

Stability of collisionless systems

2nd part

Outlines

Linear response theory

- in fluid systems
- in stellar systems

The Jeans instability

- in fluid systems
- in stellar systems

Entropy of a collisionless system of N particles

By analogy: $\rho \rightarrow \rho(\vec{q}, \vec{p})$

$$S := -N \int d\vec{q} d\vec{p} \rho(\vec{q}, \vec{p}) \ln(\rho(\vec{q}, \vec{p}))$$

ρ : DF

Can we maximize S for a system of a given mass M and energy E ?

Yes: The solution is the isothermal sphere!

But! The isothermal sphere is unphysical

$$\left\{ \begin{array}{l} M = \infty \\ E = \infty \end{array} \right.$$



Where is the problem?

Corollary : No DF with finite mass M and finite energy E maximizes S

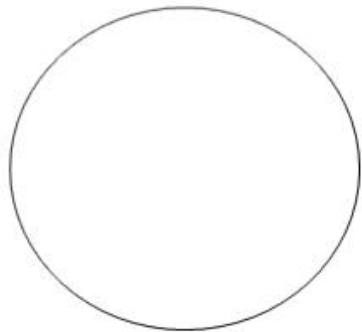
Demonstration

Spherical system

} mass M
total energy E

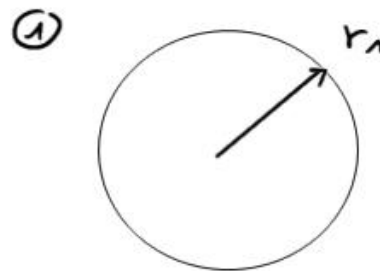
Idea: split the system into

- ① inner part
- ② outer part



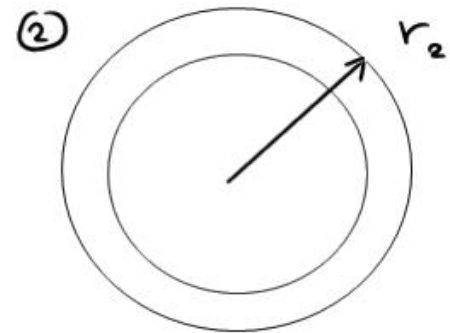
M

=



M_1

+



$M_2 \ll M$

Virial Equation

$$2K + W = 0$$

$$E = K + W = \frac{W}{2}$$

$$E_1 = \frac{W}{2} \approx -\frac{GM_1^2}{2r_1}$$

⚡
virial

$$E_2 \approx -\frac{GM_1 M_2}{2r_2}$$

↙ the pot. is dominated by M_1

If we shrink ①

$$r_1 \rightarrow (1 - \epsilon) r_1 \quad (\epsilon > 0 \text{ but } \ll 1)$$

$$E_1 \rightarrow -\frac{GM_1^2}{2r_1(1-\epsilon)}$$

$$\Delta E = E_1 - E_1' \approx \epsilon \frac{GM_1^2}{r_1} \quad (> 0 \text{ excess of grav. energy})$$

This excess of energy is deposited into ② which will extend $r_2' > r_2$

$$E_2' = E_2 + \Delta E = -\frac{GM_1 M_2}{r_2'}$$

$$\frac{1}{r_2'} \sim E_2 + \Delta E$$

At the virial equilibrium,
the envelope velocity will be

$$\sigma_2'^2 \sim \frac{GM_1}{r_2'}$$

The points in ② will cover a region of the phase space with a volume of about :

$$V_{\text{①}} = \sigma_2'^3 \cdot r_2'^3 \approx \left(\frac{GM_1}{r_2'} \right)^{3/2} \cdot r_2'^3 = (GM_1 r_2')^{3/2}$$

as $f_{\text{②}} \sim \frac{1}{V_{\text{①}}} \Rightarrow f_{\text{②}} \sim r_2'^{-3/2}$

Entropy of ② $S_{\text{②}} = -N_2 \int \underbrace{d^3r d^3v f_{\text{②}} \ln(f_{\text{②}})}_{\approx 1}$ $\frac{-GM_1 M_2}{2r_2}$ $\epsilon \frac{GM_1^2}{r_1}$

$$= -N_2 \frac{3}{2} \ln\left(\frac{1}{r_2'}\right) = -N_2 \frac{3}{2} \ln\left(\bar{E}_2 + \Delta E\right)$$

if $\Delta E = |\bar{E}_2|$

i.e. $\epsilon = \frac{1}{2} \frac{M_2}{M_1} \frac{r_1}{r_2} \Rightarrow S_{\text{②}} \rightarrow \infty$!!! $S_{\text{①}} + S_{\text{②}} \rightarrow \infty$

We can always collapse a portion of a system and release gravitational energy to the outer part (diffuse envelope) in such a way that the entropy increase (no bounds)

Conclusions

Stellar systems may increase their entropy, but never reach a maximum, as this maximum does not exist.

Finite stellar systems cannot reach a thermodynamical equilibrium.

Moreover

- The entropy is defined locally, while the gravity is a long-range force
- When defining the entropy, we consider the conservation of energy but not angular momentum

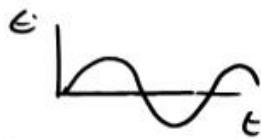
Our goal Study the stability of systems
at equilibrium

Method : perturbation theory

perturbation \rightarrow response

Types of responses

- Exponential growth of the perturbation
- Oscillation of the perturbation
- Die of the perturbation



Stability of collisionless systems

Linear response theory

Linear response theory

Study the perturbation of system at the equilibrium

Perturbation: external gravitational field $-\varepsilon \vec{\nabla} \phi_e$: $|\vec{\nabla} \phi_e| \sim |\vec{\nabla} \phi_0|$

Linear response theory

Study the perturbation of system at the equilibrium

Perturbation: external gravitational field $-\varepsilon \vec{\nabla} \phi_e$: $|\vec{\nabla} \phi_e| \sim |\vec{\nabla} \phi_0|$

stellar/system
at equilibrium



$$\rho_{S_0}(x)$$

$$\phi_{S_0}(x)$$

$$\nabla^2 \phi_{S_0} = 4\pi G \rho_{S_0}$$

Linear response theory

Study the perturbation of system at the equilibrium

Perturbation: external gravitational field $-\varepsilon \vec{\nabla} \phi_e$: $|\vec{\nabla} \phi_e| \sim |\vec{\nabla} \phi_0|$

stellar/system
at equilibrium

external
perturbation



+



$$\rho_{S_0}(x)$$

$$\varepsilon \rho_e(x)$$

$$\phi_{S_0}(x)$$

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$$\nabla^2 \phi_{S_0} = 4\pi G \rho_{S_0}$$

$$\nabla^2 \phi_e = 4\pi G \rho_e$$

Linear response theory

Study the perturbation of system at the equilibrium

Perturbation: external gravitational field $-\epsilon \vec{\nabla} \phi_e$: $|\vec{\nabla} \phi_e| \sim |\vec{\nabla} \phi_0|$

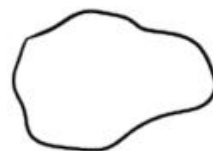
stellar/system
at equilibrium

external
perturbation

stellar/fluid
responses
linearly



+



$$\rho_{s_0}(x)$$

$$\epsilon \rho_e(x)$$

$$\rho_s = \rho_{s_0} + \epsilon \rho_{s_1}$$

$$\phi_{s_0}(x)$$

$$\epsilon \phi_e(x)$$

$$\phi_s = \phi_{s_0} + \epsilon \phi_{s_1}$$

$$\nabla^2 \phi_{s_0} = 4\pi G \rho_{s_0}$$

$$\nabla^2 \phi_e = 4\pi G \rho_e$$

$$\nabla^2 \phi_s = 4\pi G \rho_s$$

$$\nabla^2 \phi_{s_1} = 4\pi G \rho_{s_1}$$

Linear response theory

Study the perturbation of system at the equilibrium

Perturbation: external gravitational field $-\epsilon \vec{\nabla} \phi_e$: $|\vec{\nabla} \phi_e| \sim |\vec{\nabla} \phi_0|$

stellar/system
at equilibrium

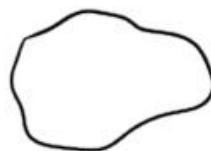
external
perturbation

stellar/fluid
responses
linearly

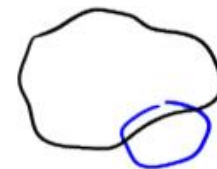
total stellar/fluid
linear response



+



→



$$\rho_{s_0}(x)$$

$$\epsilon \rho_e(x)$$

$$\rho_s = \rho_{s_0} + \epsilon \rho_{s_1}$$

$$\begin{aligned} \rho_{tot} &= \rho_{s_0} + \epsilon \rho_{s_1} + \epsilon \rho_e \\ &= \rho_{s_0} + \epsilon \rho_1 \end{aligned}$$

$$\phi_{s_0}(x)$$

$$\epsilon \phi_e(x)$$

$$\phi_s = \phi_{s_0} + \epsilon \phi_{s_1}$$

$$\begin{aligned} \phi_{tot} &= \phi_{s_0} + \epsilon \phi_{s_1} + \epsilon \phi_e \\ &= \phi_{s_0} + \epsilon \phi_1 \end{aligned}$$

$$\nabla^2 \phi_{s_0} = 4\pi G \rho_{s_0}$$

$$\nabla^2 \phi_e = 4\pi G \rho_e$$

$$\nabla^2 \phi_s = 4\pi G \rho_s$$

$$\nabla^2 \phi_{s_1} = 4\pi G \rho_{s_1}$$

$$\nabla^2 \phi_1 = 4\pi G \rho_1$$

$$\nabla^2 \phi_{tot} = 4\pi G \rho_{tot}$$

Linear response theory

Study the perturbation of system at the equilibrium

Perturbation: external gravitational field $-\epsilon \vec{\nabla} \phi_e$: $|\vec{\nabla} \phi_e| \sim |\vec{\nabla} \phi_0|$

stellar/system
at equilibrium



$$\rho_{s_0}(x)$$

$$\phi_{s_0}(x)$$

$$\nabla^2 \phi_{s_0} = 4\pi G \rho_{s_0}$$

external
perturbation

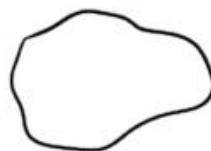


$$\epsilon \rho_e(x)$$

$$\epsilon \phi_e(x)$$

$$\nabla^2 \phi_e = 4\pi G \rho_e$$

stellar/fluid
responses
linearly



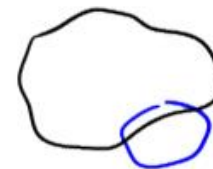
$$\rho_s = \rho_{s_0} + \epsilon \rho_{s_1}$$

$$\phi_s = \phi_{s_0} + \epsilon \phi_{s_1}$$

$$\nabla^2 \phi_s = 4\pi G \rho_s$$

$$\nabla^2 \phi_{s_1} = 4\pi G \rho_{s_1}$$

total stellar/fluid
linear response



$$\begin{aligned} \rho_{tot} &= \rho_{s_0} + \epsilon \rho_{s_1} + \epsilon \rho_e \\ &= \rho_{s_0} + \epsilon \rho_1 \end{aligned}$$

$$\begin{aligned} \phi_{tot} &= \phi_{s_0} + \epsilon \phi_{s_1} + \epsilon \phi_e \\ &= \phi_{s_0} + \epsilon \phi_1 \end{aligned}$$

$$\nabla^2 \phi_1 = 4\pi G \rho_1$$

$$\nabla^2 \phi_{tot} = 4\pi G \rho_{tot}$$

Conventions : $\rho_{s_0} = \rho_0$ $\phi_{s_0} = \phi_0$ $\rho_{tot} = \rho$ $\phi_{tot} = \phi$

Linearized equations for a self-gravitating system

Self-gravitating fluid

$\rho(\vec{x}, t)$ $\phi(\vec{x}, t)$ $p(\vec{x}, t)$ $\vec{v}(\vec{x}, t)$

6 Equ.
6 Unkn.

① Continuity Equation

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{v}) = 0$$

② Euler Equation

$$\frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \vec{\nabla}) \vec{v} = - \frac{\vec{\nabla} p}{\rho} - \vec{\nabla} \phi$$

③ The Poisson Equation

$$\nabla^2 \phi = 4\pi G \rho$$

④ Equation of state (barotropic)

$$p(\vec{x}, t) = p(\rho(\vec{x}, t))$$

Self-gravitating stellar system

$f(\vec{x}, \vec{v}, t)$, $\rho(\vec{x}, t)$, $\phi(\vec{x}, t)$

3 Equ.
3 Unkn.

① The collisionless Boltzmann Equation

$$\frac{\partial f}{\partial t} + \vec{v} \cdot \frac{\partial f}{\partial \vec{x}} - \frac{\partial \phi}{\partial \vec{x}} \cdot \frac{\partial f}{\partial \vec{v}} = 0$$

$$= \frac{\partial f}{\partial t} + [f, \mathcal{H}] = 0$$

② The Poisson Equation

$$\nabla^2 \phi = 4\pi G \rho = 4\pi G \int d^3v f(\vec{x}, \vec{v}, t)$$

Linearizing equations

Goal: describe the response of the system (without the perturbation)

$$f_s(\tilde{x}, t) = f_{s0}(\tilde{x}) + \varepsilon f_{s1}(\tilde{x}, t) \quad \phi_s \quad \tilde{v}_s \quad p_s \quad f_s$$

- ① Equations for $f_s(\tilde{x}, t)$
- ② Equations for $f_{s0}(\tilde{x})$ (system at equilibrium)
- ③ Keep only first order terms ($\varepsilon^2 \rightarrow 0$)

linear differential equations for f_{s1} $\phi_{s1} \quad \tilde{v}_{s1} \quad p_{s1} \quad f_{s1}$

Linearized Equations for a self-gravitating fluid

Equations for a self-gravitating fluid (we follow only the system, without the perturbation)

System of density $\rho_s(\vec{x}, t)$ $\phi_s(\vec{x}, t)$ $\vec{v}_s(\vec{x}, t)$ $p_s(\vec{x}, t)$

① Continuity Equation

$$\frac{\partial \rho_s}{\partial t} + \vec{\nabla} \cdot (\rho_s \vec{v}_s) = 0$$

total potential $\phi = \phi_s + \epsilon \phi_e$

② Euler Equation

$$\frac{\partial \vec{v}_s}{\partial t} + (\vec{v}_s \cdot \vec{\nabla}) \vec{v}_s = - \frac{\vec{\nabla} p_s}{\rho_s} - \vec{\nabla} \phi$$

③ The Poisson Equation

$$\nabla^2 \phi_s = 4\pi G \rho_s$$

④ Equation of state

$$p_s = P(\rho_s)$$

Definition :

specific enthalpy

$$h(p_s) = \int_0^{p_s} \frac{1}{\rho'} \frac{\partial p_s}{\partial \rho_s}(\rho') d\rho'$$

for a barotropic
EOS $P = P(\rho)$

$$\vec{\nabla} h_s = \frac{1}{\rho_s} \vec{\nabla} p_s$$

Euler equation
becomes

$$\frac{\partial \vec{v}_s}{\partial t} + (\vec{v}_s \cdot \vec{\nabla}) \vec{v}_s = - \frac{\vec{\nabla} p_s}{\rho_s} - \vec{\nabla} \phi$$

$$\frac{\partial \vec{v}_s}{\partial t} + (\vec{v}_s \cdot \vec{\nabla}) \vec{v}_s = - \vec{\nabla} (h_s + \phi)$$

