

Equilibria of collisionless systems

2rd part

Outlines

The Jeans theorems

- Symmetry and integrals of motion

Connections between barotropic fluids and ergodic stellar systems

Self-consistent spherical models with Ergodic DF

- DFs from mass distribution
 - The Eddington formula
 - Examples
- Models defined from DFs
 - Polytropes and Plummer models

Quick summary of the last lecture

Distribution function (DF)

Definition ① $f(\vec{x}, \vec{v}, t)$ or $f(\vec{w}, t)$ such that

$f(\vec{x}, \vec{v}, t) d^3\vec{x} d^3\vec{v}$ or $f(\vec{w}, t) d^3\vec{w}$
 is the probability that at the time t ,
 a randomly chosen star "i" has its position \vec{x}_i ,
 an velocity \vec{v}_i , or phase space coordinates \vec{w}_i
 in the ranges $\vec{x}_i \in [\vec{x}, \vec{x} + d\vec{x}]$
 $\vec{v}_i \in [\vec{v}, \vec{v} + d\vec{v}]$
 $\equiv \vec{w}_i \in [\vec{w}, \vec{w} + d\vec{w}]$

obviously :
 (normalisation)

$$\int f(\vec{x}, \vec{v}, t) d^3\vec{x} d^3\vec{v} = 1$$

$$\equiv \int f(\vec{w}, t) d^3\vec{w} = 1$$

the particle
 is for sure
 somewhere in
 the phase space

$f(\vec{x}, \vec{v}, t)$ is the probability density of the phase space.

The collisionless Boltzmann equation

- What is the evolution of $f(\vec{w})$ over time?

As the mass, the probability is a conserved quantity.

$$f = N\bar{f}$$

the number of stars is a conserved quantity.

δ'

in the phase space

Continuity equation (similar than for hydrodynamics)

Gauss  the time variation of the mass in V : $\frac{dM}{dt} = \sum_{\text{faces}} \vec{S} \cdot \vec{V} \cdot d\vec{S}$
mass flux

Mass conservation

$$\frac{\partial \rho}{\partial t} + \vec{\nabla}_x \cdot (\rho \vec{v}) = 0$$

Probability conservation

$$\frac{\partial f}{\partial t} + \vec{\nabla}_w \cdot (f \vec{w}) = 0$$

mass flux through the surface
of the volume

probability flux through the surface
of the volume

The Collisionless Boltzmann equation in various coordinates

Generalized coordinates

$$\vec{p} = \frac{\partial L(\vec{q}, \vec{p})}{\partial \dot{\vec{q}}}$$

$$\frac{\partial f}{\partial t} + \dot{\vec{q}} \cdot \frac{\partial f}{\partial \vec{q}} + \dot{\vec{p}} \cdot \frac{\partial f}{\partial \vec{p}} \equiv \frac{\partial f}{\partial t} + \frac{\partial f}{\partial \vec{q}} \cdot \frac{\partial H}{\partial \vec{p}} - \frac{\partial f}{\partial \vec{p}} \cdot \frac{\partial H}{\partial \vec{q}} = 0$$

Cartesian coordinates

$$\begin{cases} p_x = \dot{x} = v_x \\ p_y = \dot{y} = v_y \\ p_z = \dot{z} = v_z \end{cases} \quad H = \frac{1}{2} (v_x^2 + v_y^2 + v_z^2) + \Phi(x, y, z)$$

$$\frac{\partial f}{\partial t} + \vec{v} \cdot \frac{\partial f}{\partial \vec{x}} - \frac{\partial \Phi}{\partial \vec{x}} \cdot \frac{\partial f}{\partial \vec{v}} = 0$$

Spherical coordinates

$$\begin{cases} p_r = \dot{r} = v_r \\ p_\theta = r^2 \dot{\theta} = r v_\theta \\ p_\phi = r^2 \sin^2(\theta) \dot{\phi} = r \sin(\theta) v_\phi \end{cases}$$

$$H = \frac{1}{2} \left(p_r^2 + \frac{p_\theta^2}{r^2} + \frac{p_\phi^2}{r^2 \sin^2(\theta)} \right) + \Phi(R, \theta, \phi)$$

$$\frac{\partial f}{\partial t} + p_r \frac{\partial f}{\partial r} + \frac{p_\theta}{r^2} \frac{\partial f}{\partial \theta} + \frac{p_\phi}{r^2 \sin^2(\theta)} \frac{\partial f}{\partial \phi} - \left(\frac{\partial \Phi}{\partial r} - \frac{p_\theta^2}{r^3} - \frac{p_\phi^2}{r^3 \sin^2(\theta)} \right) \frac{\partial f}{\partial p_r} - \left(\frac{\partial \Phi}{\partial \theta} - \frac{p_\phi^2 \cos(\theta)}{r^2 \sin^3(\theta)} \right) \frac{\partial f}{\partial p_\theta} - \frac{\partial \Phi}{\partial \phi} \frac{\partial f}{\partial p_\phi} = 0$$

Cylindrical coordinates

$$\begin{cases} p_R = \dot{R} = v_R \\ p_\phi = R^2 \dot{\phi} = R \\ p_z = \dot{z} = v_z \end{cases}$$

$$H = \frac{1}{2} \left(p_R^2 + \frac{p_\phi^2}{R^2} + p_z^2 \right) + \Phi(R, \phi, z)$$

$$\frac{\partial f}{\partial t} + p_R \frac{\partial f}{\partial R} + \frac{p_\phi}{R^2} \frac{\partial f}{\partial \phi} + p_z \frac{\partial f}{\partial z} - \left(\frac{\partial \Phi}{\partial R} - \frac{p_\phi^2}{R^3} \right) \frac{\partial f}{\partial p_R} - \frac{\partial \Phi}{\partial \phi} \frac{\partial f}{\partial p_\phi} - \frac{\partial \Phi}{\partial z} \frac{\partial f}{\partial p_z} = 0$$

Jeans theorems

- I. Any steady-state solution of the collisionless Boltzmann equation depends on the phase-space coordinates only through integrals of motion in the given potential.

Demonstration:

If a function is a solution of the steady-state collisionless Boltzmann equation, then, it is an integral of motion, thus the function depends on the phase-space coordinates only through integrals of motion (itself!).

- II. Any function of integrals of motion yields a steady-state solution of the collisionless Boltzmann equation.

Extremely useful to generate DFs

Demonstration:

Assume $f(\vec{x}, \vec{v}) = f(I_1(\vec{x}, \vec{v}), I_2(\vec{x}, \vec{v}), I_3(\vec{x}, \vec{v}), \dots)$ and derive...

Equilibria of collisionless systems

Symmetries and DFs

Choices of DFs and relations with the velocity moments

1. DFs that depend only on H

(no particular symmetry)
except time:

$$\phi = \phi(\vec{x}, t)$$

Ergodic distribution functions

Example $\left\{ \begin{array}{l} H(\vec{x}, \vec{v}) = \frac{1}{2} \vec{v}^2 + \phi(\vec{x}) \\ g = g\left(\frac{1}{2} \vec{v}^2 + \phi(\vec{x})\right) \end{array} \right.$

→ Note: the velocity dependency is
only through v^2 (isotropic)

Mean velocity

$$\bar{v}(\vec{x}) = \frac{1}{g(\vec{x})} \int \vec{v} g\left(\frac{1}{2} \vec{v}^2 + \phi(\vec{x})\right) d^3\vec{v} = 0$$

indeed

$$\bar{v}_x(\vec{x}) = \frac{1}{g(\vec{x})} \int_{-\infty}^{\infty} dv_t \int_{-\infty}^{\infty} dv_y \int_{-\infty}^{\infty} dv_x \underbrace{v_x}_{\text{odd}} \underbrace{g\left(\frac{1}{2} \vec{v}^2 + \phi(\vec{x})\right)}_{\text{even}} = 0$$

1. DFs that depend only on \mathbf{U}

Velocity dispersions

$$\sigma_{ij}^2 = \frac{1}{V(\bar{\mathbf{v}})} \int \underbrace{(v_i - \bar{v}_i)(v_j - \bar{v}_j)}_{=0} g\left(\frac{1}{2}\bar{v}^2 + \phi(\bar{\mathbf{v}})\right) d\bar{v}$$

$$= \delta_{ij} \sigma^2 \quad \text{odd, except if } i=j \quad (\sigma_{xx} = \sigma_{yy} = \sigma_{zz})$$

$$\sigma^2 = \frac{1}{V(\bar{\mathbf{v}})} \int_{-\infty}^{\infty} v_x^2 dv_x \int_{-\infty}^{\infty} dv_y \int_{-\infty}^{\infty} dv_z g\left(\frac{1}{2}\bar{v}^2 + \phi(\bar{\mathbf{v}})\right)$$

using spherical coord in velocity space : $\begin{cases} dv_x dv_y dv_z = V^2 \sin \theta \, dv \, d\phi \, d\theta \\ v_x^2 = V^2 \cos^2 \theta \\ V^2 = v_x^2 + v_y^2 + v_z^2 \end{cases}$

$$\sigma^2 = \frac{4}{3} \pi \frac{1}{V(\bar{\mathbf{v}})} \int_0^{\infty} v^4 g\left(\frac{1}{2}v^2 + \phi(\bar{\mathbf{v}})\right) dv$$

$$\sigma_{ij} = \begin{pmatrix} \sigma & 0 & 0 \\ 0 & \sigma & 0 \\ 0 & 0 & \sigma \end{pmatrix}$$

isotropic system :
the velocity ellipsoid is a sphere

2. DFs that depend on H and \vec{L}

(spherical symmetry)
 $\phi = \phi(r)$

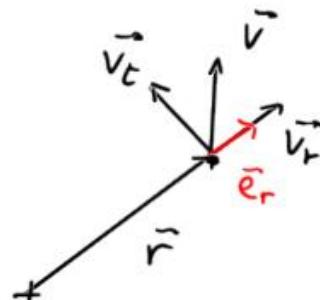
We restrict our study to symmetric DFs : indep. of any direction

$$f(\vec{x}, \vec{v}) = f(H, L)$$

$$\vec{L} \rightarrow |\vec{L}| = L$$

we consider

$$v_r = \vec{v} \cdot \hat{e}_r$$

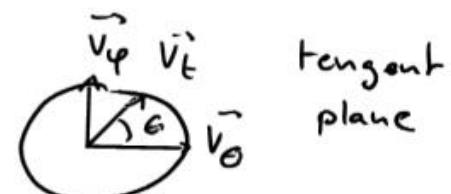


$$\text{radial velocity : } \tilde{v}_r = v_r \hat{e}_r$$

$$\text{tangential velocity : } \tilde{v}_t = \vec{v} - v_r \hat{e}_r$$

$$\tilde{v}_t^2 = \tilde{v}_\theta^2 + \tilde{v}_\varphi^2$$

$$v_\theta = v_t \cos \theta \quad v_\varphi = v_t \sin \theta$$



$$\left\{ \begin{array}{l} L = r^2 \dot{\theta} = r v_t = r \sqrt{v_\theta^2 + v_\varphi^2} \\ H = \frac{1}{2} \underbrace{(v_r^2 + v_t^2)}_{v_r^2 + v_\theta^2 + v_\varphi^2} + \phi(r) \end{array} \right.$$

