


Continue on basic defs for tensors.

- As multidimensional arrays of numbers

$$T^{\alpha\beta\gamma} \in \mathbb{R}^{I_1} \times \mathbb{R}^{I_2} \times \mathbb{R}^{I_3}$$

order $p = 3$

- Mathematical def is as follows: a tensor

is a multilinear transformation acting on

vectors; Take for example 3 vectors $\underline{x}, \underline{y}, \underline{z}$

$$\underline{x} \in \mathbb{R}^{I_1}, \underline{y} \in \mathbb{R}^{I_2}, \underline{z} \in \mathbb{R}^{I_3};$$

$$\sum_{\alpha, \beta, \gamma} T^{\alpha\beta\gamma} x^\alpha y^\beta z^\gamma \equiv T(\underline{x}, \underline{y}, \underline{z})$$

\leftarrow scalar $\in \mathbb{R}$.

This expression is linear separately in \underline{x} ,

in \underline{y} , in \underline{z} $\Rightarrow T(d\underline{x}, \mu\underline{y}, \rho\underline{z})$

$= d\mu\rho T(\underline{x}, \underline{y}, \underline{z})$.

(T is Multilinear transformation).

$$[\mathbb{T}(\mathbb{I}, \underline{y}, \underline{z})]^\alpha = \sum_{\beta, \gamma} T^{\alpha\beta\gamma} \underline{y}^\beta \underline{z}^\gamma$$

identity matrix $\underline{y}, \underline{z}$ is a vector $\in \mathbb{R}^{\mathbb{I}_1}$.

$\mathbb{T}(\mathbb{I}, \underline{y}, \underline{z})$ is bilinear expression

$$[\mathbb{T}(\underline{x}, \mathbb{I}, \underline{z})]^\beta = \sum_{\alpha, \gamma} T^{\alpha\beta\gamma} x^\alpha \underline{z}^\gamma$$

bilinear in \underline{x} & \underline{z} . a vector $\in \mathbb{R}^{\mathbb{I}_2}$

$$[\mathbb{T}(\underline{x}, \mathbb{I}, \mathbb{I})]^\beta = \sum_{\alpha} T^{\alpha\beta\gamma} x^\alpha$$

linear expression in \underline{x}

it is a matrix $\in \mathbb{R}^{\mathbb{I}_2} \times \mathbb{R}^{\mathbb{I}_3}$

$$[\mathbb{T}(\underline{M}_1, \underline{M}_2, \underline{M}_3)]^{\alpha\beta\gamma} = \sum_{\alpha\beta\gamma} T^{\alpha\beta\gamma} M_1^\alpha M_2^\beta M_3^\gamma$$

3 matrices

obtain trilinear in $\underline{M}_1, \underline{M}_2, \underline{M}_3$ and

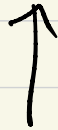
is a tensor

Form these multilinear expressions to obtain $\begin{cases} \text{scalars} \\ \text{vectors} \\ \text{matrices} \\ \text{tensors} \end{cases}$

- Study of such transformations is called "Multilinear algebra".

3) Tensor product of vectors.

4) Notion tensor Rank.



important metrics in
multilinear algebra.

3) Tensor product of vectors.

also called "outer product".

- $\underline{a} \in \mathbb{R}^{I_1}$, $\underline{b} \in \mathbb{R}^{I_2}$ and form the $\underline{a} \otimes \underline{b} \in \mathbb{R}^{I_1} \times \mathbb{R}^{I_2}$ with components $(\underline{a} \otimes \underline{b})^{\alpha\beta} \equiv \underbrace{a^\alpha b^\beta}_{I_1 \times I_2 \text{ matrix.}}$

- $\underline{a} \in \mathbb{R}^{I_1}$, $\underline{b} \in \mathbb{R}^{I_2}$, $\underline{c} \in \mathbb{R}^{I_3}$
 $\underline{a} \otimes \underline{b} \otimes \underline{c} \in \mathbb{R}^{I_1} \times \mathbb{R}^{I_2} \times \mathbb{R}^{I_3}$ with components $(\underline{a} \otimes \underline{b} \otimes \underline{c})^{\alpha\beta\gamma} \equiv \underbrace{a^\alpha b^\beta c^\gamma}_{I_1 \times I_2 \times I_3 \text{ tensor of order 3 (3-mode, 3 way).}}$

- Generalize to any p .

Remark

$\underline{a} \otimes \underline{b} = \underline{a} \underline{b}^T$ (column \times line) $\in \mathbb{R}^{I_1} \times \mathbb{R}^{I_2}$.
Not to confuse with "inner or scalar product" $\underline{a}^T \cdot \underline{b} \in \mathbb{R}$.

• Tensor product of matrices:

$$M \text{ with components } M^{\alpha\beta} \in \mathbb{R}^{I_1} \times \mathbb{R}^{I_2}$$

$$N \text{ " " " } N^{\gamma\delta} \in \mathbb{R}^{I_3} \times \mathbb{R}^{I_4}$$

$M \otimes N$ is the tensor with components

$$(M \otimes N)^{\alpha\beta\gamma\delta} = M^{\alpha\beta} N^{\gamma\delta}$$

{ 4-mode tensor in $\mathbb{R}^{I_1} \times \mathbb{R}^{I_2} \times \mathbb{R}^{I_3} \times \mathbb{R}^{I_4}$.
 4-dim array of numbers. (hypercube).

#

Notation: sometimes in review or refs
 (More on the web page)

$$\otimes \rightarrow \odot$$

↑

preferred for us.
 & in math literature.

Later in class other products

Kronecker product
 Khatri-Rao product
 Hadamard product.

Will be defined as we go on.

4) Tensor Rank.

For two vectors \underline{a} & $\underline{b} \rightarrow \underline{a} \otimes \underline{b} = \underline{a} \underline{b}^T$.
rank-one matrix.

By analogy we say that


def of Rank one tensors

$\underline{a} \otimes \underline{b} \otimes \underline{c}$ is a rank one tensor / order 3

$\underline{a} \otimes \underline{b} \otimes \underline{c} \otimes \underline{d}$ is a rank one tensor / order 4.

etc.

If I give you an array of numbers $T^{\alpha\beta\gamma}$

$T =$  it is always possible to represent

$$T = \sum_i \underline{a}_i \otimes \underline{b}_i \otimes \underline{c}_i \quad \leftarrow \text{decomposition of a tensor.}$$

where $\underline{a}_i, \underline{b}_i, \underline{c}_i$ are vectors if I allow
sufficiently many terms.

Definition of the rank of a tensor.

The rank of a tensor of order p is the minimal ^{possible} number of terms in

decomposables, of the form (rank one tensors in the sum).

$$\mathbb{T} = \sum_{i=1}^R \underline{a}_i^{(1)} \otimes \underline{a}_i^{(2)} \otimes \dots \otimes \underline{a}_i^{(p)}$$

order p : p -terms \otimes products.

R : rank if this is the minimal number of terms possible in the sum.

Each term of the sum is a rank-one tensor.

Remarks.

a) For matrices this defn is equivalent to the usual rank defined as the
 $\dim(\text{column span}) = \dim(\text{row span})$.

b) For tensors we do not have such a universal equiv definition. Many notions of rank.

Def introduced before: is called "Tensor Rank"

(Later we will also introduce other notions of rank.)

c) For tensors it is non-trivial to compute the Rank \rightarrow will be discussed next time.

d) For Matrices universal algo to compute the rank is SVD \rightarrow # of non zero sing values.
but for tensors No such systematic method.

END OF LECT 1.