Definition :

sound speed

$$v_s^2 = \left. \frac{\partial P(\rho)}{\partial \rho} \right|_{\rho_0}$$

for the
unperturbed
system



More on enthalpy

$$h := u + \frac{P}{\rho}$$

$\underbrace{\hspace{1.5cm}}$
spec. internal energy $\underbrace{\hspace{1.5cm}}$
mechanical energy

with $du = Tds + \frac{P}{\rho^2} d\rho$

$$dh = du + \frac{dP}{\rho} - \frac{P}{\rho^2} d\rho$$

$$dh = Tds + \frac{dP}{\rho}$$

For $S = \text{cte}$ and $P = P(\rho)$

(barotropic EOS)

$$dh = \frac{dP}{\rho} = \frac{1}{\rho} \frac{\partial P}{\partial \rho} d\rho$$

$$h(\rho) = \int_0^\rho \frac{1}{\rho'} \frac{\partial P}{\partial \rho'}(\rho') d\rho'$$

\uparrow using

$$\vec{\nabla} h(\rho) = \frac{\partial h}{\partial \rho} \vec{\nabla} \rho = \frac{1}{\rho} \frac{\partial P}{\partial \rho}(\rho) \vec{\nabla} \rho = \frac{1}{\rho} \vec{\nabla} P$$

Isolated fluid at equilibrium

$$\rho_0(\vec{x}) \quad \vec{v}_0(x) \quad h_{s0}(\vec{x}) \quad \phi_{s0}(x)$$

solutions of

① Continuity Equation

$$\frac{\partial \rho_0}{\partial t} + \vec{\nabla} \cdot (\rho_0 \vec{v}_0) = 0$$

② Euler Equation

$$\frac{\partial \vec{v}_0}{\partial t} + (\vec{v}_0 \cdot \vec{\nabla}) \vec{v}_0 = -\vec{\nabla}(h_{s0} + \phi_{s0})$$

③ The Poisson Equation

$$\nabla^2 \phi_{s0} = 4\pi G \rho_{s0}$$

④ Equation of state

$$P_0 = P(\rho_0)$$

The response of the system to a weak perturbation

$$- \varepsilon \nabla \phi_e$$

$$\rho_{s0}(\bar{x}) \rightarrow \rho_s(\bar{x}, t) = \rho_{s0}(\bar{x}) + \varepsilon \rho_{s1}(\bar{x}, t)$$

$$h_{s0}(\bar{x}) \rightarrow h_s(\bar{x}, t) = h_{s0}(\bar{x}) + \varepsilon h_{s1}(\bar{x}, t)$$

$$\vec{v}_{s0}(\bar{x}) \rightarrow \vec{v}_s(\bar{x}, t) = \vec{v}_{s0}(\bar{x}) + \varepsilon \vec{v}_{s1}(\bar{x}, t)$$

$$\phi_{s0}(\bar{x}) \rightarrow \phi_s(\bar{x}, t) = \phi_{s0}(\bar{x}) + \varepsilon \phi_{s1}(\bar{x}, t)$$

$$\phi_{s0}^{\text{tot}}(\bar{x}) \rightarrow \phi(\bar{x}, t) = \phi_{s0}(\bar{x}) + \varepsilon \phi_1(\bar{x}, t)$$



system only,
without the
perturbation

total pot. include
the perturbation

$$= \phi_{s0}(\bar{x}) + \varepsilon \phi_{s1}(\bar{x}, t) + \varepsilon \phi_e(\bar{x}, t)$$

contrib. of the ext. perturb.

→ insert those equations into the equations for a self-gravitating fluid $\rho_s(\bar{x}, t)$ $\phi_s(\bar{x}, t)$ $\vec{v}_s(\bar{x}, t)$ $h_s(\bar{x}, t)$

→ use equations for the unperturbed fluid

→ keep only first order terms ($\varepsilon^2 \rightarrow 0$)

We get a set of linear differential equations

→ time evolution of the perturbation

① "Continuity Equation"

$$\frac{\partial}{\partial t} \rho_{s1} + \bar{\nabla} \cdot (\rho_{s0} \vec{v}_{s1}) + \bar{\nabla} \cdot (\rho_{s1} \vec{v}_{s0}) = 0$$

ρ_{s1} \vec{v}_{s1} ϕ_{s1} h_{s1}
6 unknowns
6 equations

② "Euler Equation"

$$\begin{aligned} \frac{\partial}{\partial t} \vec{v}_{s1} + \vec{v}_{s0} \cdot (\bar{\nabla} \cdot \vec{v}_{s1}) + \vec{v}_{s1} (\bar{\nabla} \cdot \vec{v}_{s0}) &= - \bar{\nabla} \cdot (h_{s1} + \phi_{s1} + \phi_e) \\ &= - \frac{\bar{\nabla} p_{s1}}{\beta_0} - \bar{\nabla} \cdot (\phi_{s1} + \phi_e) \end{aligned}$$

③ "Poisson Equation"

$$\bar{\nabla} \cdot \phi_{s1} = 4\pi G \rho_{s1}$$

④ "Equation of state"

$$h_{s1} = \left. \frac{dP(\rho)}{d\rho} \right|_{\rho_0} \frac{\rho_{s1}}{\rho_0} = v_s^2 \frac{\rho_{s1}}{\rho_0}$$

Linearized Equations for a self-gravitating stellar system

Equations for a self-gravitating stellar system

System of DF

$$f_s(\vec{x}, \vec{v}, t) \rightarrow f_s(\vec{x}, t) \quad \phi_s(\vec{x}, t)$$

(without the perturbation)

① The collisionless Boltzmann Equation

↙ total potential $\phi = \phi_s + \epsilon \phi_c$

$$\frac{\partial f_s}{\partial t} + \vec{v} \frac{\partial f_s}{\partial \vec{x}} - \frac{\partial \phi}{\partial \vec{x}} \frac{\partial f_s}{\partial \vec{v}} = 0$$

$$= \frac{\partial f_s}{\partial t} + [f_s, \mathcal{H}] = 0$$

$$\mathcal{H} = \frac{1}{2} \vec{v}^2 + \phi(\vec{x}, t)$$

② The Poisson Equation

$$\nabla^2 \phi_s = 4\pi G \rho_s = 4\pi G \int d^3v f_s(\vec{x}, \vec{v}, t)$$

Isolated stellar system at equilibrium

$$f_0(\vec{x}, \vec{v}) \quad \rho_0(\vec{x}) \quad \phi_0(\vec{x})$$

solutions of

① The collisionless Boltzmann Equation

$$\frac{\partial f_0}{\partial t} + [f_0, \psi_0] = 0$$

$$\psi_0 = \frac{1}{2} \vec{v}^2 + \phi_0(\vec{x})$$

② The Poisson Equation

$$\nabla^2 \phi_0 = 4\pi G \rho_0 = 4\pi G \int d^3v f_0(\vec{x}, \vec{v}, t)$$

The response of the system to a weak perturbation

$$- \varepsilon \vec{\nabla} \phi_e$$

$$\rho_{s0}(\vec{x}, \vec{v}, t) \rightarrow \rho_s(\vec{x}, \vec{v}, t) = \rho_{s0}(\vec{x}, \vec{v}) + \varepsilon \rho_{s1}(\vec{x}, \vec{v}, t)$$

$$\rho_{s0}(\vec{x}, t) \rightarrow \rho_s(\vec{x}, t) = \rho_{s0}(\vec{x}) + \varepsilon \rho_{s1}(\vec{x}, t)$$

$$\phi_{s0}(x, t) \rightarrow \phi_s(x, t) = \phi_{s0}(\vec{x}) + \varepsilon \phi_{s1}(\vec{x}, t)$$

$$\phi_{s0}(x, t) \rightarrow \phi(x, t) = \phi_{s0}(\vec{x}) + \varepsilon \phi_{s1}(\vec{x}, t)$$

$$= \phi_{s0}(\vec{x}) + \varepsilon \phi_{s1}(\vec{x}, t) + \varepsilon \phi_e(\vec{x}, t)$$

total pot. include the perturbation

contrib of the ext. perturb.

$$H_0(\vec{x}, \vec{v}) \rightarrow H_{tot}(x, t) = \frac{1}{2} \vec{v}^2 + \phi_0(\vec{x}) + \varepsilon \phi_1(\vec{x}, t)$$

$$= H_0(\vec{x}, \vec{v}) + \varepsilon \phi_1(\vec{x}, t)$$

include the perturbation

→ insert those equations into the equations for a

self-gravitating stellar system $\rho_s(\vec{x}, \vec{v}, t)$ $\rho_s(\vec{x}, t)$ $\phi_s(\vec{x}, t)$

→ use equations for the unperturbed stellar system

→ keep only first order terms ($\varepsilon^2 \rightarrow 0$)

We get a set of linear differential equations

→ time evolution of the perturbation

① "The collisionless Boltzmann Equation"

ρ_{s1} ρ_{s1} ϕ_{s1}
3 unknowns
3 equations

$$\frac{\partial \rho_{s1}}{\partial t} + [\rho_{s1}, H_{s0}] = [\rho_{s0}, \phi_{s1}]$$

$$\frac{\partial \rho_{s1}}{\partial t} + \frac{\partial \rho_{s1}}{\partial \vec{x}} \vec{v} - \frac{\partial \rho_{s1}}{\partial \vec{v}} \frac{\partial \phi_{s0}}{\partial \vec{x}} = \frac{\partial \rho_{s0}}{\partial \vec{v}} \frac{\partial \phi_{s1}}{\partial \vec{x}}$$

② "The Poisson Equation"

$$\nabla^2 \phi_{s1} = 4\pi G \rho_{s1} = 4\pi G \int d^3v \rho_{s1}$$

Interpretation

Reminder

Variation of ρ_{s1} along the flow (Lagrangian derivative)

$$\frac{\partial \rho_{s1}}{\partial t} + [\rho_{s1}, H_{s0}] = [\rho_{s0}, \phi_1]$$

$$\frac{\partial \rho_{s1}}{\partial t} + \frac{\partial \rho_{s1}}{\partial \vec{x}} \vec{v} - \frac{\partial \rho_{s1}}{\partial \vec{v}} \frac{\partial \phi_{s0}}{\partial \vec{x}} = \frac{\partial \rho_{s0}}{\partial \vec{v}} \frac{\partial \phi_1}{\partial \vec{x}}$$

$\frac{d}{dt} \rho_{s1}$

velocity

source

gravity

$P_v(\vec{x})$



may become
big if σ is
small

Stability of collisionless systems

The Jeans instability

(1902)

The Jeans instability

Homogeneous medium subject to a perturbation

- consider an infinite static homogeneous system at equilibrium

- \triangle no polytropic homogeneous system exists

$$\vec{V}_0 = 0$$

Euler Equation

$$\cancel{\frac{\partial \vec{v}_0}{\partial t}} + (\cancel{\vec{v}_0} \cdot \cancel{\vec{\nabla}}) \vec{v}_0 = - \cancel{\frac{\vec{\nabla} p_0}{\rho_0}} - \vec{\nabla} \phi_0$$

$$\Rightarrow \vec{\nabla} \phi_0 = 0$$

Poisson Equation

$$\nabla^2 \phi_0 = 4\pi G \rho_0 \quad \Rightarrow \quad \underline{\rho_0 = 0}$$

Linearized Poisson

$$\nabla^2 \phi_s = 4\pi G \rho_s \equiv \nabla^2 (\phi_0 + \epsilon \phi_{s1}) = 4\pi G (\rho_0 + \epsilon \rho_{s1})$$

$$\nabla^2 \phi_{s1} = 4\pi G \rho_{s1}$$

Jeans swindle

The response of an homogeneous fluid

Linearized fluid equations

$\rho_{s1}(\bar{x}, t)$, $\phi_{s1}(\bar{x}, t)$, $\vec{v}_{s1}(\bar{x}, t)$, $h_{s1}(\bar{x}, t)$

$$\left\{ \begin{array}{l} \textcircled{1} \quad \frac{\partial}{\partial t} \rho_{s1} + \bar{\nabla} \cdot (\rho_0 \vec{v}_{s1}) + \bar{\nabla} \cdot (\rho_{s1} \vec{v}_0) = 0 \\ \textcircled{2} \quad \frac{\partial}{\partial t} \vec{v}_{s1} + \vec{v}_0 \cdot (\bar{\nabla} \cdot \vec{v}_{s1}) + \vec{v}_{s1} \cdot (\bar{\nabla} \cdot \vec{v}_0) = - \bar{\nabla} (h_{s1} + \phi_{s1} + \phi_e) \\ \textcircled{3} \quad \bar{\nabla} \phi_{s1} = 4\pi G \rho_{s1} \\ \textcircled{4} \quad h_{s1} = v_s^2 \frac{\rho_{s1}}{\rho_0} \end{array} \right. \quad \boxed{\vec{v}_0 = 0}$$

Solution

$$\frac{\partial}{\partial t} \textcircled{1} : \quad \frac{\partial^2}{\partial t^2} \rho_{s1} + \rho_0 \bar{\nabla} \cdot \left(\frac{\partial}{\partial t} \vec{v}_{s1} \right) = 0$$

$$\bar{\nabla} \cdot \textcircled{2} : \quad \bar{\nabla} \cdot \frac{\partial \vec{v}_{s1}}{\partial t} = - \nabla^2 (h_{s1} + \phi_{s1} + \phi_e)$$

Thus, we have ($\bar{\nabla} \cdot \textcircled{2}$ into $\frac{\partial}{\partial t} \textcircled{1}$)

$$\frac{\partial^2}{\partial t^2} \rho_{s1} - \rho_0 \nabla^2 (h_{s1} + \phi_{s1} + \phi_e) = 0$$

$$\frac{\partial^2}{\partial t^2} \rho_{sn} - \rho_0 \nabla^2 (h_{sn} + \phi_{sn} + \phi_e) = 0$$

$$\frac{\partial^2}{\partial t^2} \rho_{sn} - \rho_0 \nabla^2 h_{sn} - \rho_0 \nabla^2 \phi_{sn} = \rho_0 \nabla^2 \phi_e$$

$$\textcircled{2} \quad \vec{\nabla} h_{sn} = \frac{1}{\rho_s} \vec{\nabla} \rho_{sn}$$

$$\frac{1}{\rho_0} \frac{\partial^2}{\partial t^2} \rho_{sn} - \vec{\nabla} \cdot \left(\frac{\vec{\nabla} \rho_{sn}}{\rho_s} \right) - \vec{\nabla} \cdot (\vec{\nabla} \phi_{sn}) = \vec{\nabla} \cdot (\vec{\nabla} \phi_e)$$

Growth accel.
of ρ_{sn}

F_{pressure}

$F_{\text{grav, self}}$

$F_{\text{grav, ext}}$

(spec. forces)

$$\frac{\partial^2}{\partial t^2} \rho_{sn} - \rho_0 \nabla^2 h_{sn} - \rho_0 \nabla^2 \phi_{sn} = \rho_0 \nabla^2 \phi_e$$

$\textcircled{4} \quad - v_s^2 \nabla^2 \rho_{sn} \quad \textcircled{3} \quad - 4\pi G \rho_0 \rho_{sn} \quad \text{under } \rho_0 \nabla^2 \phi_e \quad \text{under } \rho_0 \nabla^2 \phi_e$

$$\nabla^2 \phi_e = 4\pi G \rho_e$$

$$\frac{\partial^2}{\partial t^2} \rho_{sn} - v_s^2 \nabla^2 \rho_{sn} - 4\pi G \rho_0 \rho_{sn} = 4\pi G \rho_0 \rho_e$$

pressure

self grav.

ext. grav.