2. DFs that depend on U and \vec{L}

Mean velocity

$$\begin{aligned}\bar{v}_r &= \frac{1}{\mathcal{N}(v)} \int v_r f\left(\frac{1}{2}(v_r^2 + v_t^2) + \phi(r), rv_t\right) d^3v \\ &= \frac{1}{\mathcal{N}(v)} \int_{-\infty}^{\infty} \underbrace{v_r}_{\text{odd in } v_r} dv_r \underbrace{\int d^2 \bar{v}_t f\left(\frac{1}{2}(v_r^2 + v_t^2) + \phi(r), rv_t\right)}_{\text{even in } v_r} = 0 \\ \bar{v}_t &= \frac{1}{\mathcal{N}(v)} \int \underbrace{\bar{v}_t}_{\text{odd in } v_t} d^2 \bar{v}_t \int_{-\infty}^{\infty} dv_r \underbrace{f\left(\frac{1}{2}(v_r^2 + v_t^2) + \phi(r), rv_t\right)}_{\text{even in } v_t} = 0 \\ &\quad \text{Note } v_t \in [0, \infty]\end{aligned}$$

2. DFs that depend on H and \vec{L}

Velocity dispersions

$\left\{ \begin{array}{l} \text{veloc. in c.g.s. coord} \\ dV_\theta dV_\phi \rightarrow V_t dV_t \end{array} \right.$

$$\begin{aligned}\sigma_r^2 &= \frac{1}{\nu(\infty)} \int_{-\infty}^{\infty} v_r^2 dV_r \int_{-\infty}^{\infty} dV_\theta \int_{-\infty}^{\infty} dV_\phi g\left(\frac{1}{2}(v_r^2 + v_\theta^2 + v_\phi^2) + \phi(r), r v_t\right) \\ &= \frac{2\pi}{\nu(\infty)} \int_{-\infty}^{\infty} v_r^2 dV_r \int_0^{\infty} dV_t v_t g\left(\frac{1}{2}(v_r^2 + v_t^2) + \phi(r), r v_t\right) \neq 0\end{aligned}$$

$$\begin{aligned}\sigma_\phi^2 &= \frac{1}{\nu(\infty)} \int_{-\infty}^{\infty} v_\phi^2 dV_\theta \int_{-\infty}^{\infty} dV_\phi \int_{-\infty}^{\infty} dV_r g\left(\frac{1}{2}(v_r^2 + v_\theta^2 + v_\phi^2) + \phi(r), r v_t\right) \\ &\quad dV_\theta dV_\phi \rightarrow V_t dV_t \\ &= \frac{1}{\nu(\infty)} \int_{-\infty}^{\infty} \int_0^{\infty} v_\theta^2 v_t dV_t dV_r g\left(\frac{1}{2}(v_r^2 + v_t^2) + \phi(r), r v_t\right) \\ &\quad v_\theta^2 v_t dV_t = v_t^2 \cos^2 \Theta v_t dV_t \rightarrow \pi v_t^3 dV_t \\ &= \frac{\pi}{\nu(\infty)} \int_0^{\infty} dV_t v_t^3 \int_{-\infty}^{\infty} dV_r g\left(\frac{1}{2}(v_r^2 + v_t^2) + \phi(r), r v_t\right)\end{aligned}$$

2. DFs that depend on H and \vec{L}

Velocity dispersions

$$\begin{aligned}\sigma_\varphi^2 &= \frac{1}{\rho(\infty)} \int_{-\infty}^{\infty} v_\varphi^2 dv_\varphi \int_{-\infty}^{\infty} dv_r \int_{-\infty}^{\infty} dv_t f\left(\frac{1}{2}(v_r^2 + v_t^2 + v_\varphi^2) + \phi(r), rv_t\right) \\ &= \frac{1}{\rho(\infty)} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} v_\varphi^2 v_t dv_t dv_r f\left(\frac{1}{2}(v_r^2 + v_t^2) + \phi(r), rv_t\right) \\ &= \frac{\pi}{\rho(\infty)} \int_0^{\infty} dv_t v_t^3 \int_{-\infty}^{\infty} dv_r f\left(\frac{1}{2}(v_r^2 + v_t^2) + \phi(r), rv_t\right)\end{aligned}$$

$d v_0 d v_\varphi \rightarrow v_t dv_t$

$v_\varphi^2 = v_t^2 \sin^2 \theta \rightarrow \pi v_t^3 dv_t$

$$\sigma_\varphi^2 = \sigma_\theta^2$$

oh, spherical symmetry

$$\sigma_{r,i} = 0 \text{ if } i \neq j$$

Anisotropic system

$$\sigma_r^2 \neq \sigma_\theta^2 = \sigma_\varphi^2$$

The velocity ellipsoid is
oblate  or prolate 

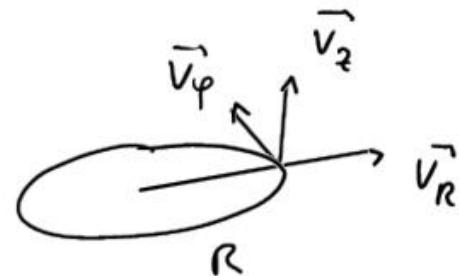
3. DFs that depend on H and L_z

(cylindrical symmetry)

$$\phi = \phi(R, |z|)$$

$$f(\vec{x}, \vec{v}) = f(H, L_z)$$

$$\left\{ \begin{array}{l} H = \frac{1}{2} (v_r^2 + v_\varphi^2 + v_z^2) + \phi(R, z) \\ L_z = R^2 \dot{\varphi} = R v_\varphi \quad (v_\varphi = R \dot{\varphi}) \end{array} \right.$$



Mean velocity

$$\bar{v}_R = \int dV_R v_R \int dV_\varphi dV_z f\left(\frac{1}{2} (v_r^2 + v_\varphi^2 + v_z^2) + \phi(R, z), R v_\varphi\right) = 0$$

$$\bar{v}_z = \int dV_z v_z \int dV_R dV_\varphi f\left(\frac{1}{2} (v_r^2 + v_\varphi^2 + v_z^2) + \phi(R, z), R v_\varphi\right) = 0$$

$$\bar{v}_\varphi = \int dV_\varphi v_\varphi \int dV_R dV_z f\left(\frac{1}{2} (v_r^2 + v_\varphi^2 + v_z^2) + \phi(R, z), R v_\varphi\right) \neq 0 \quad \text{in general (net rotation)}$$

$$= 0 \quad \text{only if } f \text{ is an even function of } L_z = R v_\varphi$$

odd in v_R

, odd in v_z

3. DFs that depend on H and L_z

Velocity dispersions

$$\sigma_n^2 = \frac{1}{N(\infty)} \int dv_R v_R^2 \int dv_z \int dv_\varphi f\left(\frac{1}{2}(v_r^2 + v_\varphi^2 + v_z^2) + \phi(r, z), R v_\varphi\right)$$

$$\sigma_z^2 = \sigma_R^2 \quad (\text{both variables } v_R \text{ and } v_z \text{ can be exchanged})$$

$$\sigma_\varphi^2 = \frac{1}{N(\infty)} \int dv_\varphi (v_\varphi - \bar{v}_\varphi)^2 \int dv_z \int dv_R f\left(\frac{1}{2}(v_r^2 + v_\varphi^2 + v_z^2) + \phi(r, z), R v_\varphi\right)$$

σ is isotropic in the meridional plane



Anisotropic system

$$\sigma_\varphi^2 \neq \sigma_R^2 = \sigma_z^2$$

The velocity ellipsoid is oblate or prolate

Interpretation : relation between the DF and the orbits

Example 1

1-D potential

$$\left\{ \begin{array}{l} E = \frac{1}{2} v^2 + \phi(r) \\ v = \pm \sqrt{2(E - \phi(r))} \end{array} \right.$$

