$

$$\underbrace{4\pi h^2 \cdot \frac{1}{r^2}}_{h=r} = 4\pi$$

$$\underline{\underline{\vec{\nabla}_{\vec{x}} \cdot \vec{g}(\vec{x}) = -4\pi G \rho(\vec{x})}}$$



variable exchange

$$\vec{\nabla}_{\vec{x}} \rho(\vec{x} - \vec{x}') = -\vec{\nabla}_{\vec{x}'} \rho(\vec{x} - \vec{x}')$$

divergence theorem

$$r = |\vec{x}' - \vec{x}| = h$$

$$\frac{\vec{x}' - \vec{x}}{|\vec{x}' - \vec{x}|^3} = \frac{1}{r^2}$$

The Poisson Equation

$$\vec{\nabla}_x \cdot \vec{g}(\vec{x}) = -4\pi G \rho(\vec{x})$$

with: $\vec{\nabla}_x \phi(\vec{x}) = -\vec{g}(\vec{x})$

$$\vec{\nabla}_x \cdot (\vec{\nabla}_x) = \vec{\nabla}_x^2$$

$$\vec{\nabla}_x^2 \phi(\vec{x}) = 4\pi G \rho(\vec{x})$$

Poisson Equation

Note: To ensure a unique solution, boundary conditions are necessary (2nd order diff. eqn.)

ex: $\phi(\infty) = 0$

$$\vec{\nabla}\phi(\infty) = \vec{g}(\infty) = 0$$

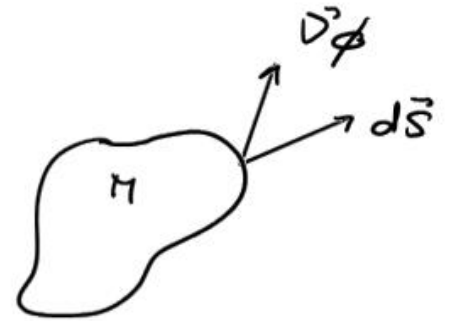
Gauss theorem

integrate the Poisson equation over a volume V that contains a mass M

$$\int_V \nabla^2 \phi(\vec{x}) d^3\vec{x} = \int_V 4\pi G \rho(\vec{x}) d^3\vec{x}$$

div.
Theorem ↓

$$\int_S d^2\vec{s} \cdot \vec{\nabla} \phi = 4\pi G M$$



Gauss theorem

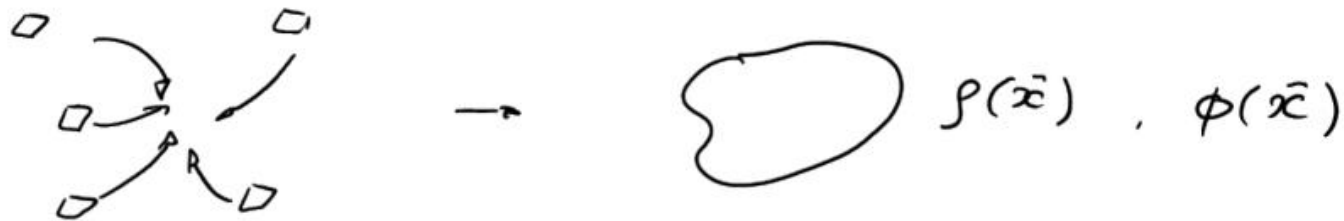
Equivalently :

$$\int_S d^2\vec{s} \cdot \vec{g}(\vec{x}) = -4\pi G M$$

Gauss's Law

Total potential energy (A)

Total work needed to assemble a density distribution $\rho(\vec{x})$

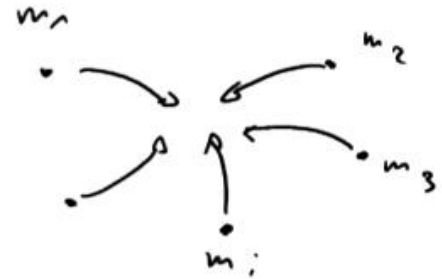


Assume a set of discrete points

• The work to bring the 1st point from ∞ to \vec{x}_1 is 0

• The work to bring the 2nd point from ∞ to \vec{x}_2 is $-\frac{Gm_1m_2}{r_{12}}$