Differential equation for ρ_{sn} only
Evolution of a perturbation in an
homogeneous fluid

Some simple cases

$$\frac{\partial^2}{\partial t^2} p_{s1} - v_s^2 \nabla^2 p_{s1} - 4\pi G \rho_0 p_{s1} = 4\pi G \rho_0 p_e$$

1) no gravity, no ext forces

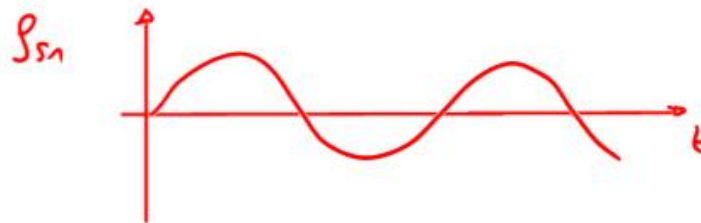
$$\frac{\partial^2}{\partial t^2} p_{s1} - v_s^2 \nabla^2 p_{s1} = 0$$

In 1-D $\frac{\partial^2}{\partial t^2} p_{s1}(x,t) - v_s^2 \frac{\partial^2}{\partial x^2} p_{s1}(x,t) = 0$ (wave equation)

general solution : f : an arbitrary function

$$p_{s1}(x,t) = \underbrace{f(x - v_s t)}_{\text{move at speed } v_s} + \underbrace{f(x + v_s t)}_{\text{move at speed } -v_s}$$

sound wave traveling at sound speed v_s



oscillatory
solution

STABLE

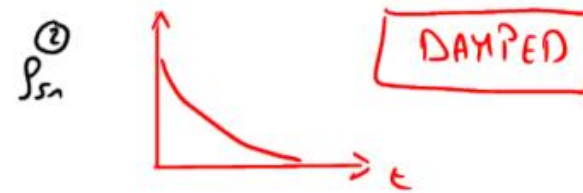
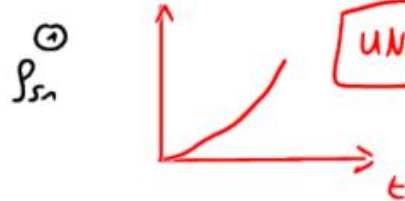
$$\frac{\partial^2}{\partial t^2} \rho_{s1} - v_s^2 \nabla^2 \rho_{s1} - 4\pi G \rho_0 \rho_{s1} = 4\pi G \rho_0 \rho_e$$

2) no pressure, no external forces

$$\frac{\partial^2}{\partial t^2} \rho_{s1} = 4\pi G \rho_0 \rho_{s1}$$

Solutions: any linear combination of

$$\rho_{s1}^{(1)}(x,t) = \tilde{f}(\vec{x}) e^{\sqrt{4\pi G \rho_0} t} \quad \text{and} \quad \rho_{s1}^{(2)}(x,t) = \tilde{f}(\vec{x}) e^{-\sqrt{4\pi G \rho_0} t}$$



3) no external forces

$$\frac{\partial^2}{\partial t^2} \rho_{s1} - v_s^2 \nabla^2 \rho_{s1} - 4\pi G \rho_0 \rho_{s1} = 0$$

pressure
stabilize

self-gravity
destabilize

General solutions

$$e^{i(\vec{k}\vec{x} - \omega t)}$$

• $\times e^{-i\vec{k}\vec{x}} + \int d^3\vec{x} \Rightarrow$ spatial Fourier transform

$$\bar{f}_{S_1}(\vec{k}, t) = \int d^3x e^{-i\vec{k}\vec{x}} f_{S_1}(\vec{x}, t)$$

$$\frac{\partial^2}{\partial t^2} \bar{f}_{S_1}(\vec{k}, t) + v_s^2 k^2 \bar{f}_{S_1}(\vec{k}, t) - 4\pi G \rho_0 \bar{f}_{S_1}(\vec{k}, t) = 4\pi G \rho_0 \bar{f}_e(\vec{k}, t)$$

(after the)

Evolution in absence of perturbation

$$f_e(x, t) = 0 \quad \bar{f}_e = 0$$

Solutions are in the form

$$\bar{f}_{S_1}(\vec{k}, t) \sim e^{-i\omega t} \quad \omega = \omega(|\vec{k}|) \in \mathbb{C}$$
$$k = |\vec{k}|$$

Introducing in the previous equation, we get the dispersion relation

$$\omega^2(k) = v_s^2 k^2 - 4\pi G \rho_0$$

More discussion

$$k_J^2 = \frac{4\pi G \rho_0}{v_s^2}$$

$$\omega^2(k) = v_s^2(k^2 - k_J^2)$$

Assume a perturbation with a fixed wave number k .

① $\rho_0 = 0$ (no gravity)

$$\Rightarrow k_J = 0$$

$k > k_J$

$$\omega^2(k) = v_s^2 k^2 \in \mathbb{R}_e$$

dispersion relation
for a sound wave
oscillation at frequ. ω

$$\bar{p}_{sn} \sim e^{-i\omega t}$$

STABLE

② $\rho_0 \neq 0$

$k > k_J$

ω decreases with k increases

STABLE

$k = k_J$

$$\omega = 0$$

$k < k_J$

$$\omega^2 \in \mathbb{I}_m$$

UNSTABLE

③ $\rho \gg v_s^2 / 4\pi G$ (no pressure) $k_J \rightarrow \infty$

UNSTABLE

Definitions

Jeans length

$$\lambda_J = \frac{e\pi}{k_J} = \sqrt{\frac{\pi v_s^2}{G\rho_0}}$$

$$\lambda > \lambda_J \Rightarrow \text{UNSTABLE}$$

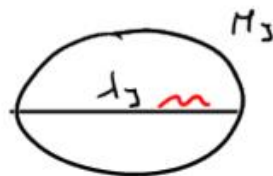
Jeans mass

Mass inside a sphere of radius $\frac{1}{2} \lambda_J$

$$M_J = \frac{4}{3} \pi \left(\frac{1}{2} \lambda_J\right)^3 \rho_0$$

$$M_J = \frac{\pi^{5/2}}{6} \frac{v_s^3}{G^{3/2} \rho_0^{1/2}}$$

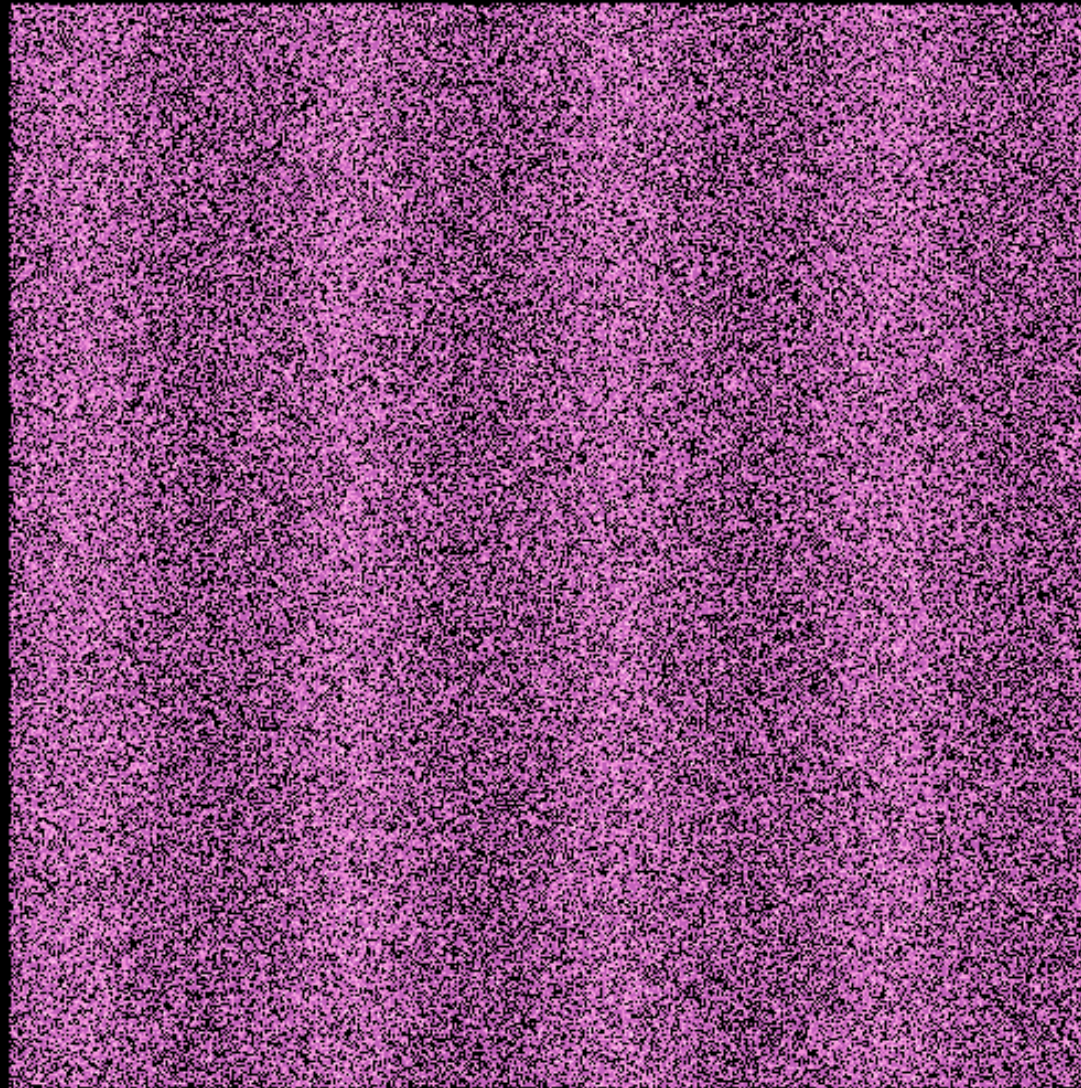
"Minimum mass that can collapse"



any perturbation with $\lambda < \lambda_J$ i.e. involving a mass $< M_J$ will be **STABLE**