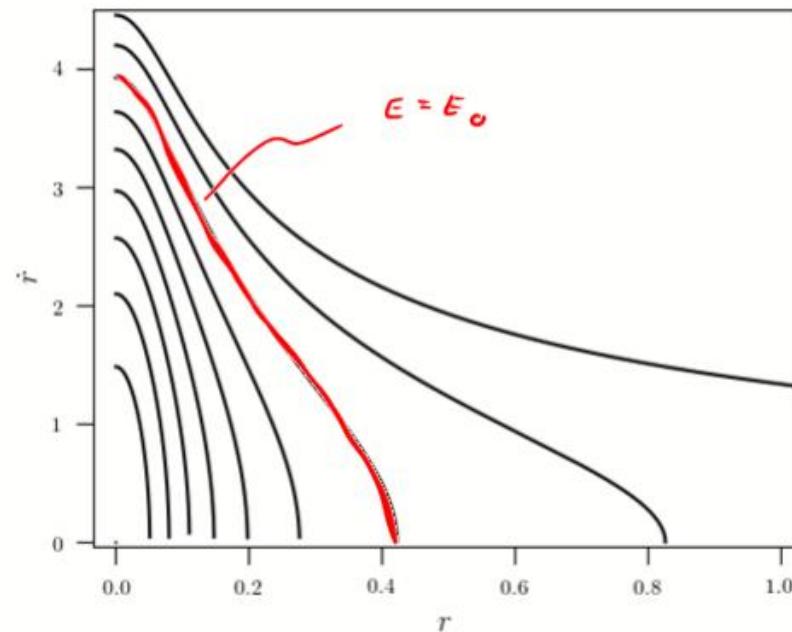
a) $\delta(x, v) = \delta(E) = \delta(E - E_0)$

$$\left\{ \begin{array}{ll} \text{oo} & v = \pm \sqrt{2(E_0 - \phi(r))} \\ 0 & \text{instead} \end{array} \right.$$

b) $\delta(x, v) = \delta(t)$

↳

give a weight to
orbits depending on
their energy



Example 2

- 3D - spherical potential
- orbits described in planes, characterized by (E, L)

a) Ergodic DF : $g(\bar{x}, \bar{v}) = g(E)$

$$\begin{pmatrix} \sigma & 0 & 0 \\ 0 & \sigma & 0 \\ 0 & 0 & \sigma \end{pmatrix}$$

- model built-out of all orbits of all planes with a weight that depends on the energy (radial and circular orbits are weighted the same way) invariant under rotation (isotropic)

b) non Ergodic DF : $g(\bar{x}, \bar{v}) = g(E, L)$

$$\sigma_r^2 \neq \sigma_\theta^2 = \sigma_\varphi^2$$

- model built-out of all orbits of all planes with a weight that depends on E and L (radial and circular orbits are weighted differently)

c) non Ergodic DF : $g(\bar{x}, \bar{v}) = g(E, \vec{L}) = g_E(E) g_L(\vec{L})$

$$\text{with } g_L(\vec{L}) = 0 \text{ if } \begin{cases} L_x + c \\ L_y + c \\ L_z = 0 \end{cases}$$

- model built-out of orbits lying in the $z=0$ plane with a weight that depends on E and L_z

$$\sigma_\varphi^2 \neq \sigma_\theta^2 = \sigma_z^2$$

Questions

Why an ergodic DF where there is a priori no constraints on the symmetry of the potential leads to an isotropic velocity dispersion tensor ?

$$\Phi(x, y, z) \quad f(H) \quad \implies \quad \begin{pmatrix} \sigma & 0 & 0 \\ 0 & \sigma & 0 \\ 0 & 0 & \sigma \end{pmatrix}$$

Equilibria of collisionless systems

**Connections between
barotropic fluids and
ergodic stellar systems**

Connections between fluids and stellar systems

In fluid dynamics, the properties of a fluid at rest in a potential is obtained through the Euler equation

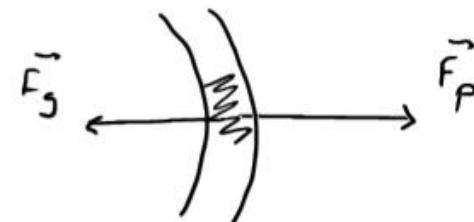
$$\frac{d\vec{v}}{dt} = - \underbrace{\frac{\vec{\nabla} p}{\rho}}_{\text{pressure force}} - \underbrace{\vec{\nabla} \phi}_{\text{gravity}}$$

At rest

$$\frac{d\vec{v}}{dt} = 0$$

pressure
force gravity

$$\frac{\vec{\nabla} p}{\rho} = - \vec{\nabla} \phi$$



In 1-D (isothermal case)

$$\frac{1}{\rho} \frac{dp}{dr} = - \frac{d\phi}{dr}$$

Equation of state (EOS)

$$\rho = \rho(\rho, T)$$

$\rho = \rho(\rho)$: barotropic (depends only on the density)

$P = K\rho^\gamma$: polytropic

$P = \frac{k_B T}{m} \rho$: isotherm ($T = \text{cte}$)

Together with the hydrostatic equation,

$$\boxed{\frac{1}{\rho} \frac{dP}{d\rho} = - \frac{d\phi}{dr}}$$

This relates $\rho(r)$ with $\phi(r)$.

Self - gravity

The Poisson equation

$$\vec{\nabla}^2 \phi = 4\pi G \rho$$

This constraints the potential $\phi(r)$

or equivalently the density $\rho(r)$

Parallel between gaseous systems and ergodic stellar systems

Note An ergodic DF is such that the velocity dispersion is isotropic

(σ_σ) = similar to a gaseous system

Idea : define a function $P(\rho)$ (an equivalent of the pressure)
which is such that :

$$\frac{\vec{\nabla} P}{\rho} = - \vec{\nabla} \phi$$

$$\frac{1}{\rho} \frac{dP}{d\rho} = - \frac{d\phi}{dr}$$

if spherical

If we find $P(\rho)$ for our stellar system, its density will be the same than the one of a gaseous system as the "pressure" will be equivalent.

Ergodic DF

$$g(\bar{x}, \bar{v}) = g\left(\frac{1}{2}\bar{v}^2 + \phi(\bar{x})\right)$$

Density

$$f(\bar{x}) = \int d^3v \ g(\bar{x}, \bar{v})$$

$$= \int d^3v \ g\left(\frac{1}{2}\bar{v}^2 + \phi(\bar{x})\right)$$

as f depends on \bar{x} only through ϕ , we can write:

$f = f(\phi)$ and assuming it to be bijective

$$\boxed{\phi = \phi(f)}$$

we can then compute $\frac{\partial \phi}{\partial f}$

Lets define the function $\rho(\rho)$

$$\rho(\rho) = - \int_0^\rho d\rho' \rho' \frac{\partial \phi}{\partial \rho}(\rho')$$

Differentiating gives

$$\frac{\partial \rho}{\partial \rho}(\rho) = - \rho \frac{\partial \phi}{\partial \rho}(\rho)$$

with $\rho = \rho(\vec{x})$ $\frac{\partial \rho}{\partial \rho} = \vec{\nabla} \rho \cdot \frac{\partial \vec{x}}{\partial \rho}$, $\frac{\partial \phi}{\partial \rho} = \vec{\nabla} \phi \cdot \frac{\partial \vec{x}}{\partial \rho}$

it becomes:

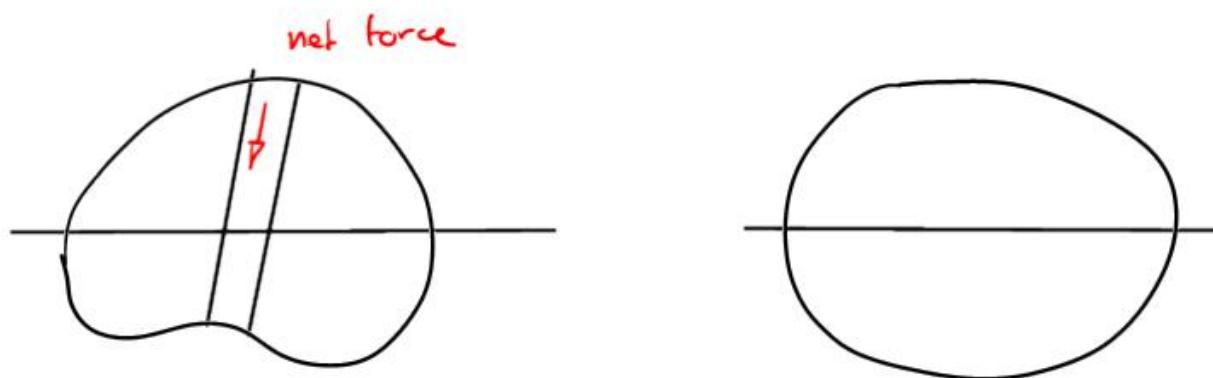
$$\frac{\vec{\nabla} \rho}{\rho} = - \vec{\nabla} \phi$$

Which is the equation of equilibrium for a barotropic fluid.

Conclusions

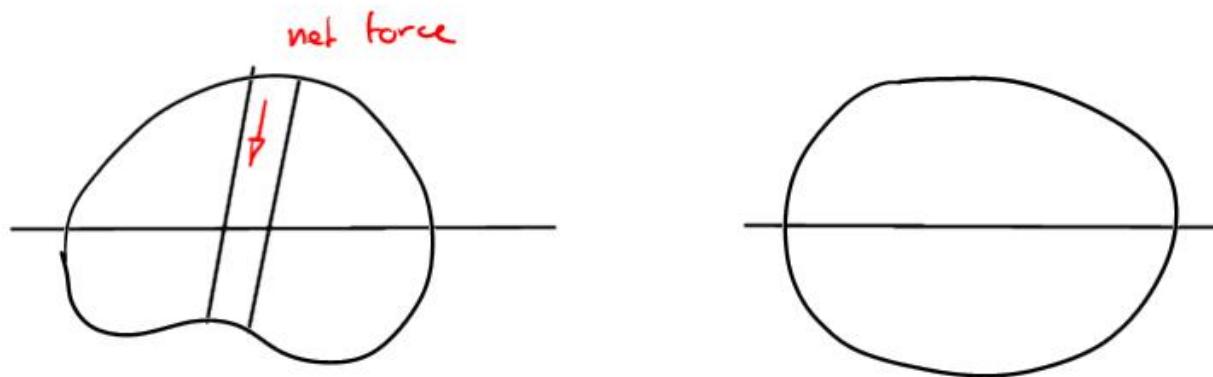
- ① To demonstrate the analogy between an ergodic stellar system and a gaseous system, it is sufficient to show that the DF leads to the same pressure form $P(\rho)$
- ② An ergodic isolated stellar system is spherical

As an isolated finite, static, self-gravitating barotropic fluid must be spherical. (Lichtenstein's theorem)



As a stellar system with an ergodic DF satisfies the same equations, it must be spherical

As an isolated finite, static, self-gravitating barotropic fluid must be spherical. (Lichtenstein's theorem)



Theorem

Any isolated, finite, stellar system with an ergodic distribution function must be spherical.