• The work to bring the 3rd point from ∞ to \vec{x}_3 is $-\frac{Gm_1m_3}{r_{13}} - \frac{Gm_2m_3}{r_{23}}$



The total work is thus

$$\begin{aligned} W &= -\frac{G m_1 m_2}{r_{12}} - \frac{G m_1 m_3}{r_{13}} - \frac{G m_2 m_3}{r_{23}} - \dots - \sum_{j=1}^{N-1} \frac{G m_{jN}}{r_{jN}} \\ &= -\sum_{i=1}^N \sum_{j=1}^{i-1} \frac{G m_i m_j}{r_{ij}} = -\frac{1}{2} \sum_{i=1}^N \sum_{\substack{j=1 \\ i \neq j}}^N \frac{G m_i m_j}{r_{ij}} \end{aligned}$$

With $\phi_i = -\sum_{\substack{j=1 \\ j \neq i}}^N \frac{G m_j}{r_{ij}}$

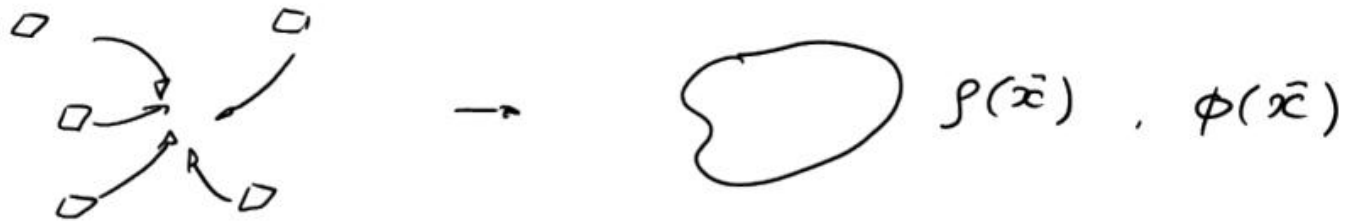
$$W = \frac{1}{2} \sum_{i=1}^N m_i \phi_i \equiv \frac{1}{2} \sum_{i=1}^N V_i$$

For a continuous mass distribution $\rho(\vec{x})$

$$W = \frac{1}{2} \int \rho(\vec{x}) \phi(\vec{x}) d^3 \vec{x}$$

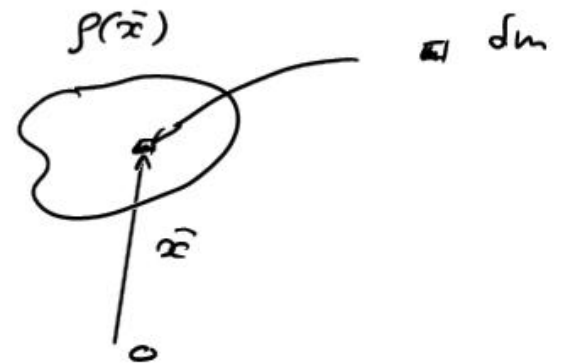
Total potential energy B

Total work needed to assemble a density distribution $\rho(\vec{x})$



- ① Work done to assemble a piece of mass $\delta m = \delta \rho d^3 \vec{x}$ from ∞ to \vec{x} assuming an existing mass distribution $\rho(\vec{x}), \phi(\vec{x})$

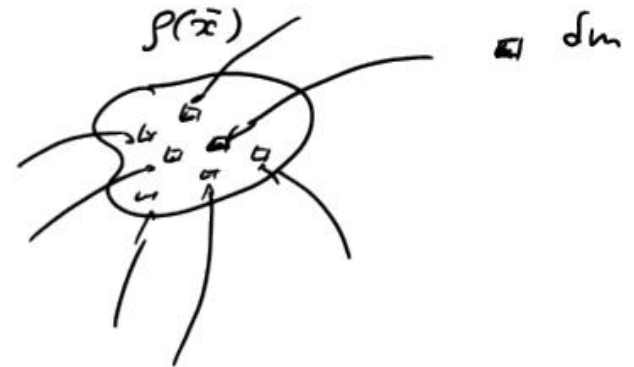
$$\begin{aligned} \delta W_{\vec{x}} &= V(\vec{x}) - \underbrace{V(\infty)}_{=0} \\ &= \delta m \phi(\vec{x}) = \delta \rho(\vec{x}) d^3 \vec{x} \phi(\vec{x}) \end{aligned}$$