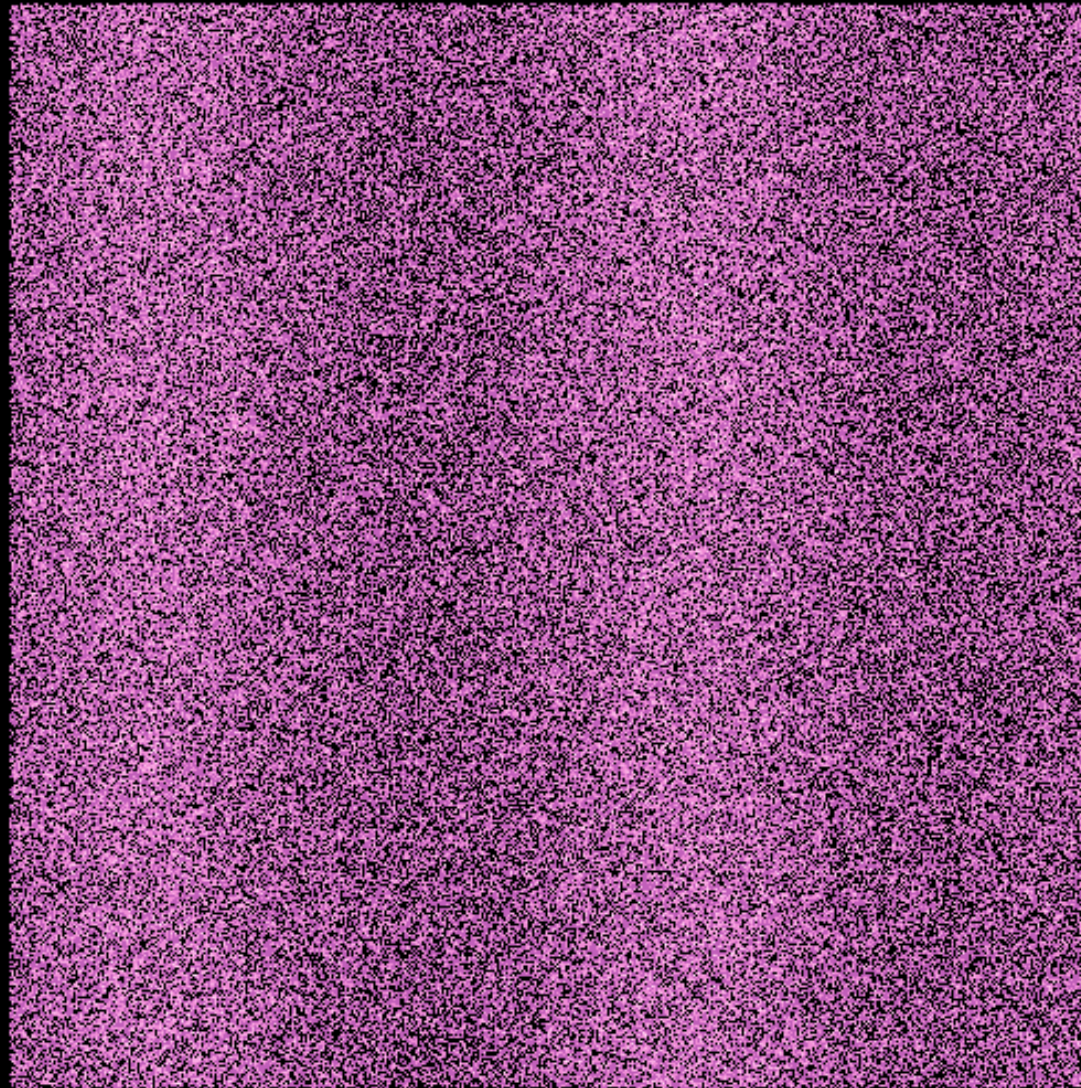
The Jeans instability in fluid systems

$$\lambda_J = 1.50 \quad \lambda = 0.25$$



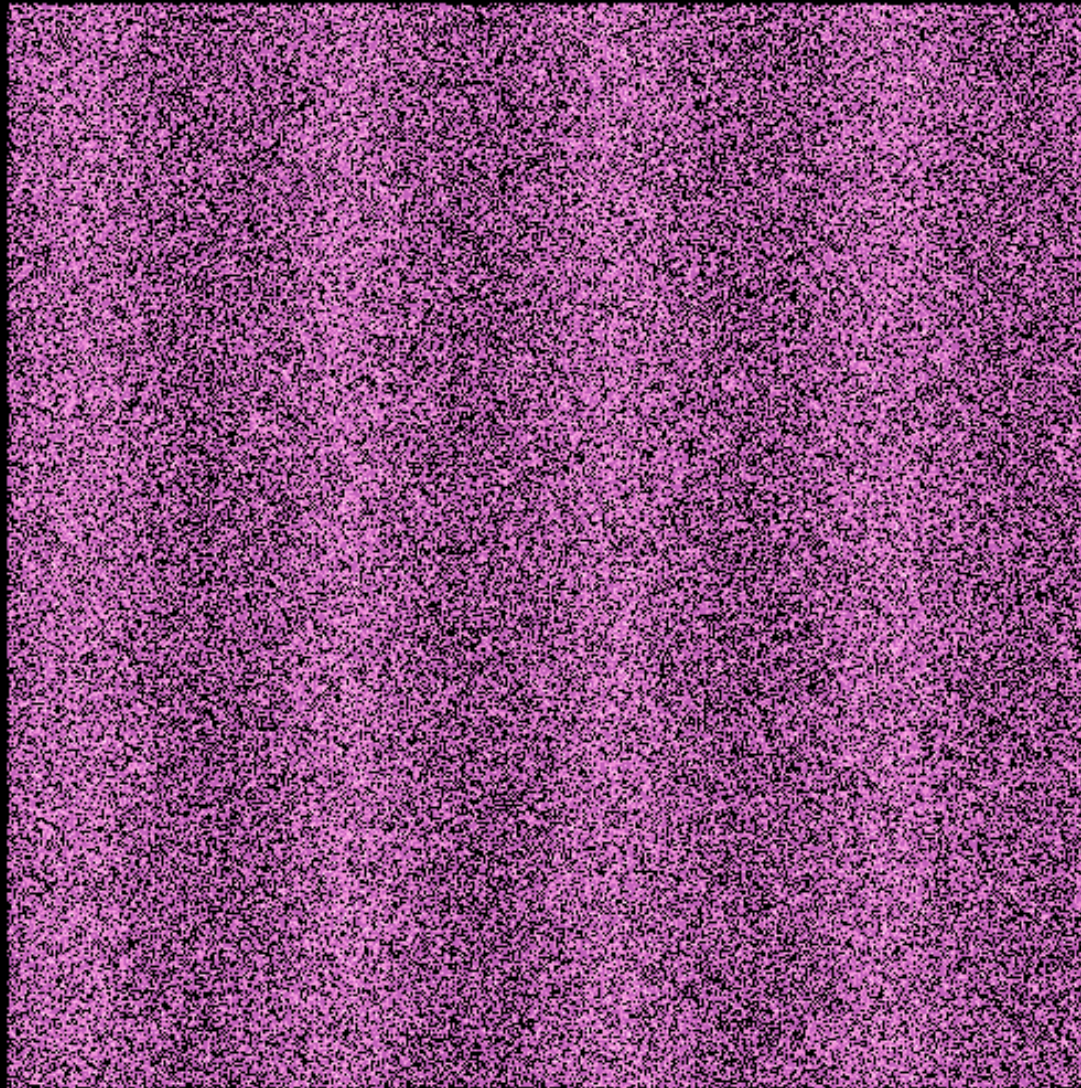
The Jeans instability in fluid systems

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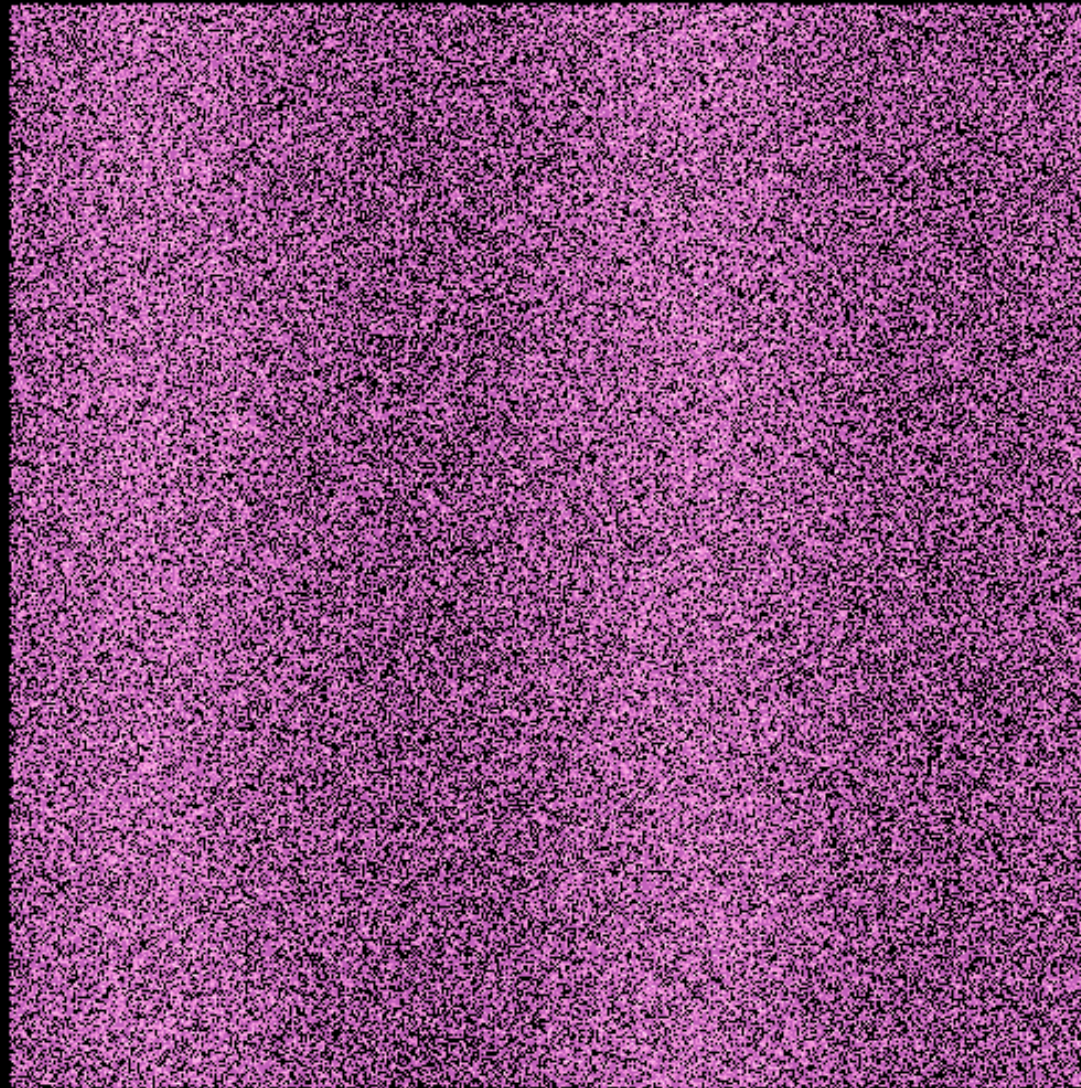
The Jeans instability in fluid systems

$$\lambda_J = 0.25 \quad \lambda = 0.25$$



The Jeans instability in fluid systems

$$\lambda_J = 0.25 \quad \lambda = 0.50$$



The response of an homogeneous stellar system

Linearized equations

$$\left\{ \begin{array}{l} \textcircled{1} \quad \frac{\partial \rho_{s1}}{\partial t} + [\rho_{s1}, H_0] = [\rho_0, \phi_1] \\ \equiv \quad \frac{\partial \rho_{s1}}{\partial t} + \frac{\partial \rho_{s1}}{\partial \vec{x}} \vec{v} - \frac{\partial \rho_{s1}}{\partial \vec{v}} \frac{\partial \phi_0}{\partial \vec{x}} = \frac{\partial \rho_0}{\partial \vec{v}} \frac{\partial \phi_1}{\partial \vec{x}} \equiv \frac{\partial \rho_0}{\partial \vec{v}} \frac{\partial}{\partial \vec{x}} (\phi_{s1} + \phi_e) \\ \textcircled{2} \quad \nabla^2 \phi_{s1} = 4\pi G \rho_{s1} = 4\pi G \int d^3\vec{v} \rho_{s1} \end{array} \right.$$

$\phi_0 = 0$

Manipulation + special Fourier space

$$\bar{\rho}_1(\vec{k}, \vec{v}, t) = i\vec{k} \cdot \frac{\partial \rho_0}{\partial \vec{v}} \int_{-\infty}^t dt' e^{i\vec{k} \cdot \vec{v}(t-t')} [\bar{\phi}_{s1}(\vec{k}, t') + \bar{\phi}_e(\vec{k}, t')]$$

⚠ The DF depends on the past history $\left(\int_{-\infty}^t \rho_{s1} + \rho_e \right)$

Integration over $d^3\vec{v}$ + Poisson

$$\downarrow \bar{f}_{sn}(\vec{k}, t) = -\frac{4\pi G}{k^2} i \int d^3\vec{v} \vec{k} \cdot \frac{\partial \rho_0}{\partial \vec{v}} \int_{-\infty}^t dt' e^{i\vec{k}\cdot\vec{v}(t-t')} [\bar{f}_{sn}(\vec{k}, t') + \bar{f}_e(\vec{k}, t')] \quad \downarrow$$

In temporal Fourier space

This term may diverge if $\vec{k}\cdot\vec{v} = \omega$

$$\tilde{f}_{sn}(\vec{k}, \omega) = \int dt \bar{f}_{sn}(\vec{k}, t) e^{-i\omega t}$$

$$\tilde{f}_{sn}(\vec{k}, \omega) = \left(-\frac{4\pi G}{k^2} \int \frac{d^3\vec{v}}{\vec{k}\cdot\vec{v} - \omega} \vec{k} \cdot \frac{\partial \rho_0}{\partial \vec{v}} \right) \left(\tilde{f}_{sn}(\vec{k}, \omega) + \tilde{f}_e(\vec{k}, \omega) \right)$$

In absence of perturbation

$$f_e = 0$$

we must have:

$$-\frac{4\pi G}{k^2} \int \frac{d^3\vec{v}}{\vec{k}\cdot\vec{v} - \omega} \vec{k} \cdot \frac{\partial \rho_0}{\partial \vec{v}} = 1$$

$$\frac{\text{Im}(\omega) > 0}{\text{---}}$$

(instead, we may have a divergence)

This is our dispersion relation

$$\omega = \omega(\vec{k}, \rho_0)$$

Assuming a Maxwellian for the unperturbed DF f_0

$$f_0(\vec{v}) = \frac{f_0}{(2\pi\sigma^2)^{3/2}} e^{-\frac{v^2}{2\sigma^2}}$$

The dispersion relation becomes

$$-\frac{4\pi G}{k^2} \int \frac{d^3\vec{v}}{k \cdot \vec{v} - \omega} \bar{k} \cdot \frac{\partial f_0}{\partial \vec{v}} = 1 \quad \Rightarrow \quad \frac{4\pi G f_0}{k^2 \sigma^2} (1 + w' Z(w')) = 1$$

with

$$w' = \sqrt{2} k \sigma w \quad Z(w') = \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} ds \frac{e^{-s^2}}{s - w'} = i\sqrt{\pi} e^{-w'^2} [1 + \text{erf}(i w')]$$

$$k = |k|$$

$$\text{erf}(z) = \frac{2}{\sqrt{\pi}} \int_0^z dt e^{-t^2}$$

The dispersion relation is $\text{Im}(w) > 0$

$$\frac{4\pi G \rho_0}{k^2 \sigma^2} (1 + w' z(w')) = 1$$

$$w' = \sqrt{2} k \sigma w$$

$$z(w') = \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} ds \frac{e^{-s^2}}{s - w'}$$

Defining $k_j^2 = \frac{4\pi G \rho_0}{\sigma^2}$

fluid $k_j^2 = \frac{4\pi G \rho_0}{c_s^2}$

$$\frac{k^2}{k_j^2} = 1 + w' z(w')$$

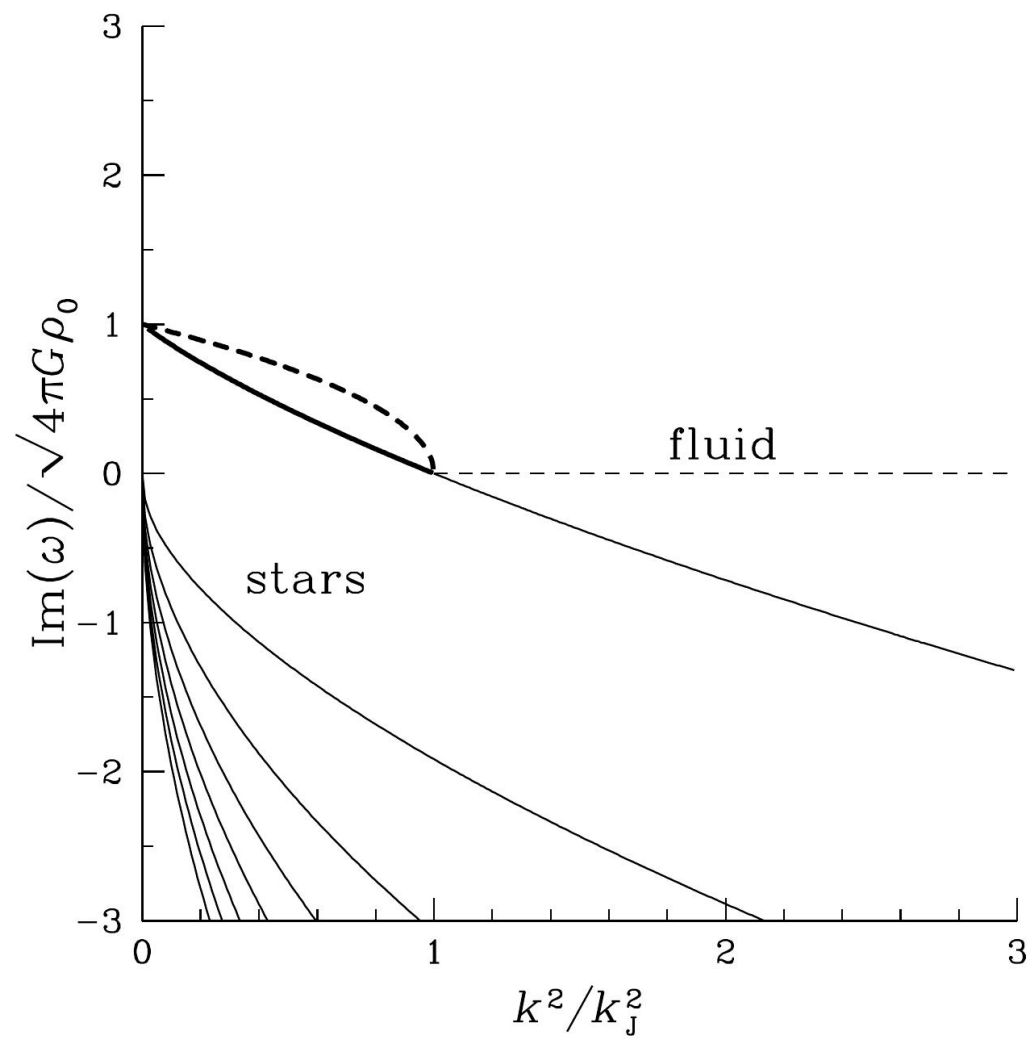
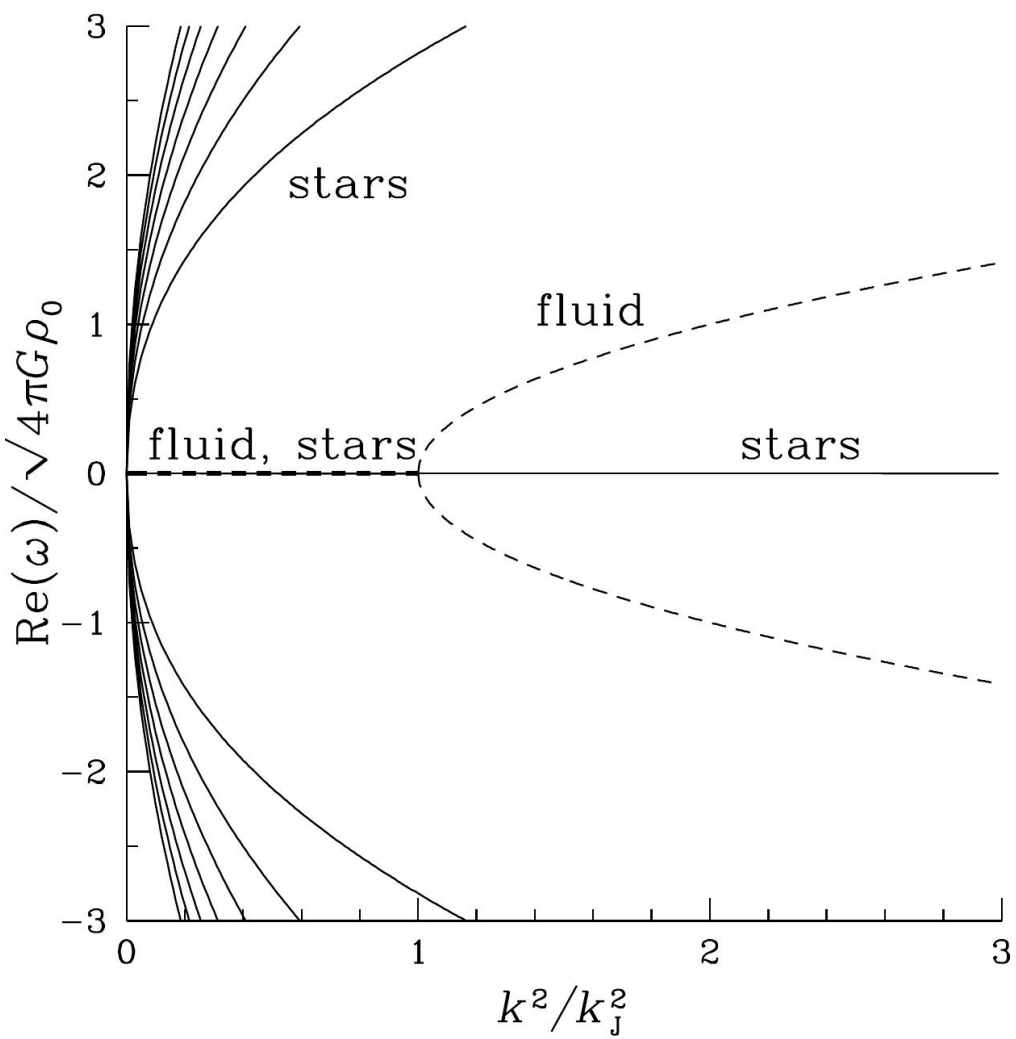
$$\frac{k^2}{k_j^2} = 1 + \frac{w^2}{k_j^2 c_s^2}$$