Equilibria of collisionless systems

**Self-consistent spherical
models with ergodic DFs**

Distribution function for spherical systems

(Ergodic DFs)
isotropic velocity field

Goal provide a self-consistent model for a spherical stellar system

- ex: - elliptical galaxy
- galaxy cluster
- globular cluster

self-consistent = the density obtained from the DF is the one that generates the potential
i.e. is a solution of the **Poisson equation**

$$\rho(\vec{x}) = Nm \underbrace{\int d^3v g(\vec{x}, \vec{v})}_{V(\vec{x})} = \frac{1}{4\pi G} \tilde{\nabla}^2 \Phi$$

assumptions : only one type of stars (one stellar population)
i.e. all stars are modeled through the same DF.

Distribution function for spherical systems

- Method ①

- from $\rho(r)$ $\phi(r)$ \rightarrow set $f(\varepsilon) = f\left(\frac{1}{2}v^2 + \phi(r)\right)$

- Method ②

- assume $f(\varepsilon)$ \rightarrow set $\rho(r)$

Spherical systems defined by DFs

Equilibria of collisionless systems

DFs from mass distribution

Determination of the DF from the mass distribution

- We assume that $\rho(r)$ and $\phi(r)$ are known functions related together by the Poisson equation : $\nabla^2 \phi = 4\pi G \rho$

- The density is related to the DF : $\rho(r) = \frac{g(r)}{Nm} = \frac{\rho(r)}{M}$

$$\begin{aligned} g(r) &= M v(r) = \int g(E) d^3 \tilde{v} & E = \frac{1}{2} \dot{x}^2 + \frac{1}{2} \dot{y}^2 + \frac{1}{2} \dot{z}^2 + \phi(r) \\ &= \int_0^\infty dv 4\pi v^2 g\left(\frac{1}{2} v^2 + \phi(r)\right) & = \frac{1}{2} v^2 + \phi(r) \\ && \text{(isotropic in the velocity space)} \end{aligned}$$

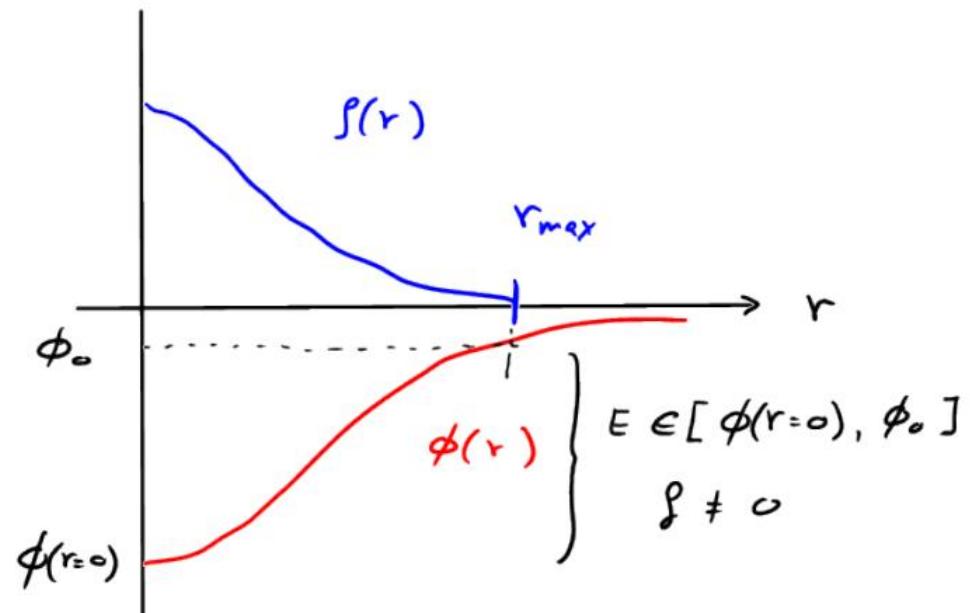
We are thus looking for DFs f that satisfy :

$$v(r) = \sqrt{\int_0^\infty v^2 f\left(\frac{1}{2} v^2 + \phi(r)\right) dv}$$

Density and potential

- $\rho(r)$ $\rho(r > r_{\max}) = 0$
- $\phi(r)$ no limit

Goal: find $\rho = \rho(\epsilon)$ with
 $\rho = 0 \quad \text{if} \quad r > r_{\max}$



Density and potential

- $\rho(r)$ $\rho(r > r_{\max}) = 0$
- $\phi(r)$ no limit

Goal: find $\rho = \rho(\varepsilon)$ with
 $\rho = 0 \quad \text{if} \quad r > r_{\max}$

Idea new variables

relative potential

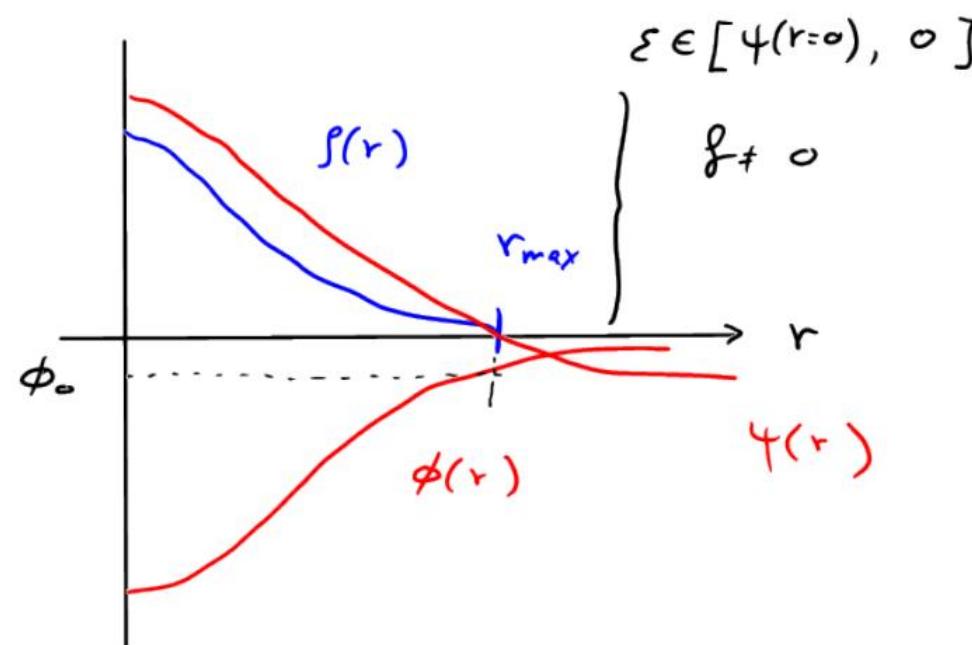
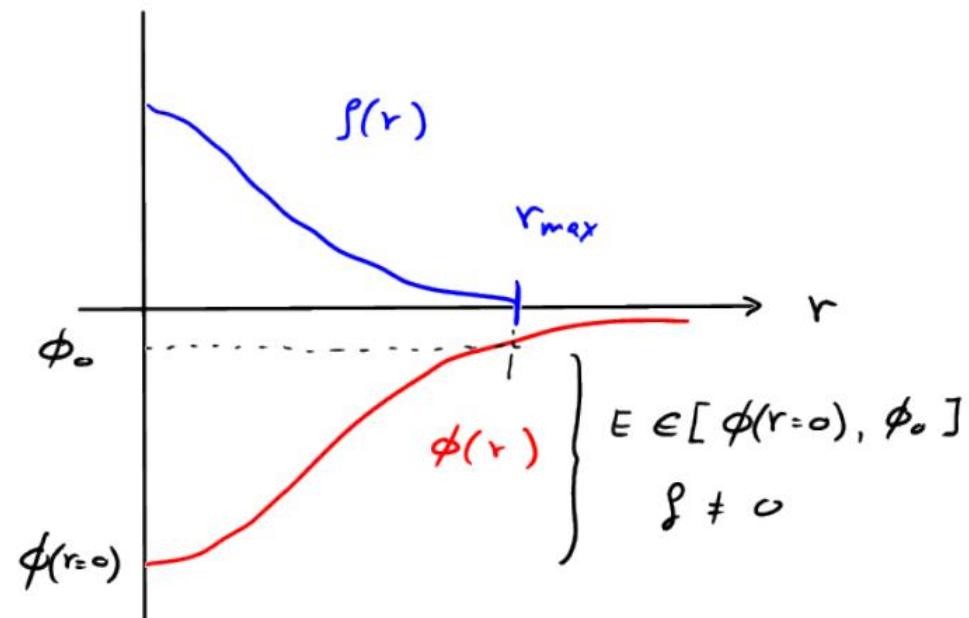
$$\begin{cases} \psi = -(\phi - \phi_0) = -\phi + \phi_0 \\ \varepsilon = -(H - \phi_0) = -H + \phi_0 \end{cases}$$

relative energy

$$= \psi - \frac{1}{2} v^2$$

$$\rho \rightarrow \rho(\varepsilon)$$

$$\begin{cases} \varepsilon > 0 \quad \rho > 0 \\ \varepsilon \leq 0 \quad \rho = 0 \end{cases}$$



Idea : Use ε as the main variable and integrate over it.