To increase energy where the mass distribution by $\delta\rho$

$$\rho(\vec{x}) \rightarrow \rho(\vec{x}) + \delta\rho(\vec{x})$$

$$\delta W = \int \delta\rho(\vec{x}) d^3\vec{x} \phi(\vec{x})$$



Poisson:
$$\delta\rho(\vec{x}) = \frac{1}{4\pi G} \nabla^2 \delta\phi(\vec{x})$$

$$\delta W = \frac{1}{4\pi G} \int \nabla^2 \delta\phi(\vec{x}) \phi(\vec{x}) d^3\vec{x}$$

divergence theorem

$$\int_V d^3x \nabla \cdot \vec{F} = \int_S \vec{F} \cdot d^2s - \int_V d^3x \vec{F} \cdot \vec{\nu}$$

$$= \frac{1}{4\pi G} \underbrace{\int_{S \text{ at } \infty} \phi(\vec{x}) \nabla \delta\phi(\vec{x})}_{=0} - \frac{1}{4\pi G} \int \nabla \phi(\vec{x}) \cdot \nabla (\delta\phi(\vec{x})) d^3\vec{x}$$

as $\phi(\infty) = 0$

$$\nabla \delta\phi(\infty) = \delta g(\infty) = 0$$

$$\delta W = - \frac{1}{4\pi G} \int \vec{\nabla} \phi(\vec{x}) \cdot \vec{\nabla} (\delta \phi(\vec{x})) d^3 \vec{x}$$

with

$$\frac{1}{2} \delta |\vec{\nabla} \phi(\vec{x})|^2 = \delta \vec{\nabla} \phi(\vec{x}) \cdot \vec{\nabla} \phi(\vec{x}) = \vec{\nabla} (\delta \phi(\vec{x})) \cdot \vec{\nabla} \phi(\vec{x})$$

$$\delta W = - \frac{1}{8\pi G} \int \delta |\vec{\nabla} \phi|^2 d^3 x = - \frac{1}{8\pi G} \delta \int |\vec{\nabla} \phi|^2 d^3 x$$

② Contribution of all δW to W

$$W = - \frac{1}{8\pi G} \int |\vec{\nabla} \phi|^2 d^3 x$$

$$W = - \frac{1}{8\pi G} \int |\vec{\nabla} \phi|^2 d^3x$$

Other expression

using the divergence theorem

$$\int d^3\vec{x} \vec{F} \cdot \vec{\nabla} g = \int_S g \cdot \vec{F} \cdot d^2\vec{S} - \int d^3\vec{x} g \vec{\nabla} \cdot \vec{F}$$

$$\int |\vec{\nabla} \phi|^2 d^3x = \int d^3\vec{x} \vec{\nabla} \phi \cdot \vec{\nabla} \phi = \int_{\vec{x} \rightarrow \infty} \underbrace{\phi \vec{\nabla} \phi}_{=0} d^2S - \int d^3\vec{x} \phi \underbrace{\vec{\nabla} \cdot (\vec{\nabla} \phi)}_{= \nabla^2 \phi = 4\pi G \rho}$$

