# Nuclear Fusion and Plasma Physics - Exercises 

Prof. A. Fasoli - Swiss Plasma Center / EPFL
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## 1 Exercise 1-The frozen flux theorem

In what follows, please keep in mind that we use interchangeably the following notation for partial derivatives: $\partial_{t} \equiv \frac{\partial}{\partial t}, \partial_{l} \equiv \frac{\partial}{\partial l}$.
a) Ideal MHD equations

$$
\begin{align*}
& \partial_{t} \rho+\nabla \cdot(\rho \mathbf{u})=0  \tag{1}\\
& \rho\left[\partial_{t} \mathbf{u}+(\mathbf{u} \cdot \nabla) \mathbf{u}\right]=-\nabla p+\mathbf{j} \times \mathbf{B}  \tag{2}\\
& \nabla \cdot \mathbf{u}=0 \quad \text { State equation }  \tag{3}\\
& \nabla \times \mathbf{B}=\mu_{0} \mathbf{j}  \tag{4}\\
& \nabla \times \mathbf{E}=-\partial_{t} \mathbf{B}  \tag{5}\\
& \mathbf{E}+\mathbf{u} \times \mathbf{B}=0 \tag{6}
\end{align*}
$$

b) Magnetic Flux through a surface $S$ of closed contour $C$


$$
\begin{align*}
& \Phi=\int_{S} \mathbf{B} \cdot \mathbf{d} \mathbf{S}  \tag{7}\\
& \frac{d \Phi}{d t}=\frac{d}{d t} \int_{S} \mathbf{B} \cdot \mathbf{d S}  \tag{8}\\
& \frac{d \Phi}{d t}=\int_{S} \frac{\partial \mathbf{B}}{\partial t} \cdot \mathbf{d S}+\int_{S} \mathbf{B} \cdot \frac{d}{d t} \mathbf{d S} \tag{9}
\end{align*}
$$

We could put the time derivative into the surface integral because the temporal and spatial coordinates are independent.
c) Equation (9) shows that the variation of the magnetic flux can happen either by a change of $\mathbf{B}$ inside the closed surface or a variation of the enclosing surface. We can rewrite each term of the equation separately.
Starting from the first one and using Faraday's law, we can write.

$$
\begin{equation*}
\int_{S} \frac{\partial \mathbf{B}}{\partial t} \cdot \mathbf{d S}=-\int_{S}(\nabla \times \mathbf{E}) \cdot \mathbf{d S} \tag{10}
\end{equation*}
$$

We use the Stokes' theorem to express the surface integral in an integral over the contour $C$, delimiting the surface.

$$
\begin{equation*}
\int_{S} \frac{\partial \mathbf{B}}{\partial t} \cdot \mathbf{d S}=-\int_{S}(\nabla \times \mathbf{E}) \cdot \mathbf{d S}=-\oint \mathbf{E} \cdot \mathbf{d} \mathbf{l} \tag{11}
\end{equation*}
$$

The second term of equation (9) can be developed further by writing the time derivative of the surface element $\mathbf{d S}$ as a function of the fluid velocity $\mathbf{u}$.

$$
\begin{align*}
& \mathrm{d} \mathbf{S}=\mathbf{u} d t \times \mathrm{d} \mathbf{l}  \tag{12}\\
& \int_{S} \mathbf{B} \cdot \frac{d}{d t} \mathbf{d} \mathbf{S}=\oint \mathbf{B} \cdot(\mathbf{u} \times \mathrm{d} \mathbf{l}) \tag{13}
\end{align*}
$$

Putting together the two contributions yields:

$$
\begin{align*}
& \frac{d \Phi}{d t}=-\oint_{C} \mathbf{E} \cdot \mathbf{d} \mathbf{l}+\oint_{C} \mathbf{B} \cdot(\mathbf{u} \times \mathrm{d} \mathbf{l})  \tag{14}\\
& \frac{d \Phi}{d t}=-\oint_{C}(\mathbf{E}+\mathbf{u} \times \mathbf{B}) \cdot \mathbf{d} \mathbf{l} \tag{15}
\end{align*}
$$

Equation (15) has been obtained rearranging the terms in the second integral of (14) and combining the two integrals. From the ideal ohm's law, if follows that $\mathbf{E}+\mathbf{u} \times \mathbf{B}=\mathbf{0} \Rightarrow \frac{\mathrm{d} \Phi}{\mathrm{dt}}=\mathbf{0}$.

## Exercise 2-Cylindrical equilibrium

a) Given that

$$
\mathbf{B}=B_{0} \hat{\mathbf{z}}, \quad p=p_{0} \cos ^{2}\left(\frac{\pi r}{2 a}\right)
$$

the MHD equilibrium is written as

$$
\begin{aligned}
\mathbf{J} \times \mathbf{B} & =\nabla p \\
\nabla \times \mathbf{B} & =\mu_{0} \mathbf{J}
\end{aligned}
$$

Combining these expressions:

$$
\begin{aligned}
& \nabla p=\frac{1}{\mu_{0}}(\nabla \times \mathbf{B}) \times \mathbf{B}=\frac{1}{\mu_{0}}\left[-\nabla \frac{B^{2}}{2}+(\mathbf{B} \cdot \nabla) \mathbf{B}\right] \\
& \nabla\left[p+\frac{B^{2}}{2 \mu_{0}}\right]=\frac{1}{\mu_{0}}(\mathbf{B} \cdot \nabla) \mathbf{B}=\frac{\mathbf{B}}{\mu_{0}}(\hat{\mathbf{b}} \cdot \nabla)(\mathbf{B} \hat{\mathbf{b}}) \\
&=\frac{B^{2}}{\mu_{0}}(\hat{\mathbf{b}} \cdot \nabla) \hat{\mathbf{b}}+\hat{\mathbf{b}}(\hat{\mathbf{b}} \cdot \nabla) \frac{B^{2}}{2 \mu_{0}}
\end{aligned}
$$

The first term corresponds to the bending force of the $B$ field. The second term corresponds to the compression of the field.
In the case of straight and parallel field lines, the two terms on the right hand side are zero, so

$$
p(r)+\frac{B_{z}^{2}}{2 \mu_{0}}=p(a)+\frac{B_{z}^{2}(a)}{2 \mu_{0}}=\frac{B_{0}^{2}}{2 \mu_{0}} \quad(p(a)=0)
$$

So the maximum $p(r)$ would occur for $B_{z}(r)=0$ and will have a value $p_{0, \max }=\frac{B_{0}^{2}}{2 \mu}$.
b)

$$
\begin{aligned}
B_{z}^{2} & =B_{0}^{2}-2 \mu_{0} p_{0} \cos ^{2}\left(\frac{\pi r}{2 a}\right) \\
& =B_{0}^{2}\left[1-\cos ^{2}\left(\frac{\pi r}{2 a}\right)\right] \\
\mathbf{B} & =B_{0} \sin \left(\frac{\pi r}{2 a}\right) \hat{\mathbf{z}} \\
\mathbf{J}=\frac{1}{\mu_{0}} \nabla \times \mathbf{B}= & \frac{1}{\mu_{0}}\left(-\frac{\partial B_{z}}{\partial r}\right) \hat{\theta}=\frac{-\pi B_{0}}{2 \mu_{0} a} \cos \left(\frac{\pi r}{2 a}\right) \hat{\theta}
\end{aligned}
$$