$$\frac{w^2}{z(w')} = \sigma^2 (k^2 - k_j^2)$$

$$w^2 = c_s^2 (k^2 - k_j^2)$$

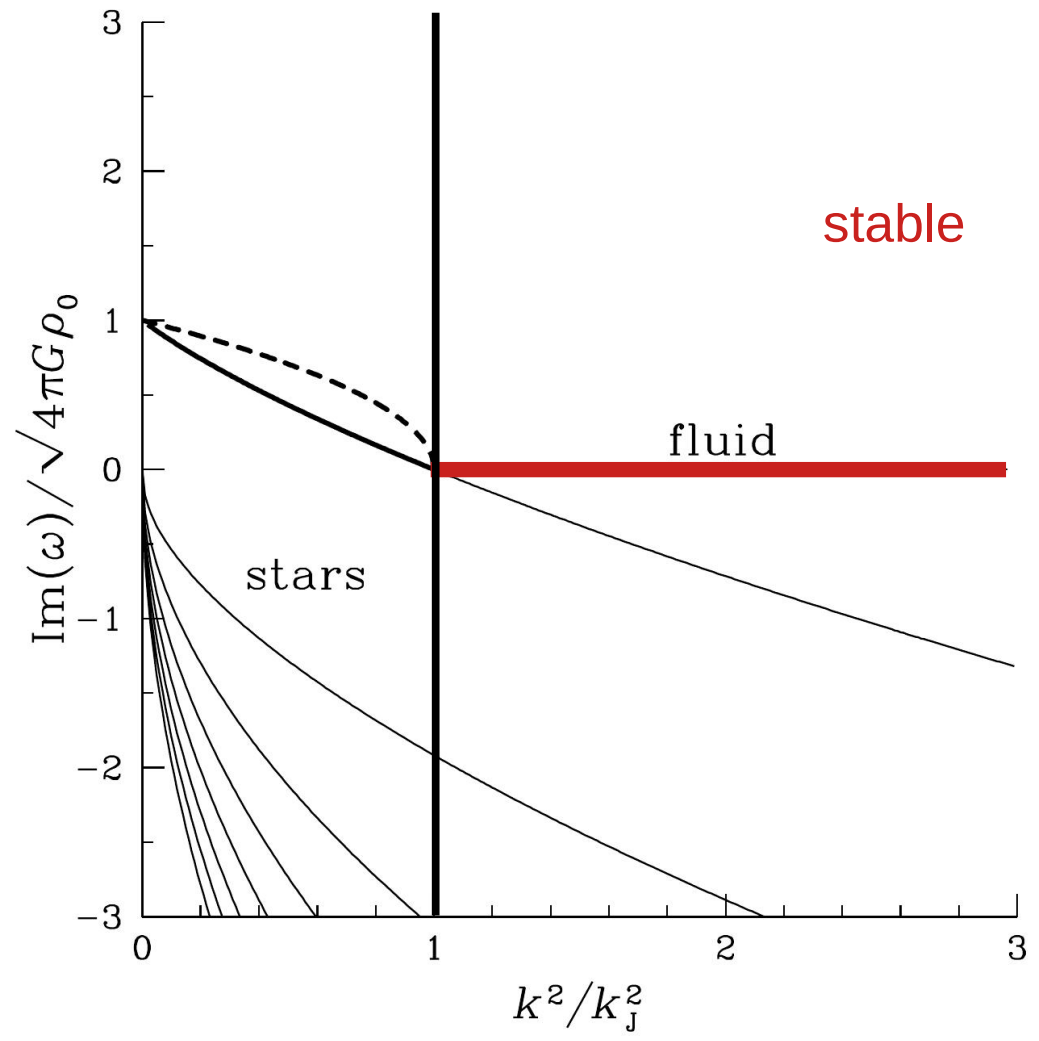
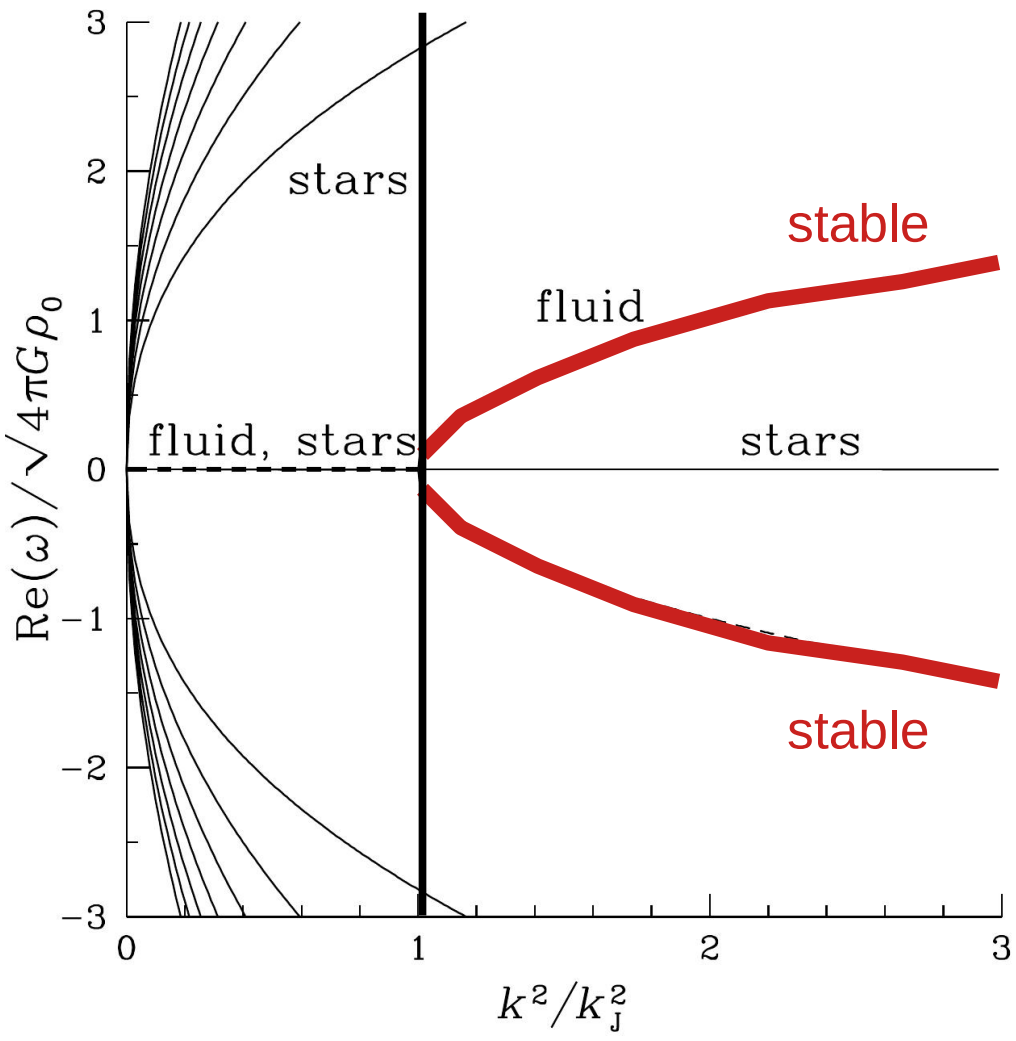
one k is hidden here

! for $\text{Im}(w) = 0$ or $\text{Im}(w) < 0$ (a bit more tricky)



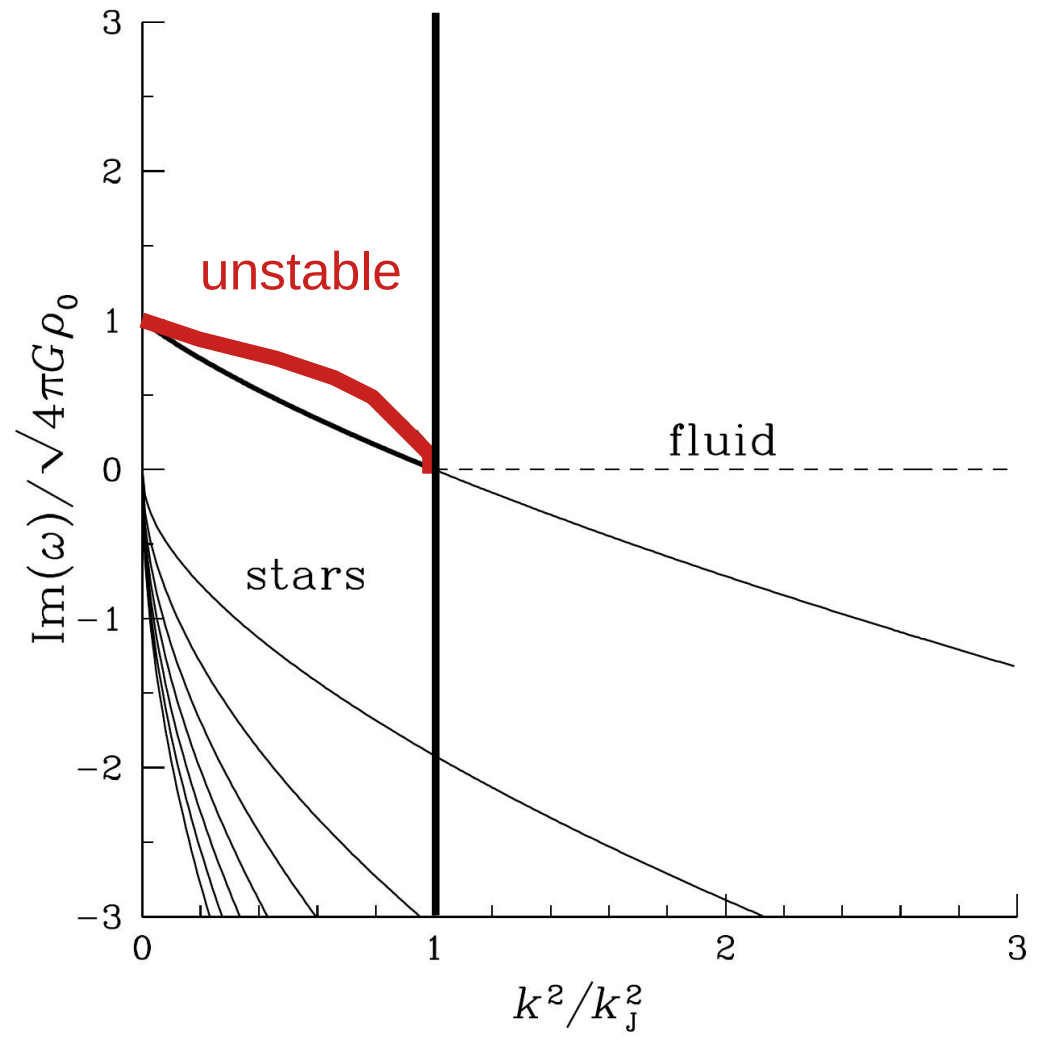
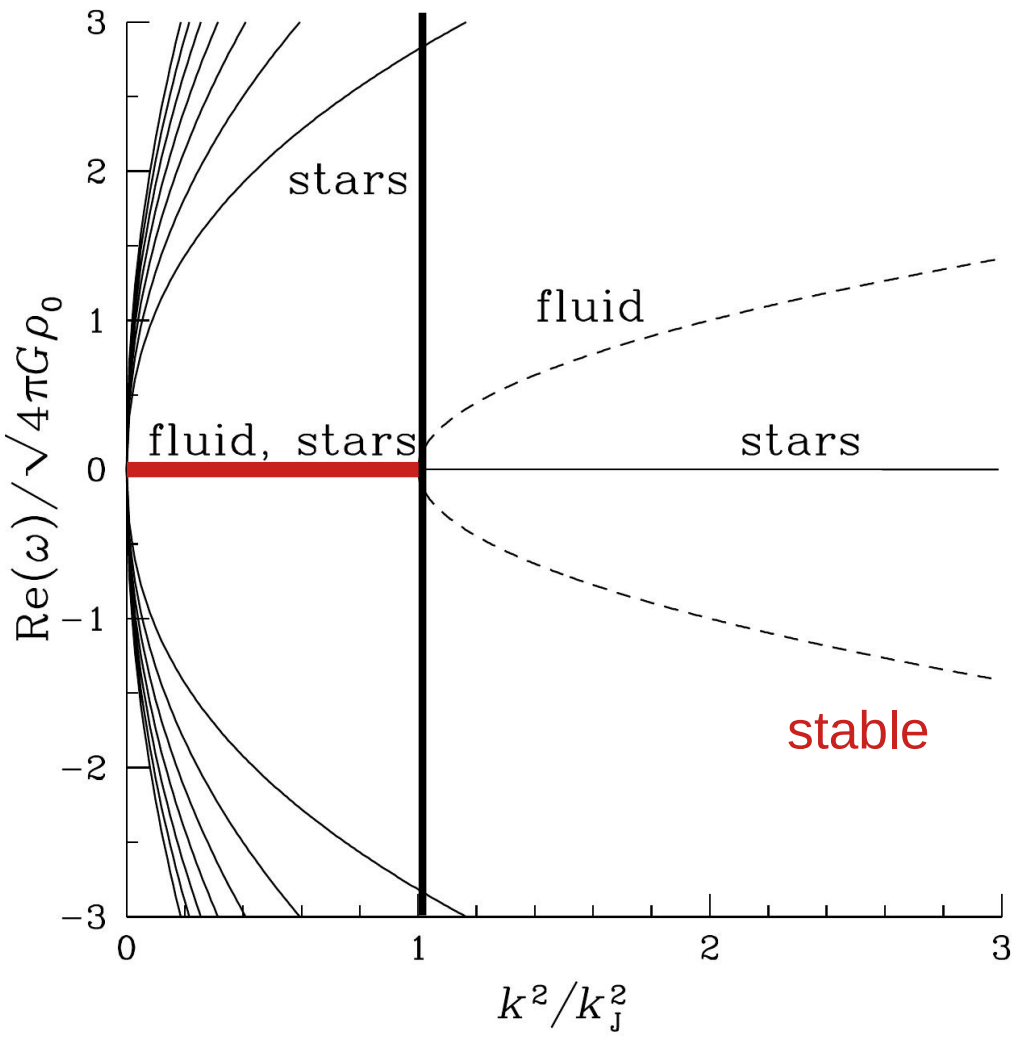
The dispersion relation for fluids