Poisson

$$W = - \frac{1}{8\pi G} \cdot \int -4\pi G \phi \cdot \rho d^3\vec{x}$$

$$W = \frac{1}{2} \int \rho(\vec{x}) \phi(\vec{x}) d^3\vec{x}$$

Other useful expression

$$W = - \int \rho(\vec{x}) \vec{x} \cdot \vec{\nabla} \phi(\vec{x}) d^3\vec{x}$$

Potential Theory

Spherical Systems

$$\rho(\vec{x}) = \rho(r)$$

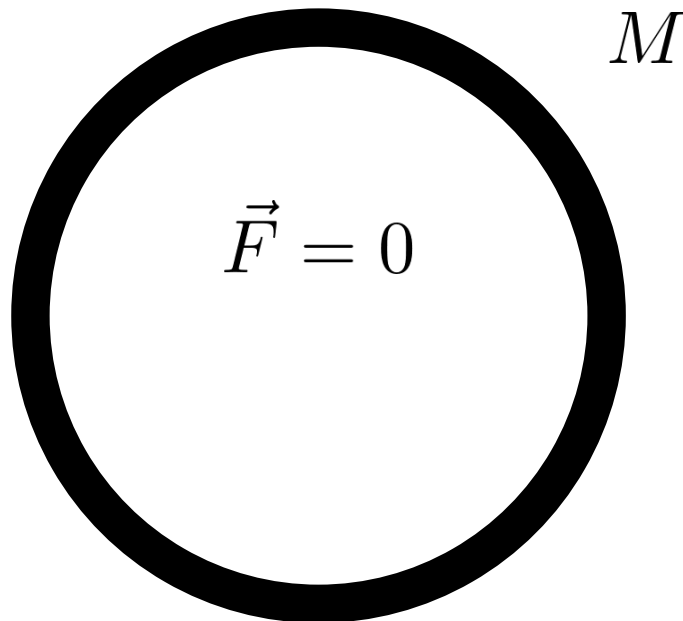
$$r = \sqrt{x^2 + y^2 + z^2}$$

Newton's Theorems

Newton (1642-1727)

First theorem:

A body that is inside a spherical shell of matter experiences no net gravitational force from the shell.



First Newton theorem

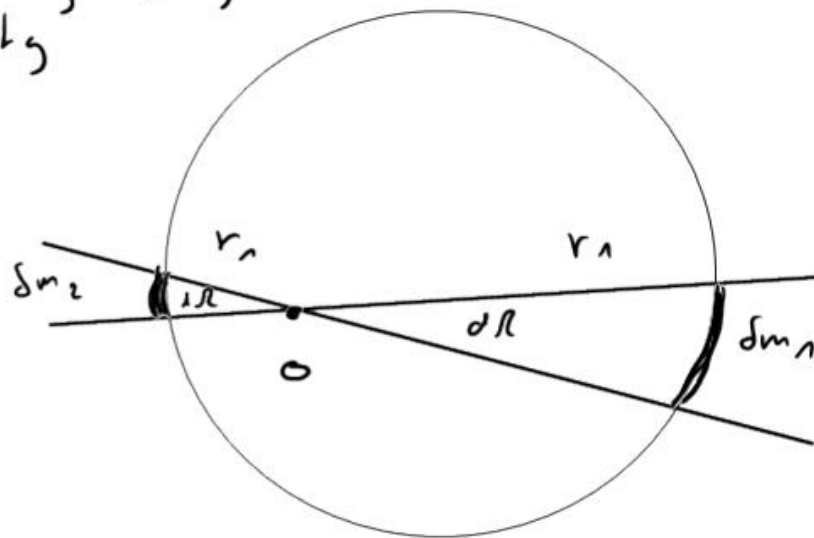
A body that is inside a spherical shell of matter experiences no net gravitational force from that shell

a shell of constant density $\rho(\vec{a}) = \rho$

$$\begin{cases} \delta m_1 = \rho(r_1) \cdot r_1^2 d\Omega dr \\ \delta m_2 = \rho(r_2) \cdot r_2^2 d\Omega dr \end{cases}$$

thus : $\frac{\delta m_1}{\delta m_2} = \frac{r_1^2}{r_2^2}$

and $\frac{\delta m_1}{r_1^2} = \frac{\delta m_2}{r_2^2}$



consequently : $\delta \vec{F}_1 = -\delta \vec{F}_2$
by integrating over the entire shell (d.R)

all forces cancel out ! \neq

Corollary

The gravitational potential $\phi(\vec{x})$ is constant inside the sphere.

$$\text{As } \vec{\nabla}_x \phi(\vec{x}) = \vec{g} = 0 \quad \phi(\vec{x}) = \text{const} \quad \#$$

What is the value of $\phi(\vec{x})$?

$$\phi(\vec{x}) = - \int_V \frac{G \rho(\vec{x}')}{|\vec{x}' - \vec{x}|} d^3 \vec{x}'$$