$v(r)$ becomes

$$v(r) = 4\pi \int_0^{\infty} v^2 g(H) dv = 4\pi \int_0^{\infty} v^2 g(\phi_0 - \varepsilon(r, v)) dv$$

With

$$\varepsilon = -H + \phi_0 = 4 - \frac{1}{2}v^2$$

$$v = \sqrt{2(4-\varepsilon)} \quad dv = \frac{-1}{\sqrt{2(4-\varepsilon)}} d\varepsilon$$

The integral becomes

$$v(r) = 4\pi \int_{-\infty}^{\infty} 2(4-\varepsilon) g(\phi_0 - \varepsilon) \underbrace{\frac{-1}{\sqrt{2(4-\varepsilon)}}}_{=g(\varepsilon)} d\varepsilon$$

$v \rightarrow \infty \quad \varepsilon \rightarrow -\infty$

$v=0 \rightarrow \varepsilon=4$

$= g(\varepsilon) \text{ we write } g \text{ as a function of } \varepsilon$

$$= 4\pi \int_{-\infty}^{4} \sqrt{2(4-\varepsilon)} g(\varepsilon) d\varepsilon$$

$$\begin{aligned}
 V(r) &= 4\pi \int_{-\infty}^r \sqrt{2(4-\varepsilon)} f(\varepsilon) d\varepsilon \\
 &= 4\pi \int_{-\infty}^0 \sqrt{2(4-\varepsilon)} f(\varepsilon) d\varepsilon + 4\pi \int_0^r \sqrt{2(4-\varepsilon)} f(\varepsilon) d\varepsilon \\
 &\quad \text{---} \\
 &\quad = 0 \quad \text{as} \\
 &\quad f(\varepsilon) = 0 \quad \text{for } \varepsilon < 0
 \end{aligned}$$

$$V(r) = 4\pi \int_0^r \sqrt{2(4-\varepsilon)} f(\varepsilon) d\varepsilon$$

- if ψ is a monotonic function of r (typical potential)

$$\psi(r) \rightarrow r(\psi) \Rightarrow V(r) = r(r(\psi)) = V(\psi)$$

$$\frac{1}{\sqrt{8\pi}} V(\psi) = \int_0^\psi \sqrt{4-\varepsilon} f(\varepsilon) d\varepsilon$$

Derivating

with respect to ν

$$\frac{1}{\sqrt{8\pi}} \nu(\nu) = 2 \int_0^{\nu} \sqrt{\nu - \varepsilon} g(\varepsilon) d\varepsilon$$

) not obvious

$$\frac{1}{\sqrt{8\pi}} \frac{d\nu}{d\nu} = \int_0^{\nu} d\varepsilon \frac{g(\varepsilon)}{\sqrt{\nu - \varepsilon}}$$

(Abel integral)

Solution : Eddington's formula

$$g(\varepsilon) = \frac{1}{\sqrt{8\pi^2}} \frac{d}{d\varepsilon} \left[\int_0^{\varepsilon} \frac{d\nu}{\sqrt{\varepsilon - \nu}} \right]$$

or

$$g(\varepsilon) = \frac{1}{\sqrt{8\pi^2}} \left[\int_0^{\varepsilon} \frac{d\nu}{\sqrt{\varepsilon - \nu}} \frac{d^2\nu}{d\nu^2} + \frac{1}{\sqrt{\varepsilon}} \left(\frac{d\nu}{d\nu} \right)_{\nu=0} \right]$$

Note : $g(\varepsilon) > 0$ only if $\int_0^{\varepsilon} \frac{d\nu}{\sqrt{\varepsilon - \nu}} \frac{d\nu}{d\nu}$ is an increasing function of ε

How using this formula ?

$$g(\varepsilon) = \frac{1}{\sqrt{8\pi^2}} \frac{d}{d\varepsilon} \left[\int_0^\varepsilon \frac{dv}{\sqrt{\varepsilon - v}} \right]$$

- We start from a given $\rho(r)$, $\phi(r)$

① get r_{\max} and compute $\phi_0 = \phi(r_{\max})$

② a) get $r(r) = \rho(r)/M$

$$v(r) = -\phi(r) + \phi_0$$

b) and $v = v(\psi)$ if $\psi(r)$ may be inverted

③ if $\frac{\partial v}{\partial \psi}$ is analytical, compute $g(\varepsilon)$ (Eddington's formula)

④ $g(x, v) = g(\varepsilon) = g(\phi_0 - \varepsilon) = g\left(\frac{1}{2}v^2 + \phi_0\right)$

Note ②a and ③ may be performed numerically

Example :

Hernquist model

$$\rho(r) = \frac{\rho_0}{(r/a)(1+r/a)^3}$$

$$M(r) = 2\pi \rho_0 a^3 \frac{(r/a)^2}{(1+r/a)^2}$$

$$M = 2\pi \rho_0 a^3 \quad (r=\infty)$$

$$\phi(r) = -2\pi G \rho_0 \frac{a^2}{(1+r/a)}$$

The density is non zero at $r = \infty$
 $\Rightarrow \phi_0 = 0$

$$\psi(r) = -\phi(r)$$

$$\begin{aligned} \Rightarrow \frac{r}{a} &= \frac{2\pi G \rho_0 a^2}{\psi(r)} - 1 \\ &= \frac{GM}{\psi(r)a} - 1 \end{aligned}$$

$\checkmark \quad \frac{u(r)}{r} = 2\pi \rho_0 a^3$

$$\frac{r}{a} = \frac{1}{\tilde{\psi}(r)} - 1$$

$$\text{where } \tilde{\psi}(r) = \frac{\psi(r)}{GM} a$$

we can now express v as $v(4)$ eliminating v/a

$$v(4) = \frac{p}{M} = \frac{1}{2\pi a^2} \frac{\tilde{4}^4}{1-\tilde{4}}$$

then

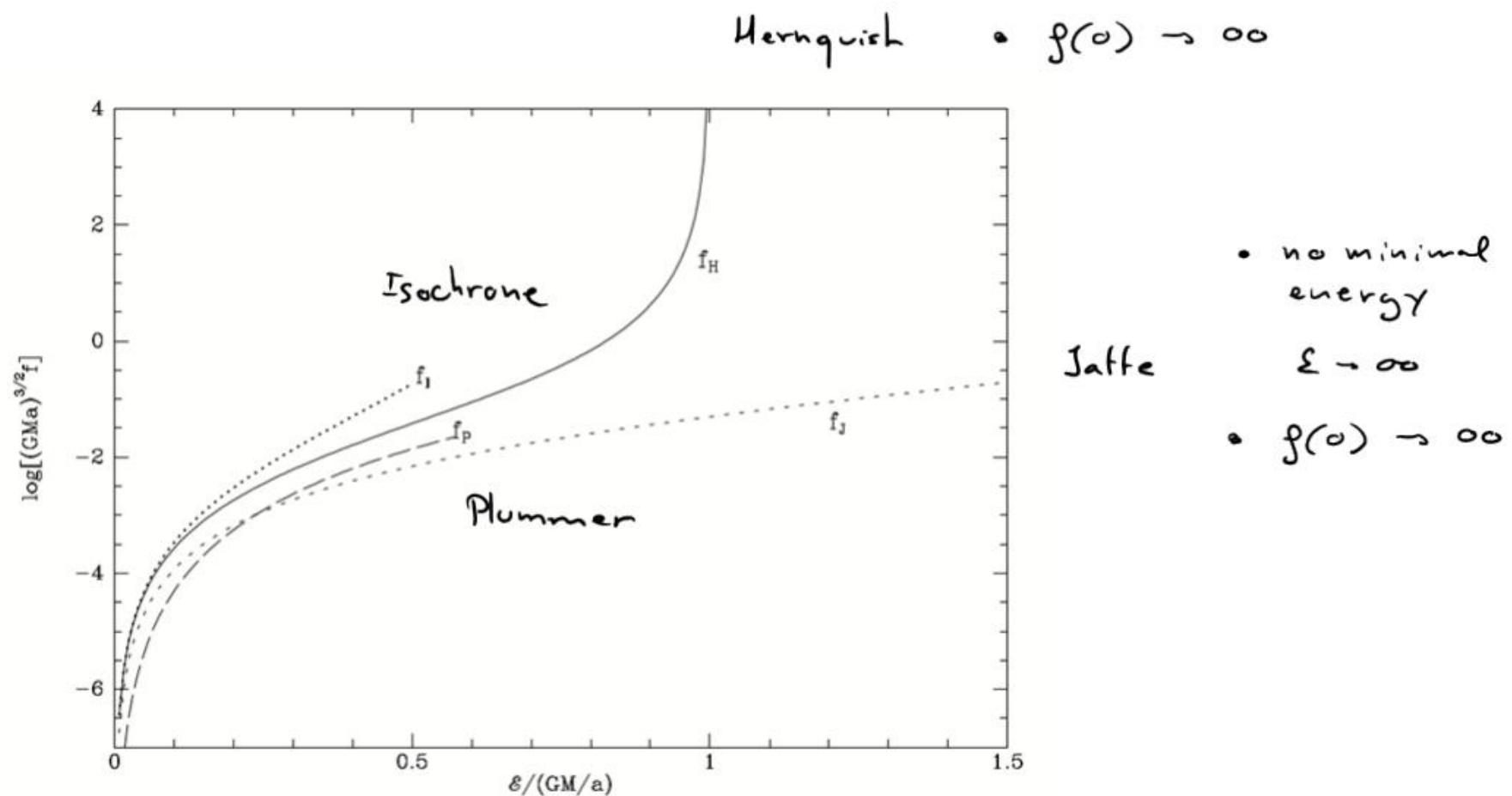
$$\frac{\partial v}{\partial 4} = \frac{1}{2\pi a^2 GM} \frac{\tilde{4}^3(4-3\tilde{4})}{(1-\tilde{4})^2}$$

And the DF becomes using $\tilde{\epsilon} = -\frac{\epsilon a}{GM}$

$$f(\epsilon) = \frac{\sqrt{2}}{(2\pi)^3 (GM)^2 a} \int_0^{\epsilon} \frac{d4}{\sqrt{\epsilon - 4}} \frac{2\tilde{4}^2(6-8\tilde{4}+3\tilde{4}^2)}{(1-\tilde{4})^3}$$

$$= \frac{1}{\sqrt{2} (2\pi)^3 (GMa)^{3/2}} \frac{\sqrt{\tilde{\epsilon}}}{(1-\tilde{\epsilon})^2} \left[(1-2\tilde{\epsilon})(8\tilde{\epsilon}^2 - 8\tilde{\epsilon} - 3) + \frac{3 \arcsin(\sqrt{\tilde{\epsilon}})}{\sqrt{\tilde{\epsilon}(1-\tilde{\epsilon})}} \right]$$