$$\frac{k^2}{k_J^2} = 1 + \frac{\omega^2}{k_J^2 v_s^2}$$



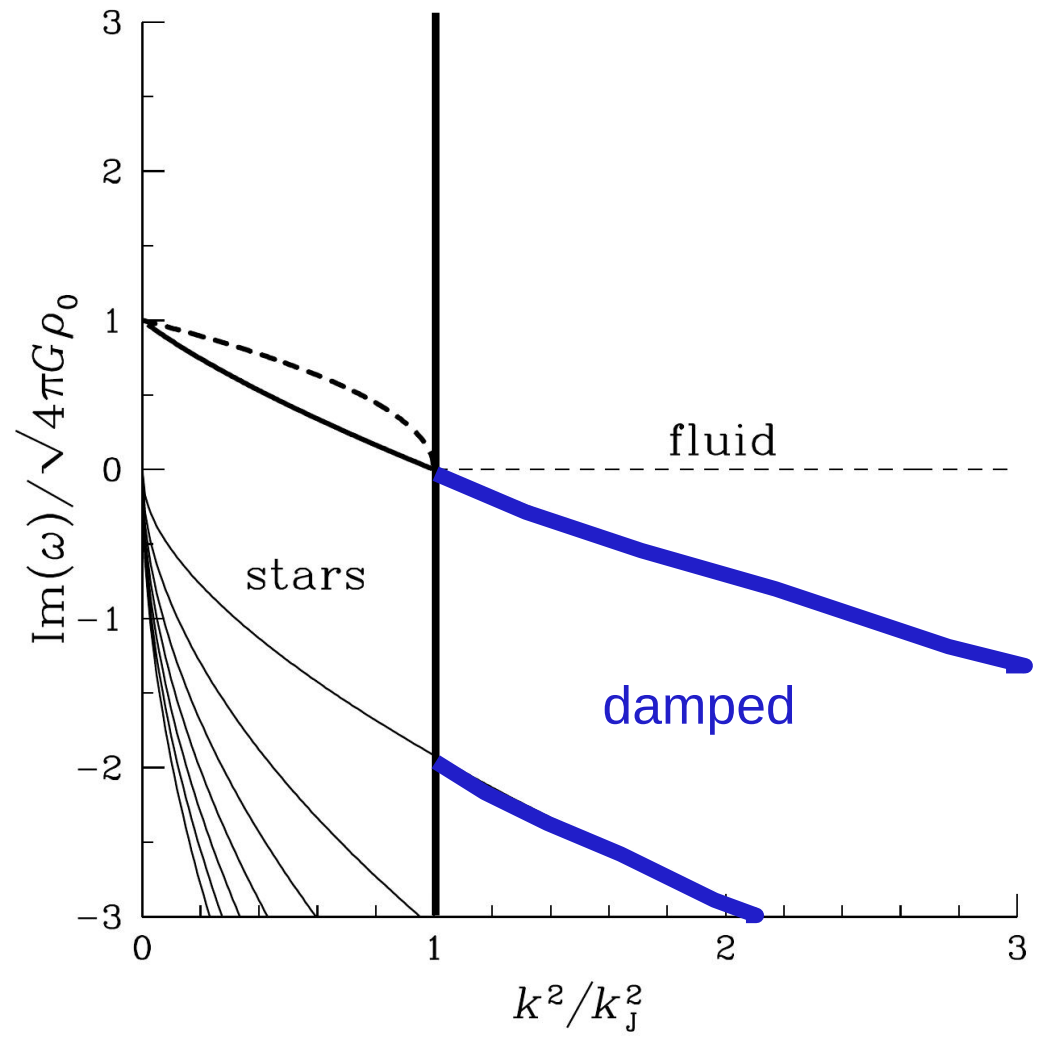
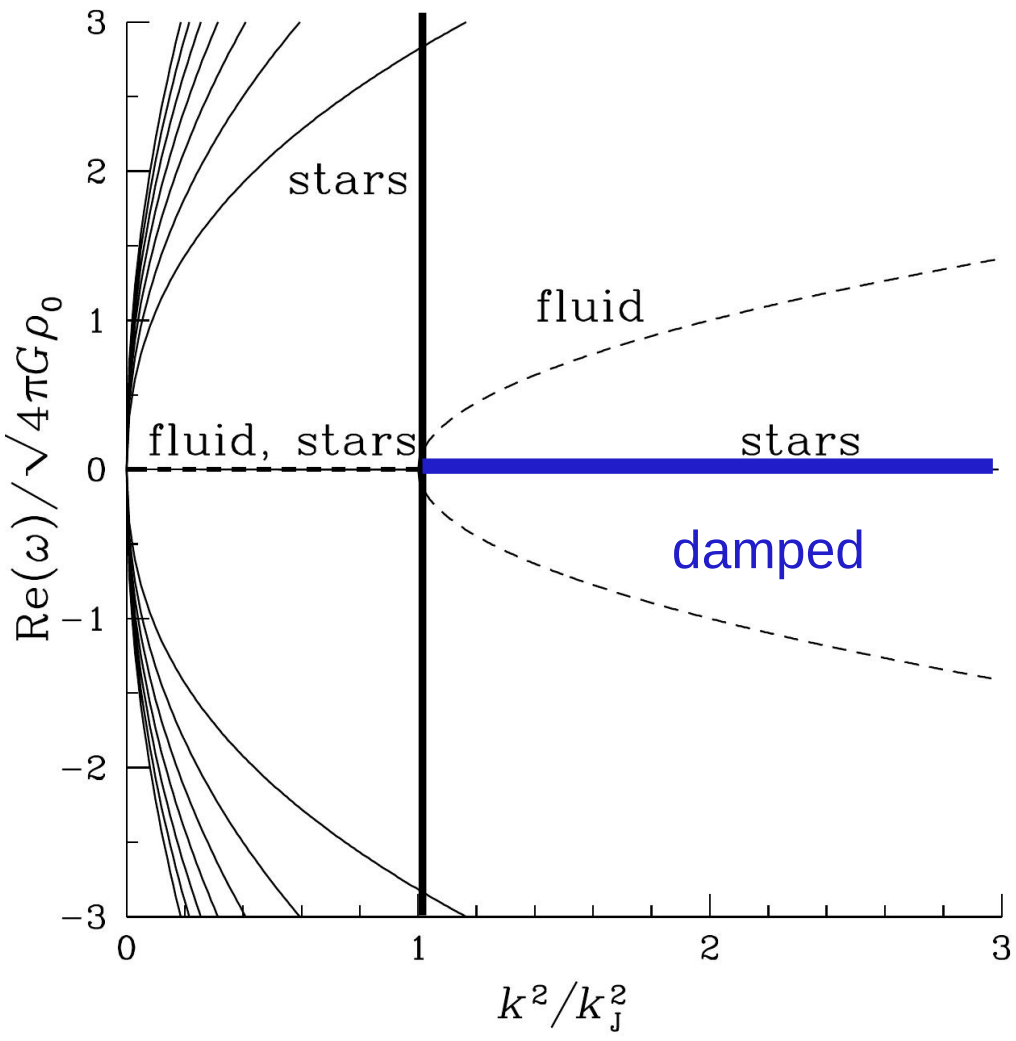
The dispersion relation for fluids

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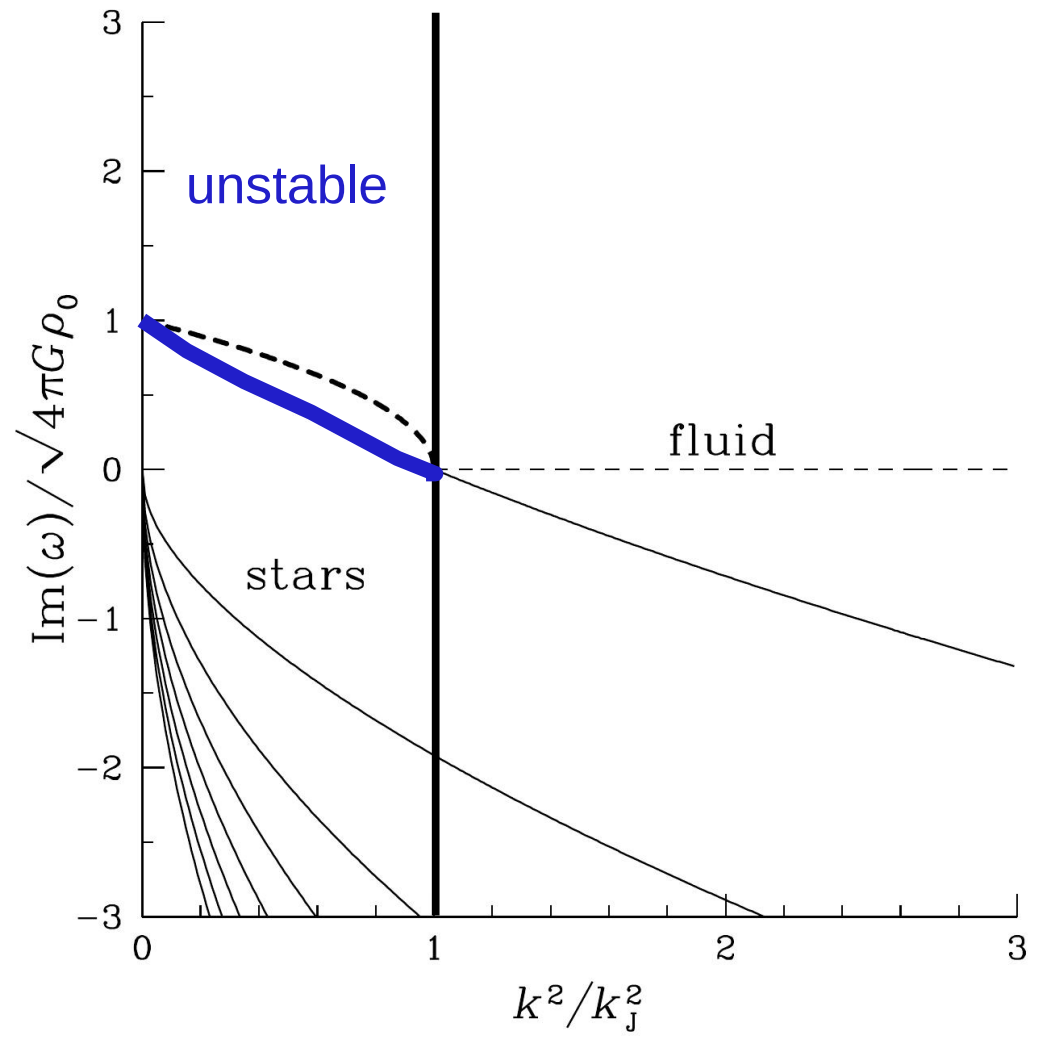
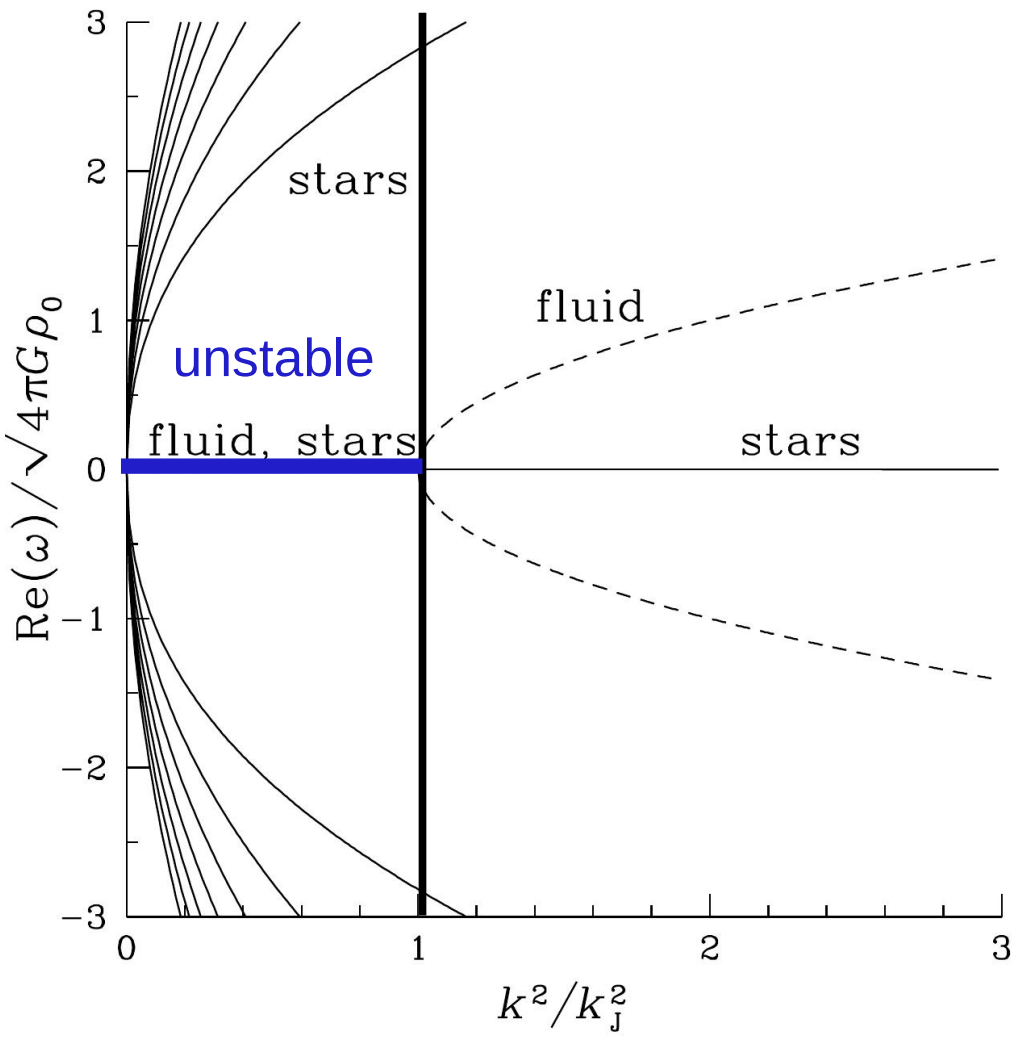
The dispersion relation for stellar systems