Spherical coordinates

$$d^3 \vec{x} = r^2 dr d\Omega = 4\pi r^2 dr$$

At the center $\vec{x} = 0$

$$\phi(0) = - 4\pi G \int_0^\infty \frac{\rho(r')}{r} r^2 dr = - 4\pi G \int_0^\infty \rho(r') r dr$$

Density of a shell
of mass M , radius R

$$\rho(r) = \frac{M}{4\pi r^2} \delta(R-r)$$

$$\left(\text{as } 4\pi \int_0^{\infty} \frac{M}{4\pi r^2} \delta(R-r) r^2 dr = M \right)$$

$$\phi(r) = -GM \int_0^{\infty} \frac{\delta(R-r)}{r^2} r dr = -\frac{GM}{R}$$

As the potential is constant for $r < R$

$$\phi(\vec{x}) = -\frac{GM}{R} \quad \vec{x} \in \text{sphere}$$

Newton's Theorems

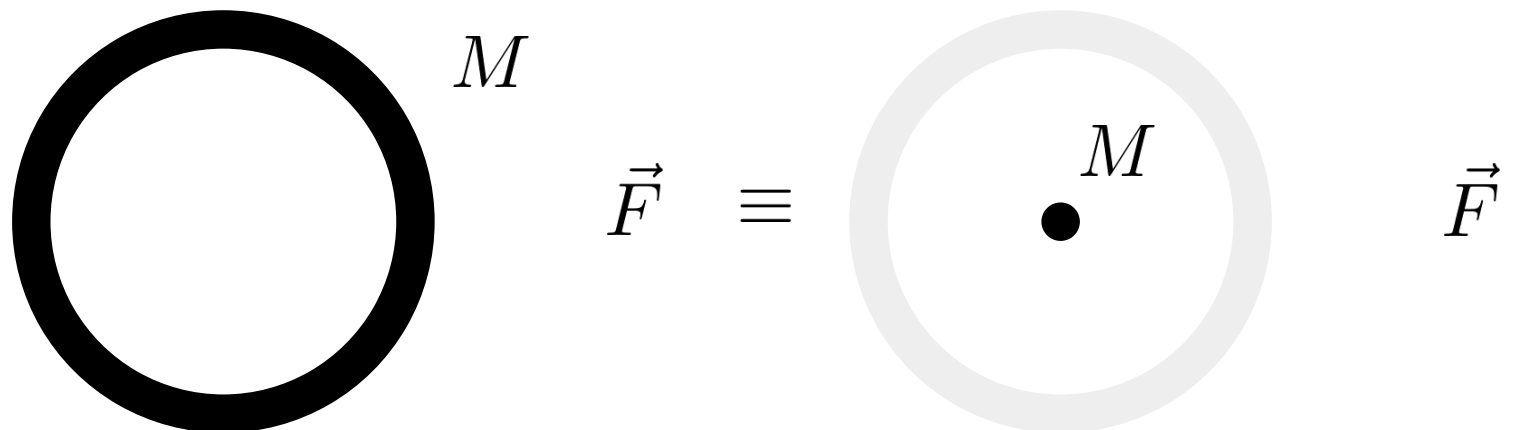
Newton (1642-1727)

First theorem:

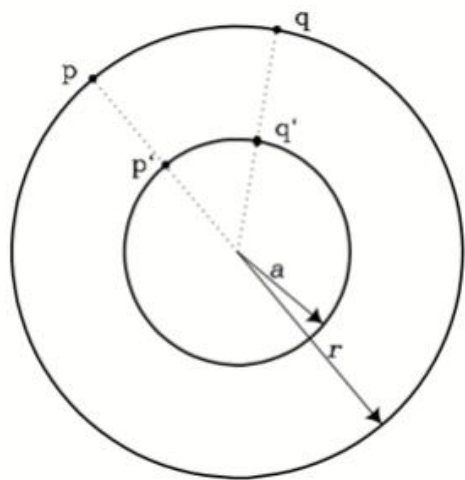
A body that is inside a spherical shell of matter experiences no net gravitational force from the shell.

Second theorem:

The gravitational force on a body that lies outside a spherical shell of matter is the same as it would be if all the shell's matter were concentrated into a point at its centre.