Note: It is possible to do the same for the Plummer, Isochrone and Jaffe models



Plummer model

$$\Phi(r) = -\frac{GM}{\sqrt{r^2 + b^2}}$$

$$\rho(r) = \frac{3M}{4\pi b^3} \left(1 + \frac{r^2}{b^2}\right)^{-5/2}$$

Isochrone model

$$\Phi(r) = -\frac{GM}{b + \sqrt{r^2 + b^2}}$$

$$\rho(r) = M \frac{3(b + \sqrt{b^2 + r^2})(b^2 + r^2) - r^2(b + 3\sqrt{b^2 + r^2})}{4\pi(b + \sqrt{b^2 + r^2})^3(b^2 + r^2)^{3/2}}$$

Jaffe model

$$\Phi(r) = -4\pi G \rho_0 a^2 \ln(1 + a/r)$$

$$\rho(r) = \frac{\rho_0}{(r/a)^2(1 + r/a)^2}$$

Hernquist model

$$\Phi(r) = -4\pi G \rho_0 a^2 \frac{1}{2(1 + r/a)}$$

$$\rho(r) = \frac{\rho_0}{(r/a)(1 + r/a)^3}$$

Equilibria of collisionless systems

Models defined from DFs

Distribution function for spherical systems

- Method ①

- from $\rho(r)$ $\phi(r)$ \rightarrow set $f(\varepsilon) = \rho\left(\frac{1}{2}v^2 + \phi(r)\right)$

- Method ②

- assume $f(\varepsilon)$ \rightarrow get $\rho(r)$

Spherical systems defined by DFs

Density

should be $N \cdot m \cdot g$

spherical integration
in velocity space

$$g(r) = \int d^3\vec{v} \, g(4(r) - \frac{1}{2}v^2) = 4\pi \int_0^\infty dv \, v^2 \, g(4(r) - \frac{1}{2}v^2)$$

Conditions for $g > 0$: $\epsilon > 0$ as $\epsilon = 4 - \frac{1}{2}v^2 > 0$

$$\sqrt{24} > v$$

$$g(r) = 4\pi \int_0^\infty dv \, v^2 \, g(4(r) - \frac{1}{2}v^2)$$

$$= 4\pi \int_0^{\sqrt{24}} dv \, v^2 \, g(4(r) - \frac{1}{2}v^2) + 4\pi \int_{\sqrt{24}}^\infty dv \, v^2 \, g(4(r) - \frac{1}{2}v^2)$$

$$= 0 \text{ as } v > \sqrt{24}$$

$$\Rightarrow g = 0$$

$$g(r) = 4\pi \int_0^{\sqrt{24}} dv \, v^2 \, g(4(r) - \frac{1}{2}v^2)$$

note
we don't
integrate over
the energy

Equilibria of collisionless systems

**Models defined from DFs:
Polytropes**

Polytropes and Plummer models

$$g(\varepsilon) = \begin{cases} F \varepsilon^{n-3/2} & (\varepsilon > 0) \\ 0 & (\varepsilon \leq 0) \end{cases}$$

F , a constant

$$g = 0 \text{ if } \varepsilon > 0$$

$$g = 0$$

Corresponding density

$$\rho(r) = 4\pi F \int_0^{\sqrt{24}} dv v^2 \left(4(r) - \frac{1}{2} v^2 \right)^{n-3/2}$$

smart substitution

: introduce the variable $\theta(v)$ such that

$$v^2 = 24 \cos^2 \theta \quad , \quad \theta = \arccos\left(\frac{v}{\sqrt{24}}\right)$$

$$2v dv = -44 \cos \theta \sin \theta d\theta$$

$$\Rightarrow dv = -\frac{24 \cos \theta \sin \theta d\theta}{\sqrt{24} \cos \theta} = -\sqrt{24} \sin \theta d\theta$$

$$\begin{cases} v=0 \rightarrow \theta = \frac{\pi}{2} \\ v=\sqrt{24} \rightarrow \theta = 0 \end{cases} \rightarrow$$

$$\psi - \frac{1}{2}v^2 = 4 - 4 \cos^2 \theta = 4 \sin^2 \theta$$

$$\begin{aligned} \rho(r) &= 4\pi F \int_0^{\pi/2} (\sqrt{24} \sin \theta d\theta) \cdot (24 \cos^2 \theta) \cdot (4 \sin^2 \theta)^{n-\frac{3}{2}} \\ &= 4\pi F \int_0^{\pi/2} 2 \cdot 2^{\frac{1}{2}} 4^{\frac{1}{2}} 4^{\frac{n}{2}} 4^{n-\frac{3}{2}} \cdot \cos^2 \theta \sin \theta^{2n-2} d\theta \\ &= 8\pi F \sqrt{2} 4^n \int_0^{\frac{\pi}{2}} \underbrace{\cos^2 \theta \sin \theta^{2n-2}}_{r \sin^2 \theta} d\theta \end{aligned}$$

So, we get

$$\boxed{\rho(r) = C_n r(r) ^n} \quad (\text{for } r > 0)$$

relation between ρ and ϕ

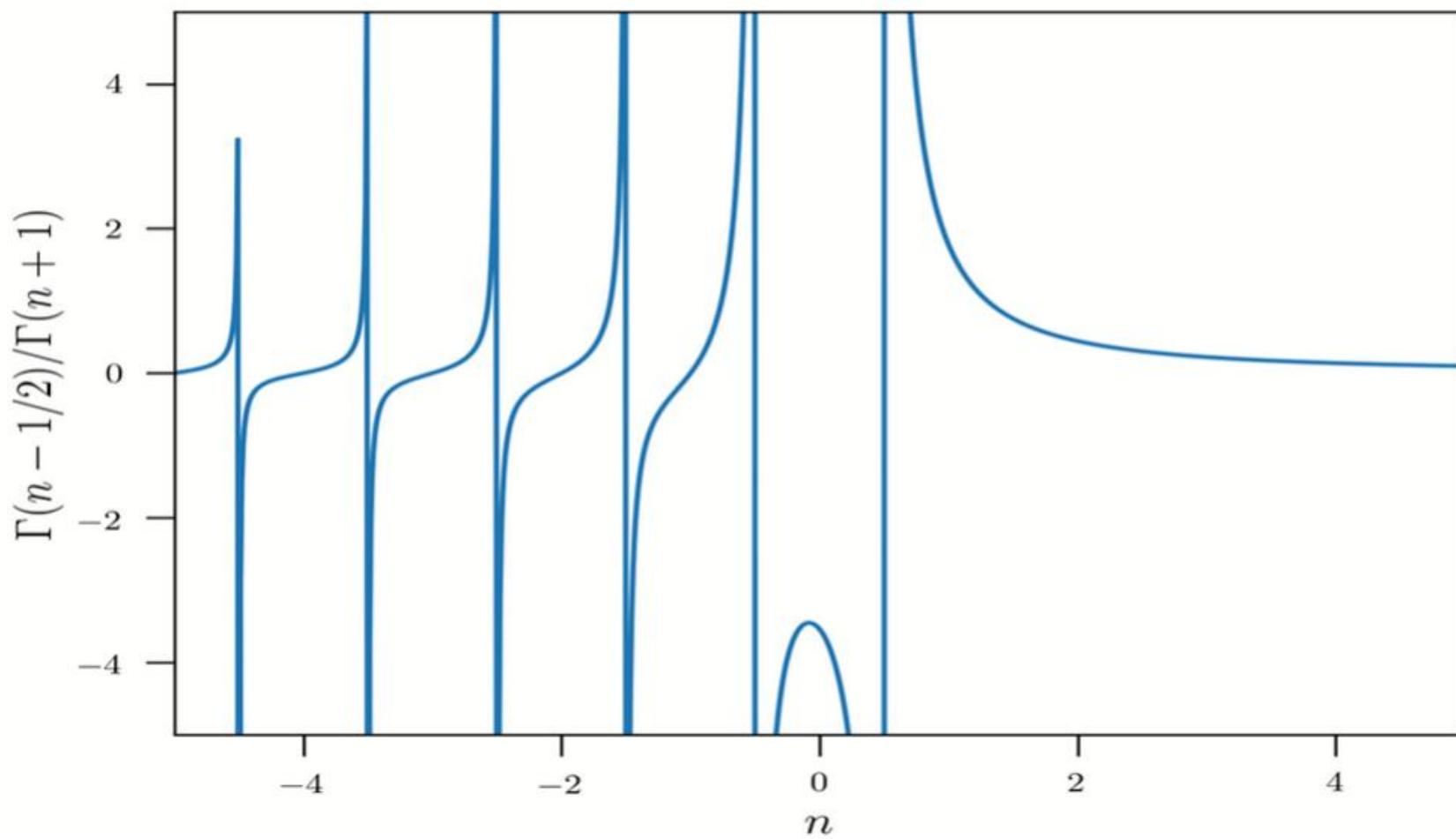
$$C_n = \frac{(2\pi)^{3/2} (n-\frac{3}{2})! F}{n!} = \frac{(2\pi)^{3/2} \Gamma(n-\frac{1}{2}) F}{\Gamma(n+1)}$$

$$n! = \Gamma(n+1) = \int_0^\infty dt t^n e^{-t}$$

$$c_n \sim \frac{(n - \frac{1}{2})!}{n!} = \frac{\Gamma(n - \frac{1}{2})}{\Gamma(n+1)}$$

$$n = \frac{1}{2}$$

$n > \frac{1}{2}, c_n > 0, f > 0$



"Pressure"

$$P(\rho) = - \int_0^\rho d\rho' \rho' \frac{\partial \phi}{\partial \rho}(\rho')$$

$$\rho = C_n \gamma^n$$

$$\gamma = \frac{1}{C_n^{\frac{1}{n}}} \rho^{\frac{1}{n}}$$

$$\frac{\partial \gamma}{\partial \rho} = \frac{1}{C_n^{\frac{1}{n}}} \frac{1}{n} \rho^{\frac{1}{n}-1}$$

$$\frac{\partial \phi}{\partial \rho} = - \frac{1}{C_n^{\frac{1}{n}}} \frac{1}{n} \rho^{\frac{1}{n}-1}$$

$$P(\rho) = \frac{1}{C_n^{\frac{1}{n}}} \frac{1}{n} \int_0^\rho d\rho' \rho'^{\frac{1}{n}} = \frac{1}{C_n^{\frac{1}{n}}} \frac{1}{n+1} \rho^{\frac{1}{n}+1}$$

$$P(\rho) = K \rho^\gamma$$

\equiv Polytropic EoS

$$\left\{ \begin{array}{l} \gamma = \frac{1}{n} + 1 \\ K = \frac{1}{C_n^{\frac{1}{n}}} \frac{1}{n+1} \end{array} \right. \quad \begin{array}{l} n = \frac{1}{\gamma-1} \\ C_n = \left(\frac{n-1}{K \gamma} \right)^{\frac{1}{n-1}} \end{array}$$

Conclusion

The density of a stellar system described by an ergodic DF

$$f(\epsilon) \sim \epsilon^{n-3/2}$$

Is the same as a polytropic gas sphere in hydrostatic equilibrium,
with:

$$P(\rho) \sim \rho^\gamma$$

This is why these DFs are called polytropes.

