

Manifolds with boundary

Exercise 10.1. Let M be a smooth n -dimensional manifold with boundary, prove that $T_p M$ is an n -dimensional real vector space:

- First prove that $T_a \mathbb{H}^n \xrightarrow{d\iota} T_a \mathbb{R}^n$ is an isomorphism (using the fact that if f is a smooth function on \mathbb{H}^n then there exists an extension \tilde{f} to a smooth function on all \mathbb{R}^n ; look back at Exercise sheet 2 and 3)
- As we did in the case of smooth manifolds without boundary, prove that $T_p U \cong T_p M$ for each open U again using the Extension Lemma and then use smooth charts (Here, once again, remember what a smooth chart means in the case of a manifold with boundary)

Line integrals

Exercise 10.2. Let $M = \mathbb{R}^2 \setminus 0$ consider the 1-form

$$\omega = \frac{xdy - ydx}{x^2 + y^2}.$$

Let $\gamma: [0, 2\pi] \rightarrow M$ the smooth curve defined by $t \mapsto (\cos t, \sin t)$.

- Compute the integral of ω along γ
- Prove that omega is not exact, i.e. is not of the form dh for $h \in C^\infty(M)$

Exercise 10.3 (to hand in). Consider the following 1-form on $M = \mathbb{R}^3$:

$$\omega = \frac{-4zdx}{(x^2 + 1)^2} + \frac{2ydy}{y^2 + 1} + \frac{2xdz}{x^2 + 1}$$

- Set up and compute the line integral of ω along the line going from $(0, 0, 0)$ to $(1, 1, 1)$
- Consider the smooth map $\Psi: W \rightarrow \mathbb{R}^3$ given by $(r, \varphi, \theta) \in W := \mathbb{R}^+ \times (0, 2\pi) \times (0, \pi)$:

$$\Psi(r, \varphi, \theta) = (r \cos \varphi \sin \theta, r \sin \varphi \sin \theta, r \cos \theta) \in \mathbb{R}^3.$$

Compute $\Psi^* \omega$

Exercise 10.4. On the plane \mathbb{R}^2 with the standard coordinates (x, y) consider the 1-form $\theta = x dy$. Compute the integral of θ along each side of the square $[1, 2] \times [3, 4]$, with each of the two orientations. (There are 8 numbers to compute.)

Tensors

Exercise 10.5. Let $\mathcal{B} = (E_i)_i$ and $\tilde{\mathcal{B}} = (\tilde{E}_j)_j$ be two bases of a vector space $V \simeq \mathbb{R}^n$, and let $\mathcal{B}^* = (\varepsilon^i)_i$ and $\tilde{\mathcal{B}}^* = (\tilde{\varepsilon}^j)_j$ be the respective dual bases. Note that a tensor $T \in \text{Ten}^k V$ can be written as

$$T = \sum_{i_0, \dots, i_{k-1}} T_{i_0, \dots, i_{k-1}} \varepsilon^{i_0} \otimes \dots \otimes \varepsilon^{i_{k-1}} \quad \text{or as} \quad T = \sum_{j_0, \dots, j_{k-1}} \tilde{T}_{j_0, \dots, j_{k-1}} \tilde{\varepsilon}^{j_0} \otimes \dots \otimes \tilde{\varepsilon}^{j_{k-1}}.$$

Find the transformation law that expresses the coefficients $\tilde{T}_{j_0, \dots, j_{k-1}}$ in terms of the coefficients $T_{i_0, \dots, i_{k-1}}$.

Exercise 10.6 (Alternating covariant tensors). Let V be a finite-dimensional real vector space. Let $T \in \text{Ten}^k V$. Suppose that with respect to some basis ε^i of V^*

$$T = \sum_{1 \leq i_1, \dots, i_k < n} T_{i_1 \dots i_k} \varepsilon^{i_1} \otimes \dots \otimes \varepsilon^{i_k}.$$

Show that T is alternating iff:

- (a) for all $\sigma \in S_k$: $T_{i_{\sigma(1)} \dots i_{\sigma(k)}} = \text{sgn}(\sigma) T_{i_1 \dots i_k}$.
- (b) $T(\dots, X_s, \dots, X_t, \dots) = -T(\dots, X_s, \dots, X_t, \dots)$