Second Newton Theorem



The gravitational force on a body that lies outside a spherical shell of matter is the same as it would be if all the shell's matter were concentrated into a point at its center

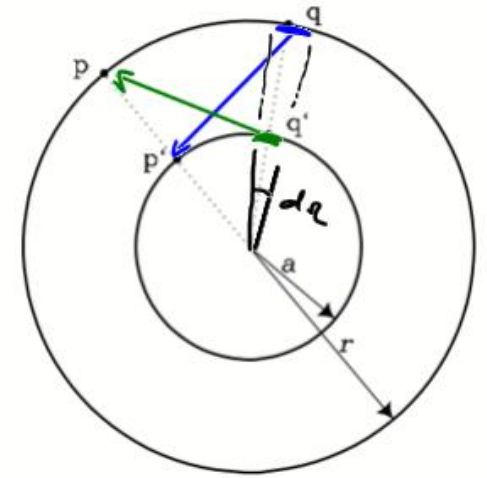
Consider two shells

- 1. inner, with radius a and mass M
- 2. outer, with radius r and mass M

Compute

1. $\phi_p = \phi_i(r)$

2. $\phi_{p'} = \phi_o(a) = -\frac{GM}{r}$



1. contribution of shell_i , in q' with solid angle $\delta\Omega$

• $\delta\phi_i(p) = -\frac{G\delta m_{q'}}{|p-q'|} = -\frac{GM}{|p-q'|} \frac{\delta\Omega}{4\pi}$

2. contribution of shell_o , in q with solid angle $\delta\Omega$

• $\delta\phi_o(p') = -\frac{G\delta m_q}{|p'-q|} = -\frac{GM}{|p'-q|} \frac{\delta\Omega}{4\pi} = \delta\phi_i(p)$

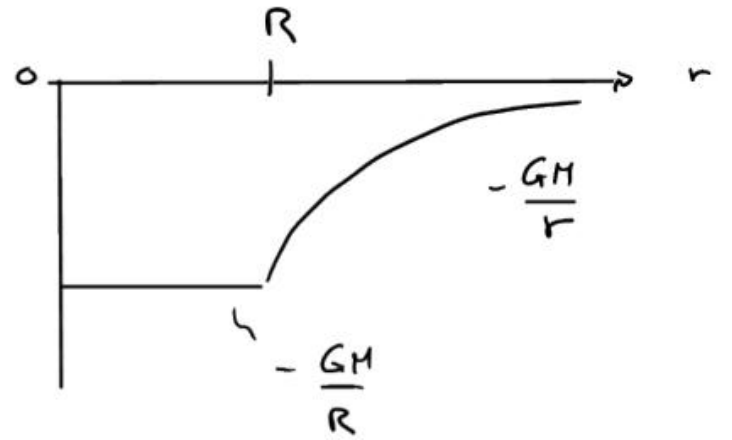
mass inside the solid angle
 $\delta m = \frac{M \delta\Omega}{4\pi}$

Summing over all q' \equiv Summing over all q

$\phi_i(p) = \phi_o(p') = -\frac{GM}{r} \quad \#$

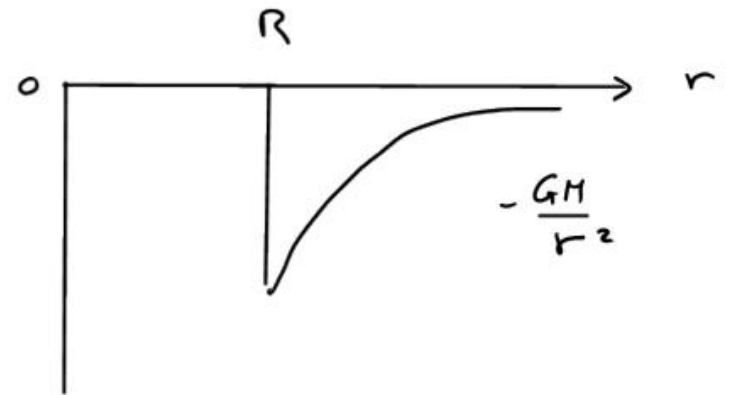
Total potential of a shell of mass M , radius R

$$\phi(r) = \begin{cases} -\frac{GM}{R} & r < R \\ -\frac{GM}{r} & r \geq R \end{cases}$$