Note : from $\rho(r) = C_n \psi(r)^n$

if $\rho = \text{cte}$ $\Rightarrow n = 0$

But from $C_n = \frac{(2\pi)^{3/2} T(n-\frac{1}{2}) F}{\Gamma(n+1)}$ $\Rightarrow C_n < 0 \quad \rho < 0$ 

① No finite ergodic stellar system
is homogeneous.

② No self-gravitating homogeneous system
equivalent to a self-gravitating sphere
of incompressible fluid exists.

Indeed : the hydrostatic solution of an incompressible fluid
of constant density requires $\frac{dP}{dr} = -\rho_0 \frac{d\phi}{dr} = -\frac{4}{3}\pi G \rho_0^2 r$

not a polytropic EOS $\leftarrow \rho = \rho_0 - \frac{2}{3}\pi G \rho_0^2 r^2$

Self-gravity !

$$\vec{\nabla}^2(\Phi) = 4\pi G\rho$$

The Poisson equation for spherical systems (with 4)

$$\frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{d\psi}{dr} \right) = -4\pi G \rho(r)$$

$$\rho = C_n r^n$$

$$\rho^{\frac{n+1}{n}} = C_n^{\frac{n-1}{n}} r^{\frac{n+1}{n}}$$

With $\rho = C_n r^n$ $\frac{d\rho}{dr} = C_n n r^{n-1} \frac{d\psi}{dr} = C_n n \left(\frac{1}{C_n} \rho \right)^{\frac{n-1}{n}} \frac{d\psi}{dr}$

thus $\frac{d\psi}{dr} = \frac{1}{C_n^{\frac{1}{n}}} \int \rho^{\frac{n-1}{n}} \frac{d\rho}{dr}$

$$\frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{1}{n C_n^{\frac{1}{n}}} \int \rho^{\frac{n-1}{n}} \right) + 4\pi G \rho = 0$$

or eliminating ρ , using $\rho(r) = C_n \psi(r)^n$.

$$\frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{d\psi}{dr} \right) + 4\pi G C_n \psi^n = 0$$

Solutions

A. Power laws

$$\frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{d\psi}{dr} \right) + 4\pi G c_n \psi^n = 0$$

$$\left\{ \begin{array}{l} \rho(r) \sim r^{-2} \\ \psi(r) \sim r^{-\frac{2}{n}} \end{array} \right. \quad \Rightarrow \quad \rho \sim \psi^n$$

$$\frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{d\psi}{dr} \right) \sim r^{-\frac{2}{n}-2}$$

Poisson

$$\underbrace{\frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{d\psi}{dr} \right)}_{r^{-\frac{2}{n}-2}} + \underbrace{4\pi G \rho(r)}_{r^{-2}} = 0$$

$$-\frac{2}{n}-2 \sim -2$$

\Rightarrow

$$\frac{2}{n} \leq 1 \Rightarrow n \geq 3$$

As the potential may not decrease faster

than the Kepler potential $\frac{1}{r}$

$$(\psi \sim r^{-\frac{2}{n}})$$

$$\frac{2}{n} \leq 1 \Rightarrow n \geq 3$$

B Models with finite potential and density

Define new variables

$$s = \frac{r}{b} \quad \psi' = \frac{\psi}{\psi_0}$$

where

$$\left\{ \begin{array}{l} b = \left(\frac{4}{3} \pi G \psi_0^{n-2} c_n \right)^{1/2} \\ \psi_0 = \psi(0) \end{array} \right.$$

The Poisson equation becomes

$$\frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{d\psi}{dr} \right) + 4\pi G c_n \psi^n = 0$$

$$\frac{1}{s^2} \frac{d}{ds} \left(s^2 \frac{d\psi'}{ds} \right) = -3\psi'^n$$

+ boundary conditions

$$\left\{ \begin{array}{ll} \cdot \psi'(0) = 1 & \text{normalisation} \\ \cdot \left. \frac{d\psi'}{dr} \right|_0 = 0 & \text{no force at the center} \\ & (\text{smooth}) \end{array} \right.$$

Lane-Emden Equation

(In general, non-trivial solutions)

Two analytical solutions

$n=1, n=5$

$$n = 1$$

$$\frac{1}{s^2} \frac{d}{ds} \left(s^2 \frac{d\psi'}{ds} \right) = -3\psi'$$

linear Helmholtz Equation

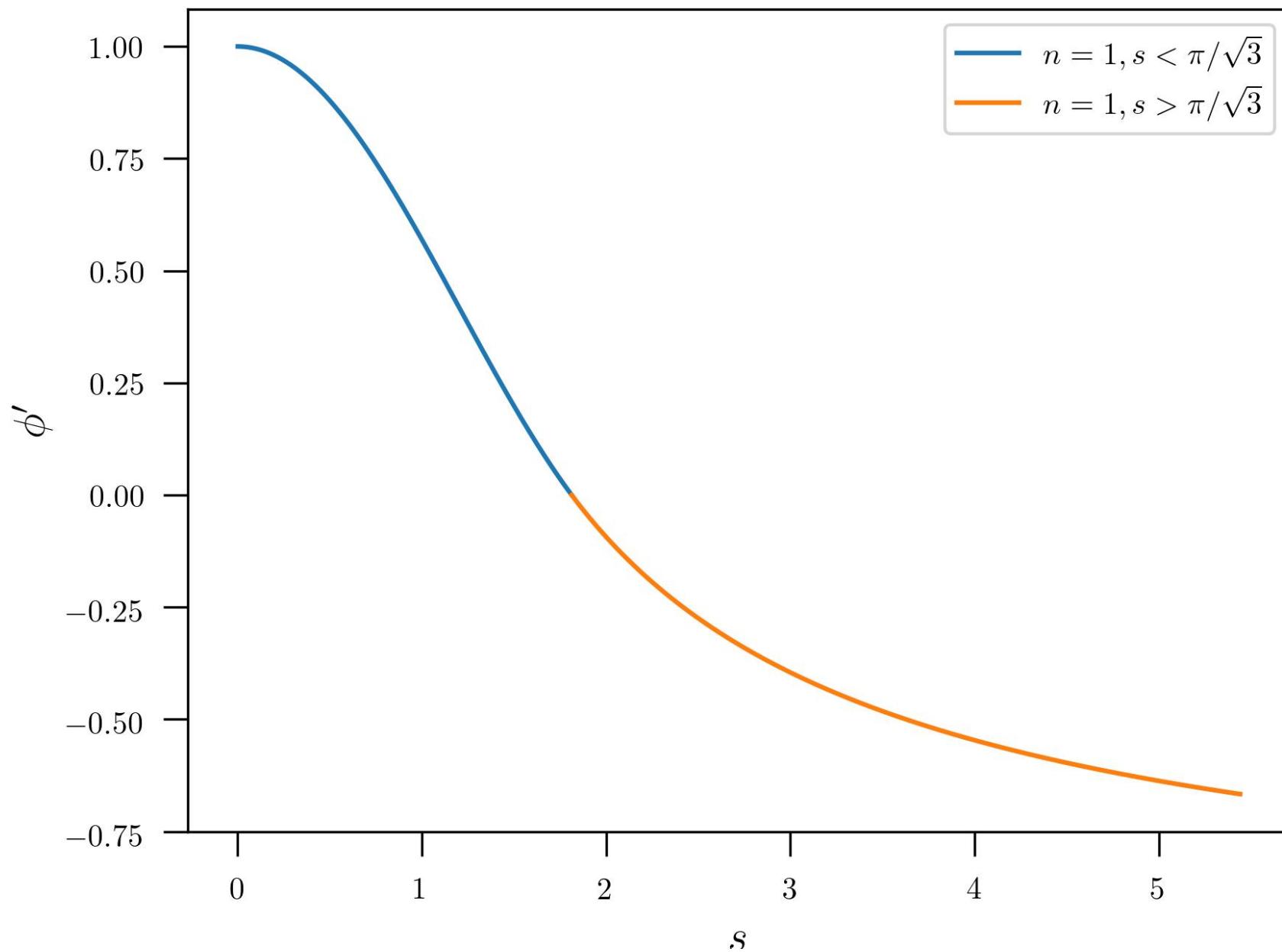
$$\psi'(s) = \begin{cases} \frac{\sin(\sqrt{3}s)}{\sqrt{3}s} & s < \frac{\pi}{\sqrt{3}} \\ \frac{\pi}{\sqrt{3}s} - 1 & s \geq \frac{\pi}{\sqrt{3}} \end{cases}$$