$$\frac{k^2}{k_J^2} = \gamma + \omega' \cdot \zeta(\omega')$$



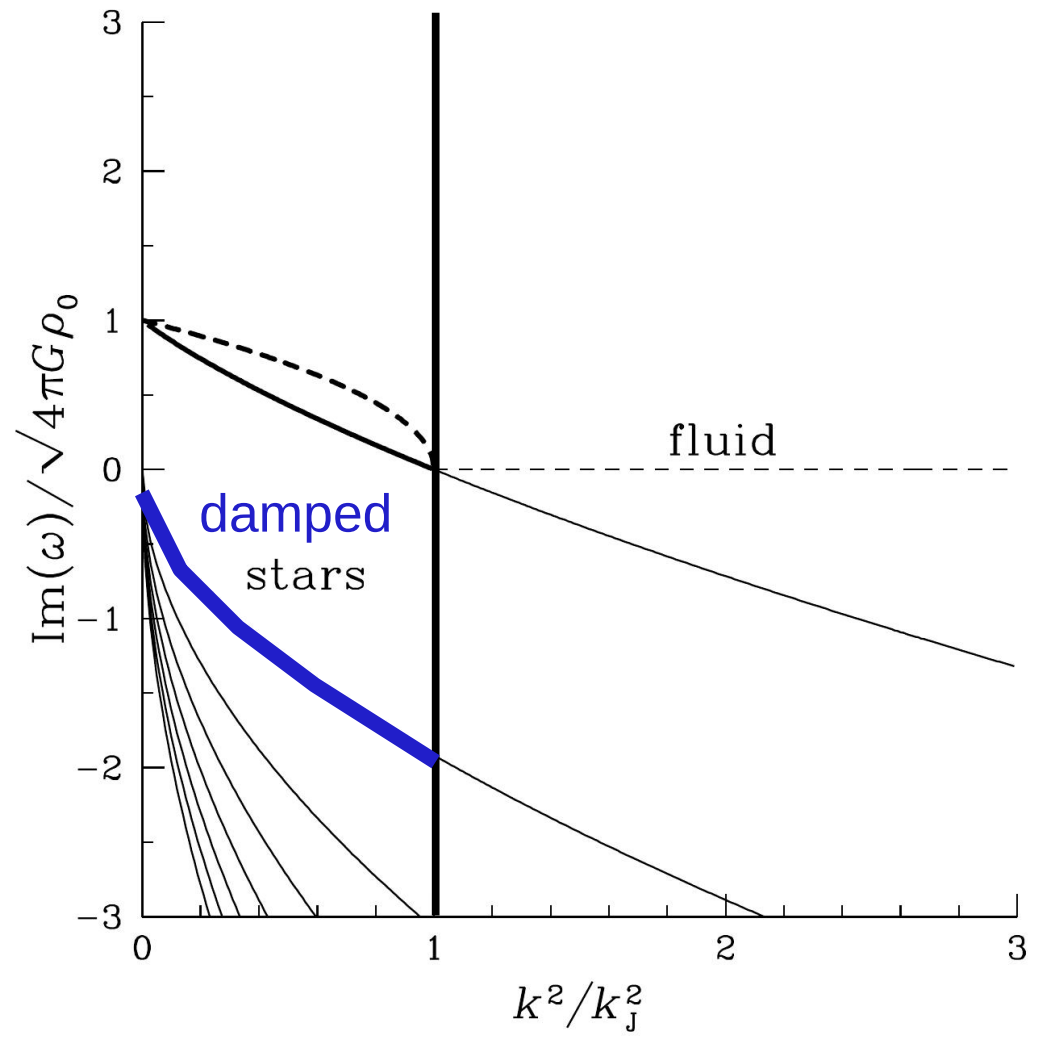
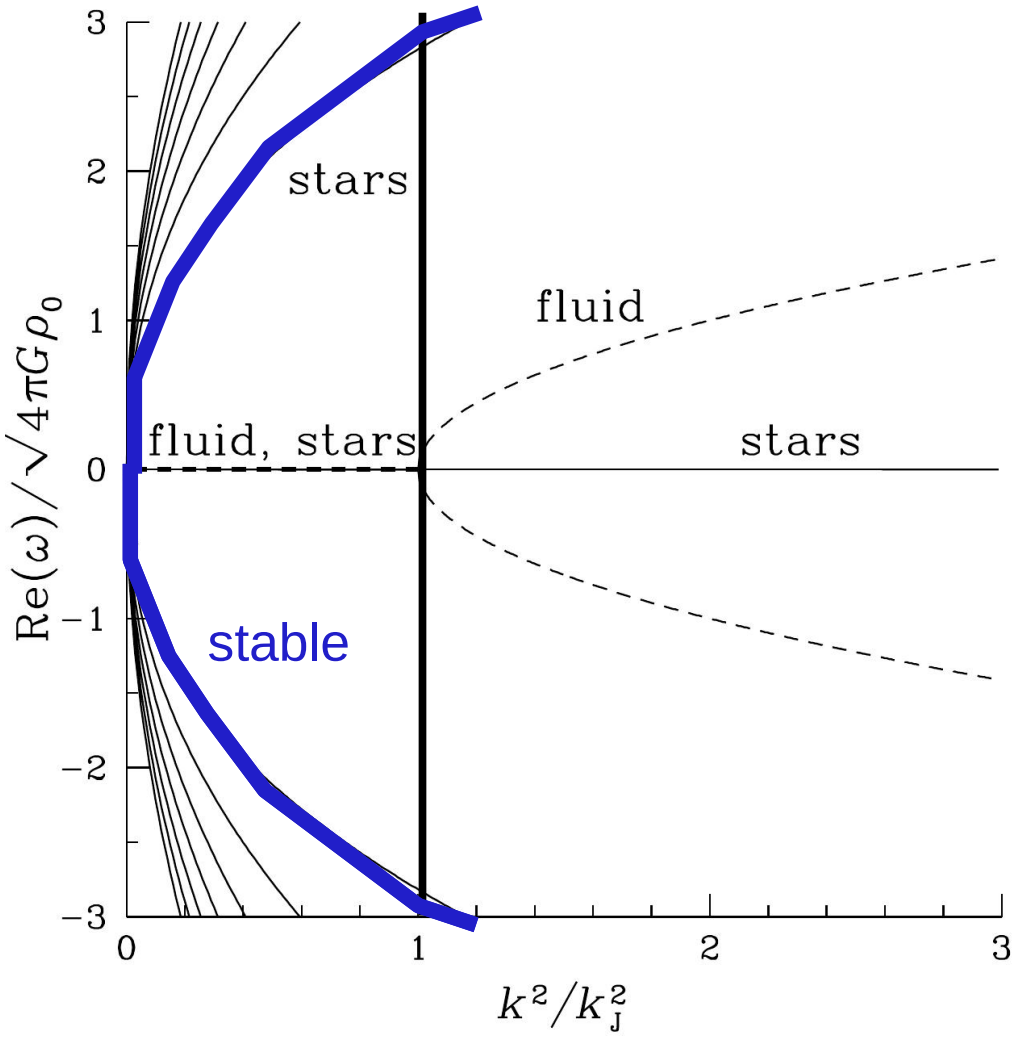
The dispersion relation for stellar systems

$$\frac{k^2}{k_J^2} = \omega^2 + \omega' \cdot \gamma(\omega')$$



The dispersion relation for stellar systems

$$\frac{k^2}{k_J^2} = \omega + \omega' \cdot \gamma(\omega')$$



Stability

$$\tilde{f} \sim e^{-i\omega t}$$

(A) Unstable

$$\text{Im}(\omega) > 0, \text{Re}(\omega) = 0$$



$$\underline{k^2 < k_J^2} \quad (\text{same than hydro})$$

(B) Stable

$$\text{Im}(\omega) = 0, \text{Re}(\omega) \neq 0$$

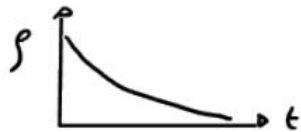


$$\underline{\omega = 0, k = k_J}$$

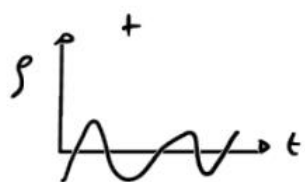
\Rightarrow no stable solution

(C) Damped

$$\text{Im}(\omega) < 0$$



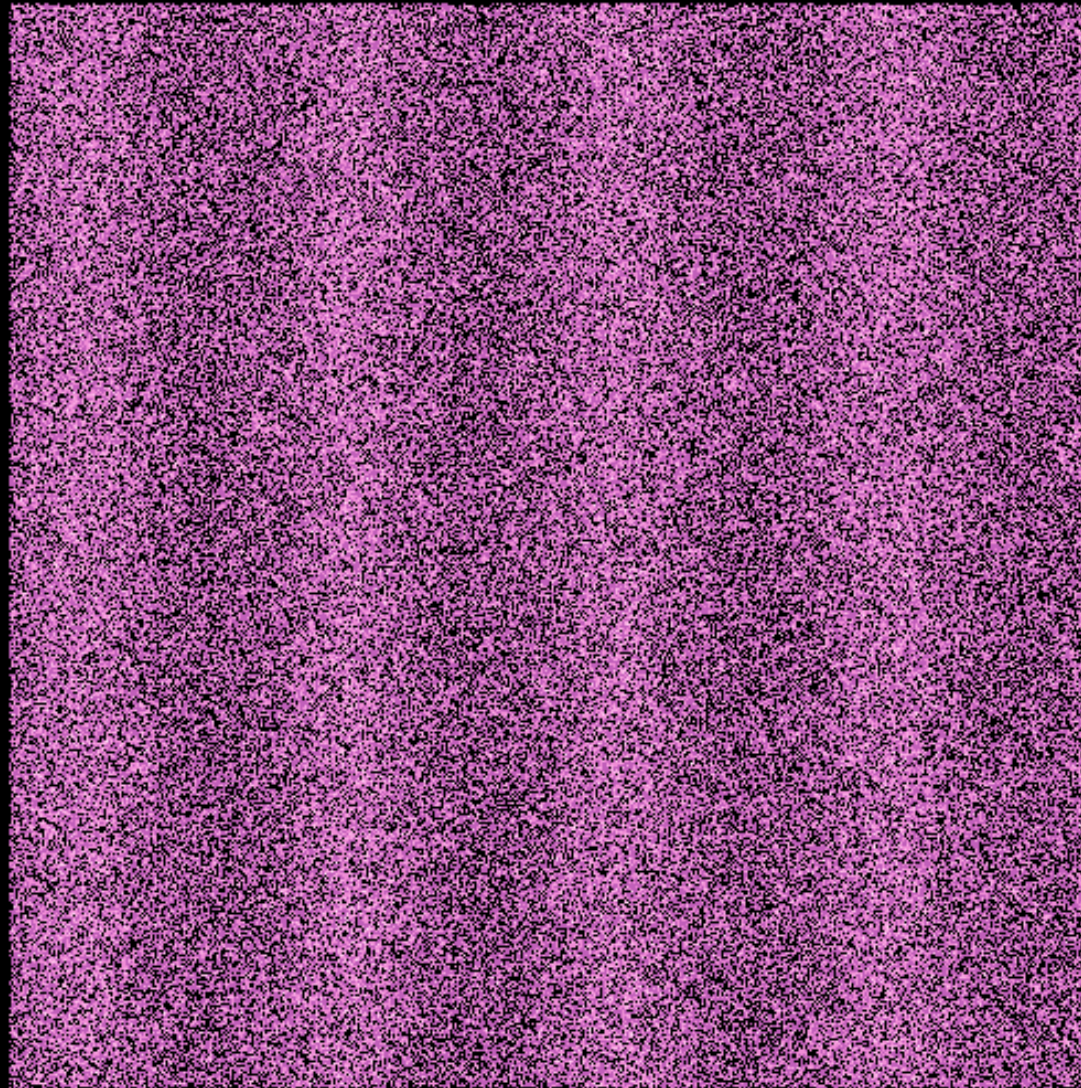
\rightarrow plenty of damped solutions



(with or without oscillation)

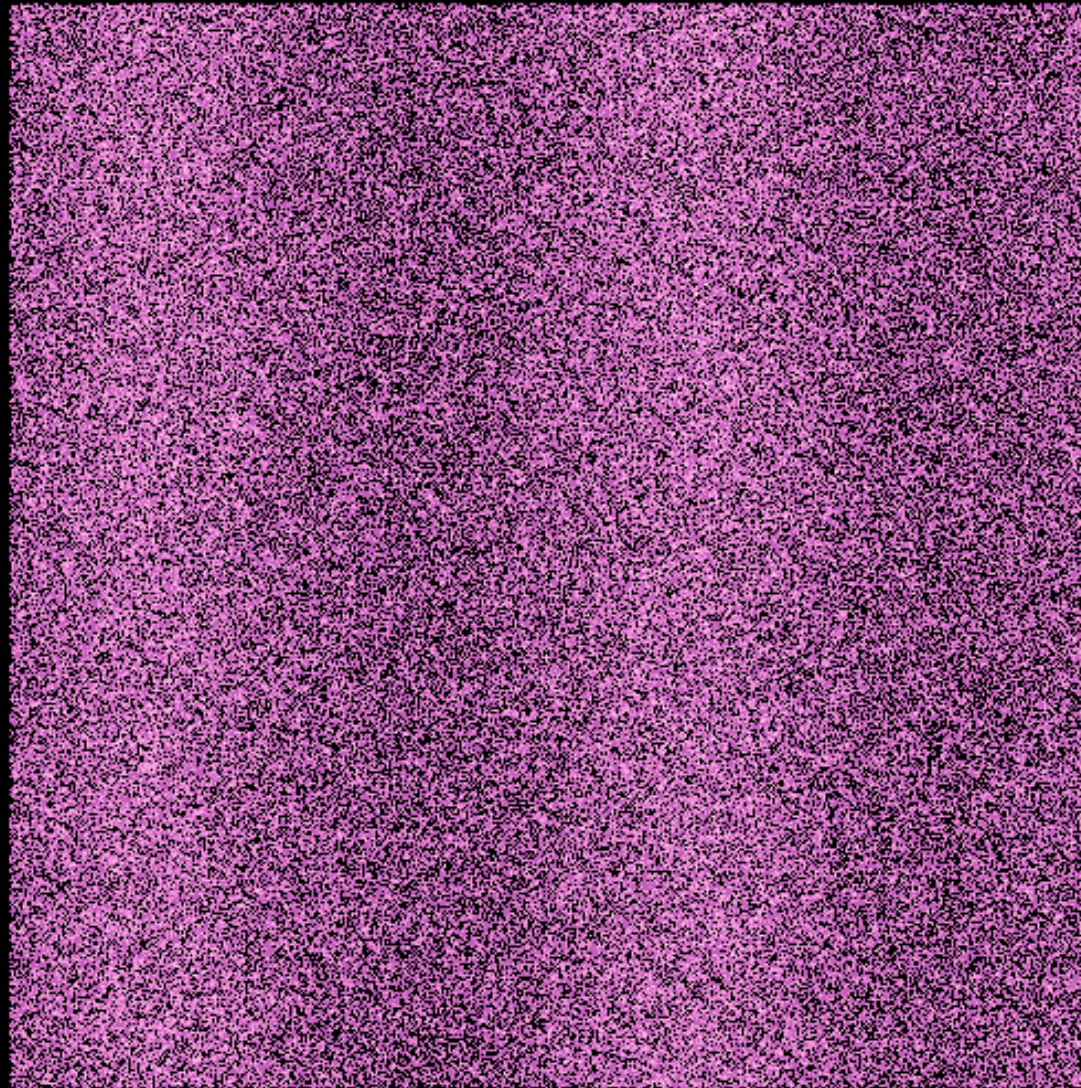
The Jeans instability in stellar systems

$$\lambda_J = 1.50 \quad \lambda = 0.25$$



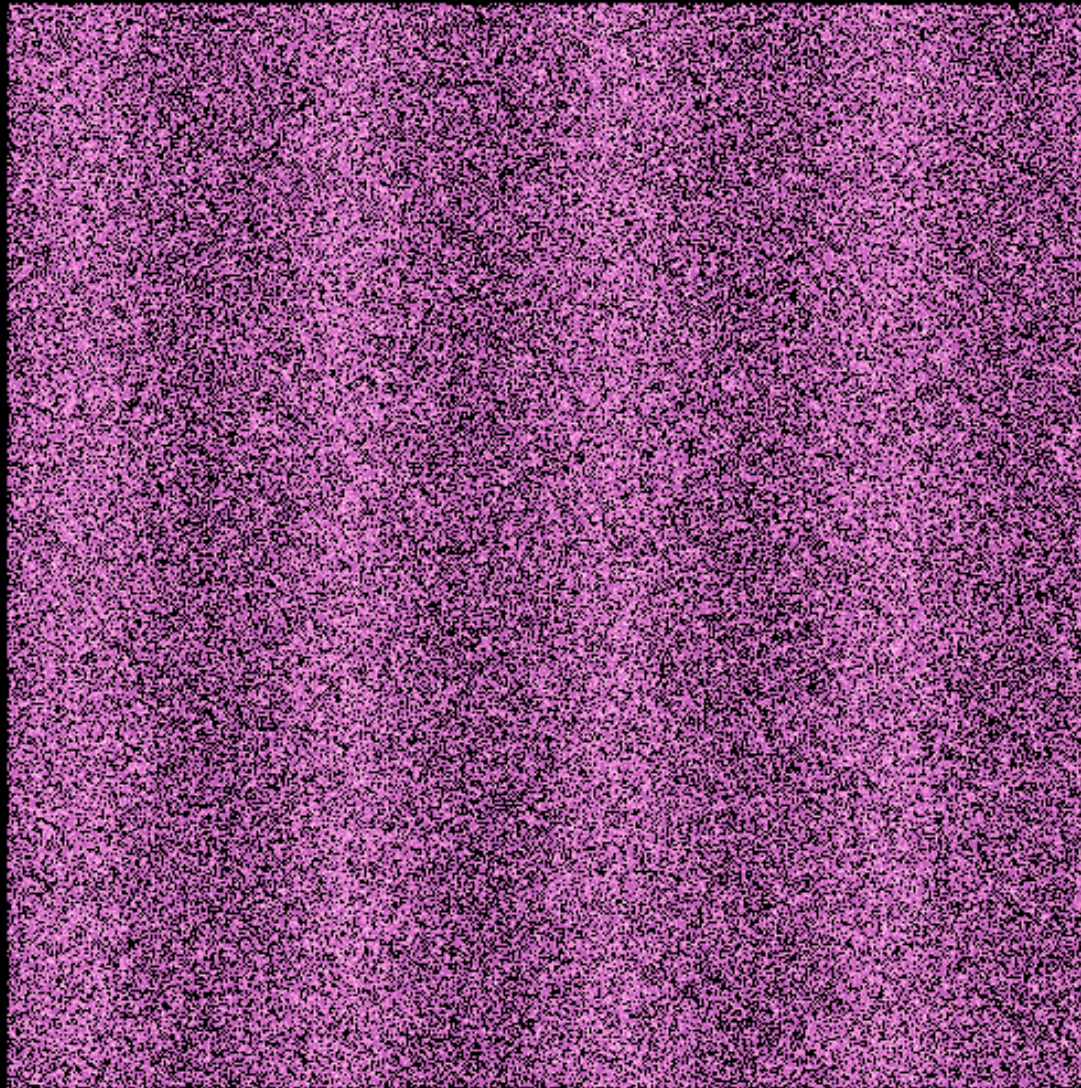
The Jeans instability in stellar systems