Total gravitational field of a shell of mass M , radius R

$$\vec{g}(r) = \begin{cases} 0 & r < R \\ -\frac{GM}{r^2} \vec{e}_r & r \geq R \end{cases}$$



Potential Theory

Spherical Systems general distribution of mass

$$\rho(\vec{x}) = \rho(r)$$

$$r = \sqrt{x^2 + y^2 + z^2}$$

Gravitational field of a spherical model

$f(r)$

Sum of shells

$$g(r) = \int_0^{\infty} \delta g_{r'}(r) \quad \delta g_{r'}(r) = \text{force due to the shell of radius } r'$$

$$= \underbrace{\int_0^r \delta g_{r'}(r)}_{\text{inner shells}} + \underbrace{\int_r^{\infty} \delta g_{r'}(r)}_{\text{outer shells}}$$

inner shells

outer shells

= 0 as we are inside

mass of a shell

$$\delta M(r') = 4\pi r'^2 dr' \rho(r') \quad \delta g_{r'}(r) = - \frac{G \delta M(r')}{r^2} = - 4\pi \rho(r') \frac{r'^2}{r^2} dr'$$

$$g(r) = - \frac{G}{r^2} \underbrace{4\pi \int_0^r \rho(r') r'^2 dr'}_{M(r)} = - \frac{GM(r)}{r^2}$$

Potential of a spherical system

$\phi(r)$

Sum of shells

$$\phi(r) = \int_0^{\infty} \delta\phi_{r'}(r)$$

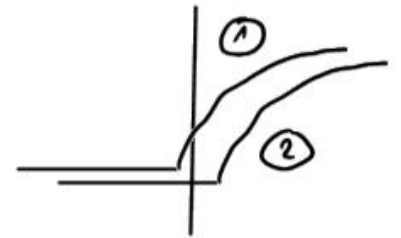
$\delta\phi_{r'}(r)$ = potential on r due to a shell in r'

$$= \int_0^r \delta\phi_{r'}(r) + \int_r^{\infty} \delta\phi_{r'}(r)$$

$$= - \int_0^r \frac{G \delta M(r')}{r} - \int_r^{\infty} \frac{G \delta M(r')}{r'}$$

① shells of radius $r' < r$

② shells of radius $r' > r$
constant potential



$$\text{with } \delta M(r') = 4\pi r'^2 dr' \rho(r')$$

$$\phi(r) = -\frac{G}{r} \underbrace{4\pi \int_0^r \rho(r') r'^2 dr'}_{M(r)} - 4\pi G \int_r^\infty \rho(r') r' dr'$$

$$\phi(r) = -\frac{GM(r)}{r} - 4\pi G \int_r^\infty \rho(r') r' dr'$$

contribution
of the mass
inside r

contribution
of the mass
outside r

Summary : for any spherical mass distribution $\rho(r)$

$$g(r) = - \frac{GM(r)}{r^2}$$

$$M(r) = 4\pi \int_0^{\infty} \rho(r') r'^2 dr'$$

$$\phi(r) = - \frac{GM(r)}{r} - 4\pi G \int_r^{\infty} \rho(r') r' dr'$$

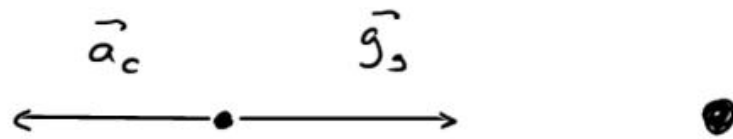
Note $g(r) = - \frac{d\phi}{dr}$

as expected from

$$\vec{g}(\vec{x}) = -\vec{\nabla} \phi(\vec{x})$$

Spherical systems : circular speed, circular velocity

Speed of a test particle in a circular orbit in the potential $\phi(r)$ at a radius r :