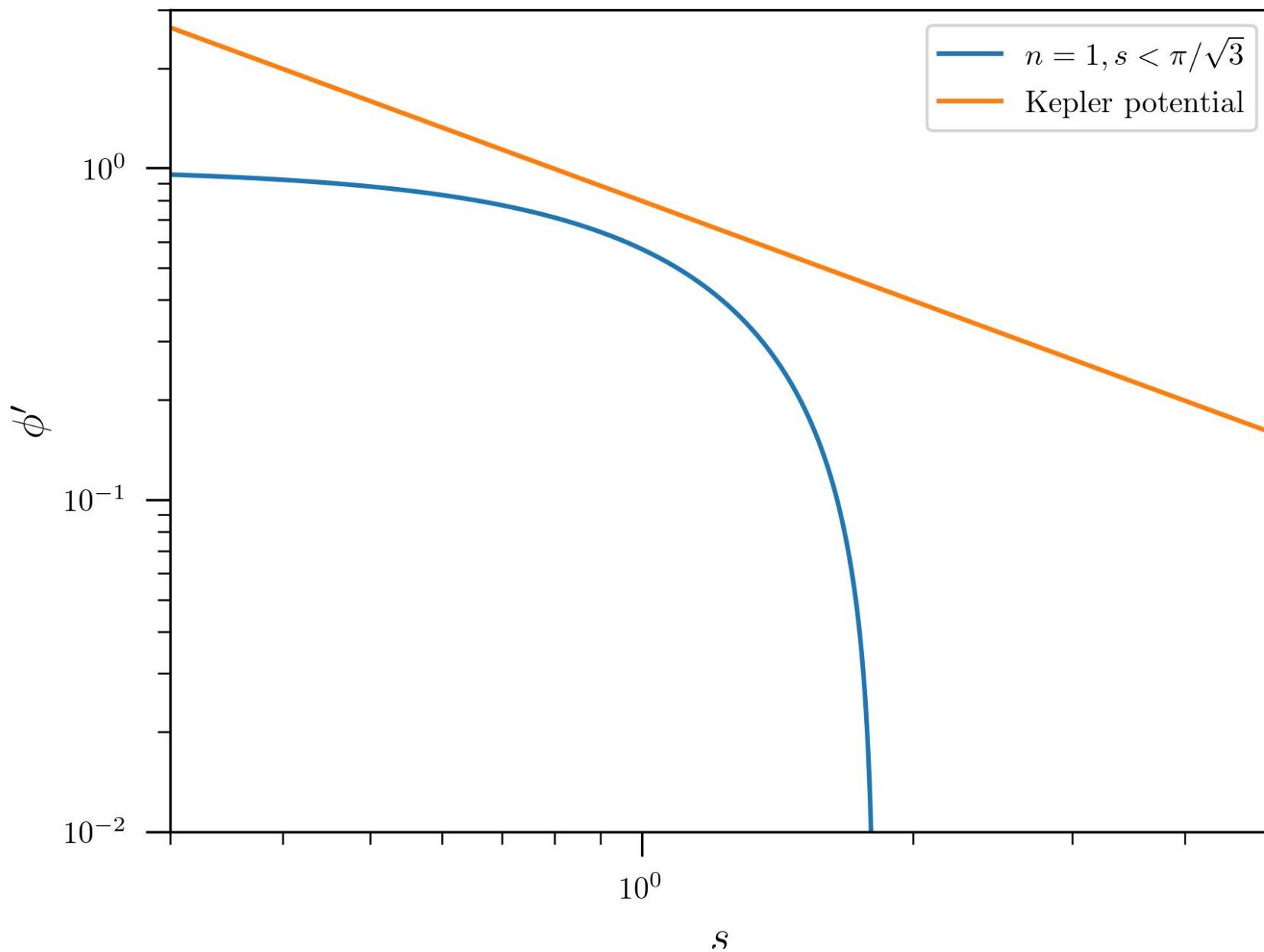
$$n = 1 < 3$$

non physical solution

Solution of the Lane-Emden Equation for n=1



Solution of the Lane-Emden Equation for n=1



$$n = 5$$

$$\frac{1}{s^2} \frac{d}{ds} \left(s^2 \frac{d\psi'}{ds} \right) = -3\psi'^5$$

consider $\psi'(s) = \frac{1}{\sqrt{1+s^2}}$

The Poisson Equation becomes

$$\frac{1}{s^2} \frac{d}{ds} \left(s^2 \frac{d\psi'}{ds} \right) = -\frac{1}{s^2} \frac{d}{ds} \left(\frac{s^3}{(1+s^2)^{3/2}} \right) = -\frac{s}{(1+s^2)^{5/2}} = -3\psi'^5$$

$\rightarrow \psi'(s)$ is a solution!

$$n = 5$$

$$\frac{1}{s^2} \frac{d}{ds} \left(s^2 \frac{d\psi'}{ds} \right) = -3\psi'^5$$

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→ $\psi'(s)$ is a solution!

and corresponds to the Plummer model

$$\phi(r) = -\frac{GM}{\sqrt{r^2+a^2}}$$

$$\rho(r) = \frac{3M}{4\pi a^3} \left(1 + \frac{r^2}{a^2} \right)^{-5/2}$$

Then : what do we learn concerning the Plummer model ?

We have access to its DF :

$$g(\varepsilon) \sim \varepsilon^{n-3/2} \sim \left(\frac{GM}{\sqrt{r^2+a^2}} + \frac{1}{2} v^2 \right)^{-1/2}$$

We have access to the kinematics structure :

① Velocity distribution function

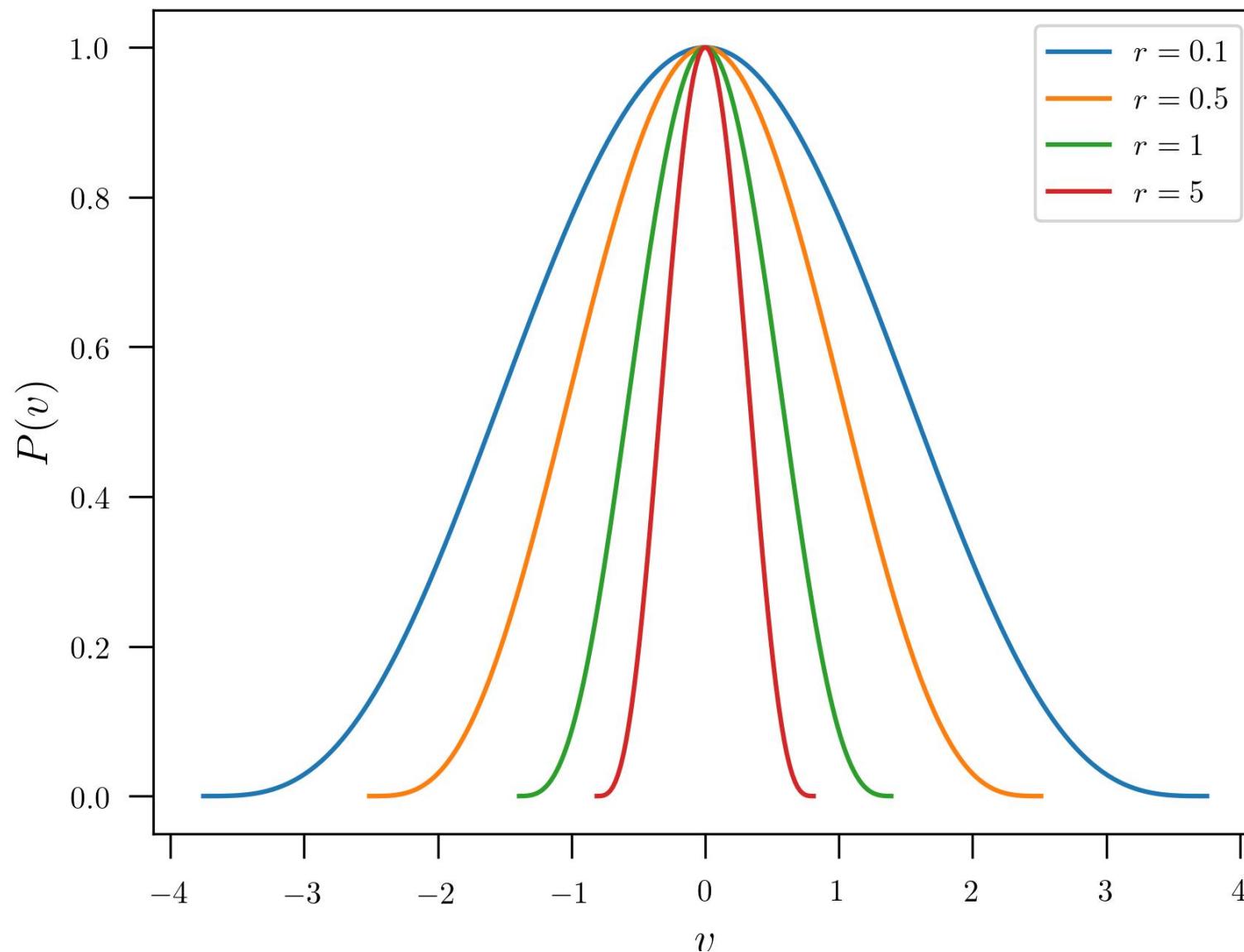
$$P_r(v) = \frac{g(\frac{1}{2}v^2 + \phi(r))}{\gamma(r)} \sim \underbrace{\left(1 + \frac{r^2}{a^2}\right)^{5/2}}_{\frac{1}{\gamma}} \underbrace{\left(\frac{GM}{\sqrt{r^2+a^2}} + \frac{1}{2}v^2\right)^{-1/2}}_{\varepsilon^{-1/2}}$$

② Velocity dispersion

$$v_{\max} = \sqrt{24}$$

$$\begin{aligned} \sigma^2 &= \frac{4}{3} \pi \frac{1}{\gamma(r)} \int_0^{v_{\max}} v^4 g\left(\frac{1}{2}v^2 + \phi(r)\right) dv \\ &= \frac{4}{3} \pi \frac{1}{\gamma(r)} \int_0^{v_{\max}} v^4 \left(\frac{1}{2}v^2 - \frac{GM}{\sqrt{r^2+a^2}} \right)^{-1/2} dv \end{aligned}$$

The Plummer velocity distribution function



The End