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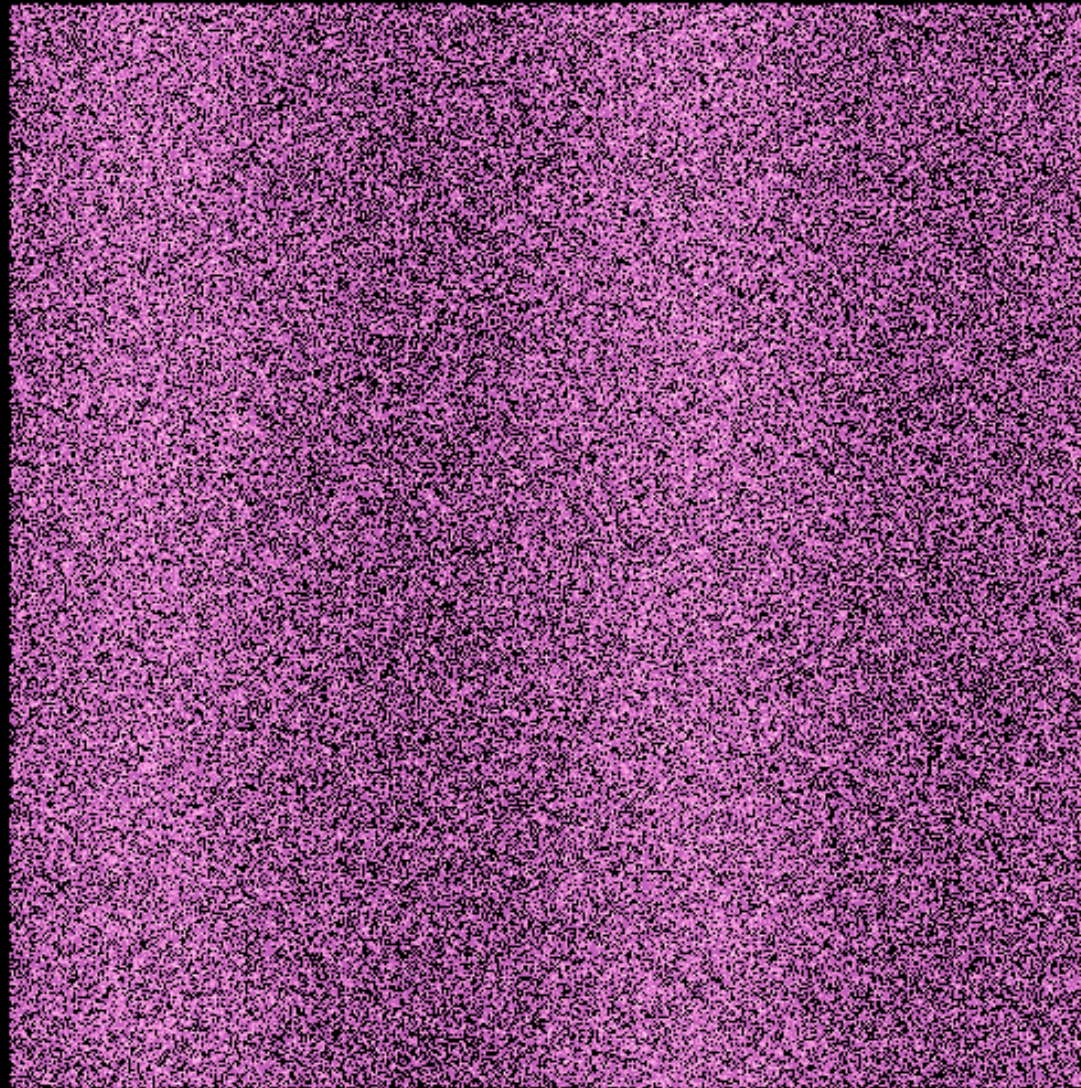
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The Jeans instability in stellar systems

$$\lambda_J = 0.25 \quad \lambda = 0.50$$



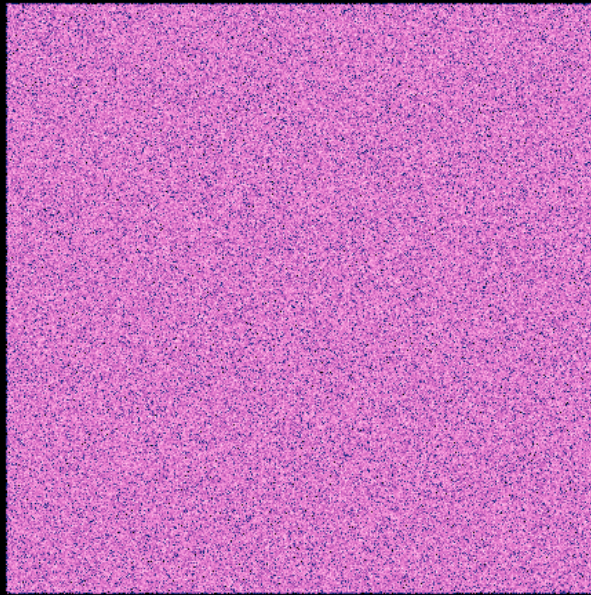
No perturbation : the instability is triggered by the noise due to the discretisation

$$\sigma = 0.1, r_J = 0.005$$

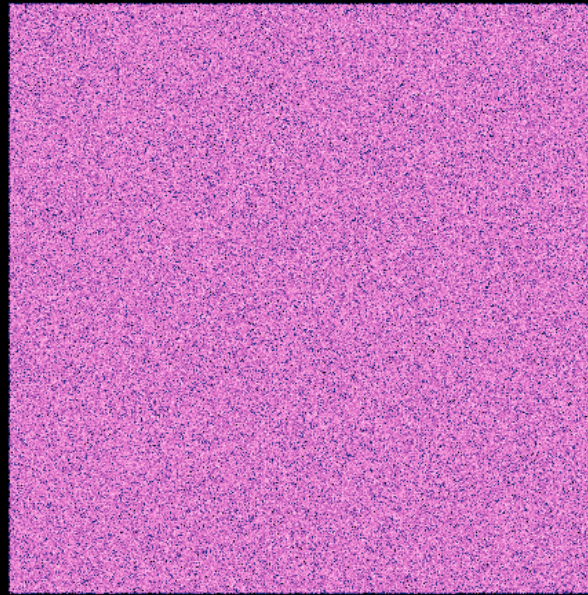
$$\sigma = 0.3, r_J = 0.05$$

$$\sigma = 0.7, r_J = 0.25$$

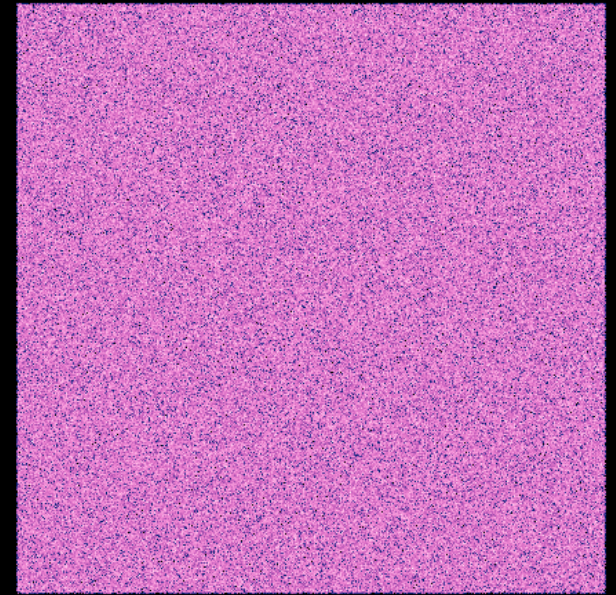
t = 0.00



rJ = 0.005



rJ = 0.05



rJ = 0.25

Landau damping

The existence of solutions with $\text{Im}(\omega) < 0$ is due to

$$\hat{f}_{S_1}(\vec{k}, \omega) = \left(-\frac{q n_0 G}{k^2} \int \frac{d^3 \vec{v}}{\boxed{\vec{k} \cdot \vec{v} - \omega}} \vec{k} \cdot \frac{\partial f_0}{\partial \vec{v}} \right) \left(\hat{f}_{S_1}(\vec{k}, \omega) + \hat{f}_e(\vec{k}, \omega) \right)$$

Wave in 1-D

$$f \sim f(kx - \omega t)$$



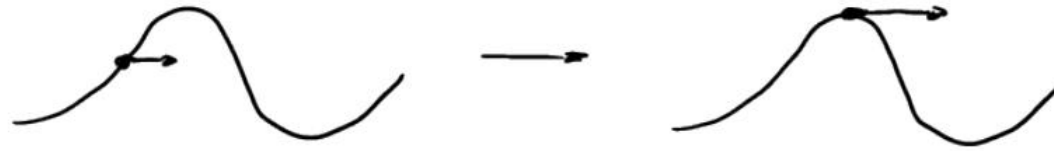
position / velocity of a static point with respect to the wave

$$x = \frac{\omega t}{k} + ck \quad v = \frac{\omega}{k} \quad \Rightarrow \quad \boxed{kv - \omega = 0}$$

\Rightarrow the integral diverges for particles moving at the same velocity than the wave

Interpretation: Density wave (perturbation) with a speed $v_w = \frac{\omega}{k}$

① if a particle with $v > v_w$ is trapped by the wave



\Rightarrow energy is **given** to the wave

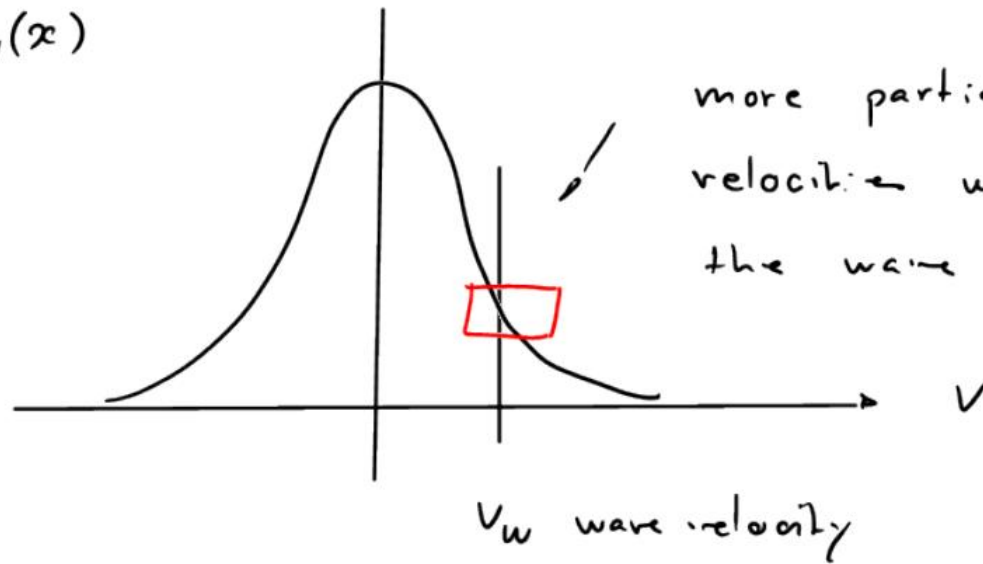
② if a particle with $v < v_w$ is trapped by the wave



\Rightarrow energy is **taken** from the wave

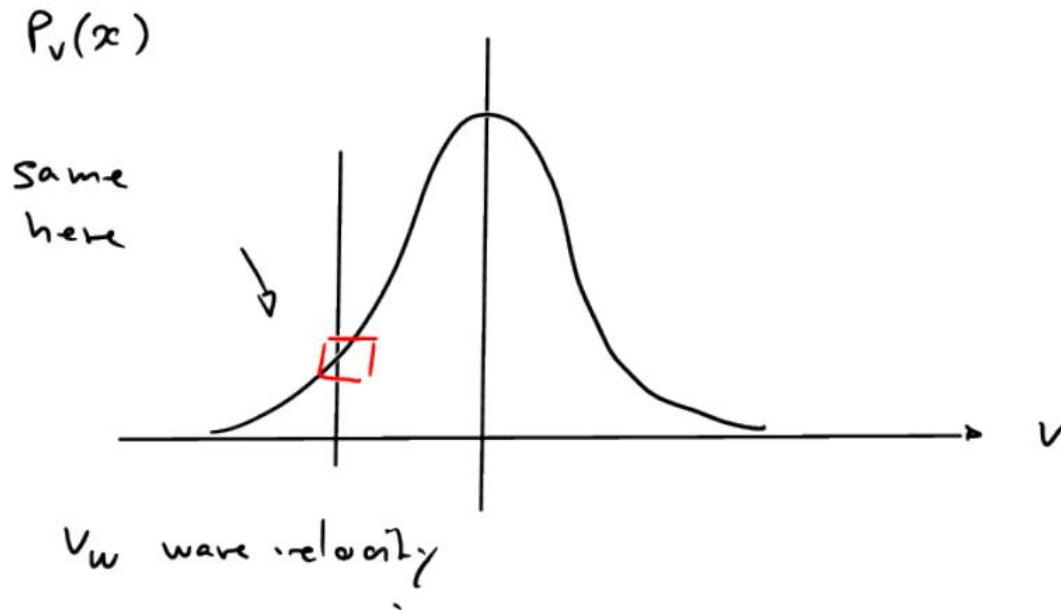
If the velocity distribution function is Maxwellian:

$P_v(x)$



LANDAU
DAMPING

$P_v(x)$



The End

Linear differential equations

$$f(x) : \frac{\partial^2 f}{\partial x^2} g_1(x) + \dots + \frac{\partial^3 f}{\partial x^3} g_2(x) + \frac{\partial f}{\partial x} g_3(x) + f(x) g_4(x) = c$$

$g_i(x)$: a continuous function

if f_1, f_2 are solutions $a f_1 + b f_2$ is a solution

Illustration

- 1-D continuity equation (f, v)

$$\frac{d}{dt} f + \underbrace{f \frac{\partial v}{\partial x} + v \frac{\partial f}{\partial x}} = 0$$

→ those terms mixes f and v

- 1-D linearized continuity equation (f_{s1}, v_1)

$$\frac{d}{dt} f_{s1} + f_0 \frac{\partial v_1}{\partial x} + v_0 \frac{\partial f_{s1}}{\partial x} = 0$$

→ no mixing