\vec{a}_c : centripetal acceleration

$$\frac{v_c^2}{r}$$

\vec{g}_s : gravity acceleration (spec force)

$$-\frac{GM(r)}{r^2} = -\frac{\partial\phi}{\partial r}$$

$$v_c^2 = \frac{GM(r)}{r}$$

$$v_c^2 = r \frac{\partial\phi}{\partial r}$$

$$[v_c^2] : \frac{\text{erg}}{\text{s}}$$

as ϕ

\equiv specific energy

$$GM(r) = r^2 \frac{\partial\phi}{\partial r}$$

Velocity composition

Note: V_0^2 scale with the mass ($M(r)$): it is thus the "important" quantity (spec. energy)

Multi-components system: ex: bulge + stellar halo + DM halo

$$\left\{ \begin{array}{l} \rho_B(r) \quad , \quad M_B(r) \quad , \quad \phi_B(r) \quad \rightarrow \quad V_{c,B}(r) \\ \rho_H(r) \quad , \quad M_H(r) \quad , \quad \phi_H(r) \quad \rightarrow \quad V_{c,H}(r) \\ \rho_{DM}(r) \quad , \quad M_{DM}(r) \quad , \quad \phi_{DM}(r) \quad \rightarrow \quad V_{c,DM}(r) \end{array} \right.$$

$$V_{c,tot}^2 = \frac{GM_{tot}(r)}{r} = \frac{G}{r} \sum_i M(r)$$

$$V_{c,tot}^2 = \sum_i V_{c,i}^2$$

$V_c^2 \sim$ energy: extensive quantity

Period of the circular orbit

$$T(r) = \frac{2\pi r}{v_c(r)} = 2\pi \sqrt{\frac{r^3}{GM(r)}} = 2\pi \sqrt{\frac{r}{\frac{\partial \phi}{\partial r}}}$$

Circular frequency (angular frequency)

$$\Omega(r) = \frac{2\pi}{T(r)} = \sqrt{\frac{GM(r)}{r^3}} = \sqrt{\frac{1}{r} \frac{\partial \phi}{\partial r}}$$

Escape speed v_e

if $\frac{1}{2}v_e^2 > \phi(r) = E > 0$

the particle may escape the system

$$v_e(r) = \sqrt{2|\phi(r)|}$$

Potential energy

from $W = - \int f(\vec{x}) \vec{x} \cdot \vec{\nabla} \phi(\vec{x}) d^3\vec{x}$

$$W = -4\pi G \int_0^{\infty} f(r) M(r) r dr$$

Gravitational radius

radius at which $\frac{GM^2}{r} = W$

(estimation of the system size)

$$r_g = \frac{GM^2}{|W|}$$

Spherical systems : useful relations

	$\rho(r)$	$\Phi(r)$	$M(r)$	$\frac{d\Phi}{dr}$
$\rho(r)$	$\rho(r)$	$\frac{1}{4\pi G} \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{d\Phi}{dr} \right)$	$\frac{1}{4\pi r^2} \frac{dM(r)}{dr}$	$\frac{1}{4\pi G} \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{d\Phi}{dr} \right)$
$\Phi(r)$	$-\frac{GM(r)}{r} - 4\pi G \int_r^\infty dr' r' \rho(r')$	$\Phi(r)$	$-G \int_r^\infty dr' \frac{M(r')}{r'^2}$	$-\int_r^\infty dr' \frac{d\Phi}{dr}$
$M(r)$	$4\pi \int_0^r dr' r'^2 \rho(r')$	$\frac{r^2}{G} \frac{d\Phi}{dr}$	$M(r)$	$\frac{r^2}{G} \frac{d\Phi}{dr}$
$\frac{d\Phi}{dr}$	$\frac{4\pi G}{r^2} \int_0^r dr' r'^2 \rho(r')$	$\frac{d\Phi}{dr}$	$\frac{GM(r)}{r^2}$	$\frac{d\Phi}{dr}$

Poisson in spherical coordinates

$$\frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{d\Phi}{dr} \right) = 4\pi G \rho(r)$$

Mass inside a radius r

$$M(r) = 4\pi \int_0^r dr' r'^2 \rho(r')$$

Potential in spherical coordinates

$$\Phi(r) = -\frac{GM(r)}{r} - 4\pi G \int_r^\infty \rho(r') r' dr'$$

Gradient of the potential in spherical coordinates

$$\frac{d\Phi(r)}{dr} = \frac{GM(r)}{r^2}$$

The End