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# Tensor Factorisation Methods.

popular also Alternating Least Squares

Method.

- Main ideas for today:

Tensor  $T \in \mathbb{R}^{I_1 \times I_2 \times I_3}$

→

Matrix representation  
or display of  
the tensor

highly non  
unique &  
we will have to  
use simultaneously  
3 such representations.  
||  
order of the tensor.

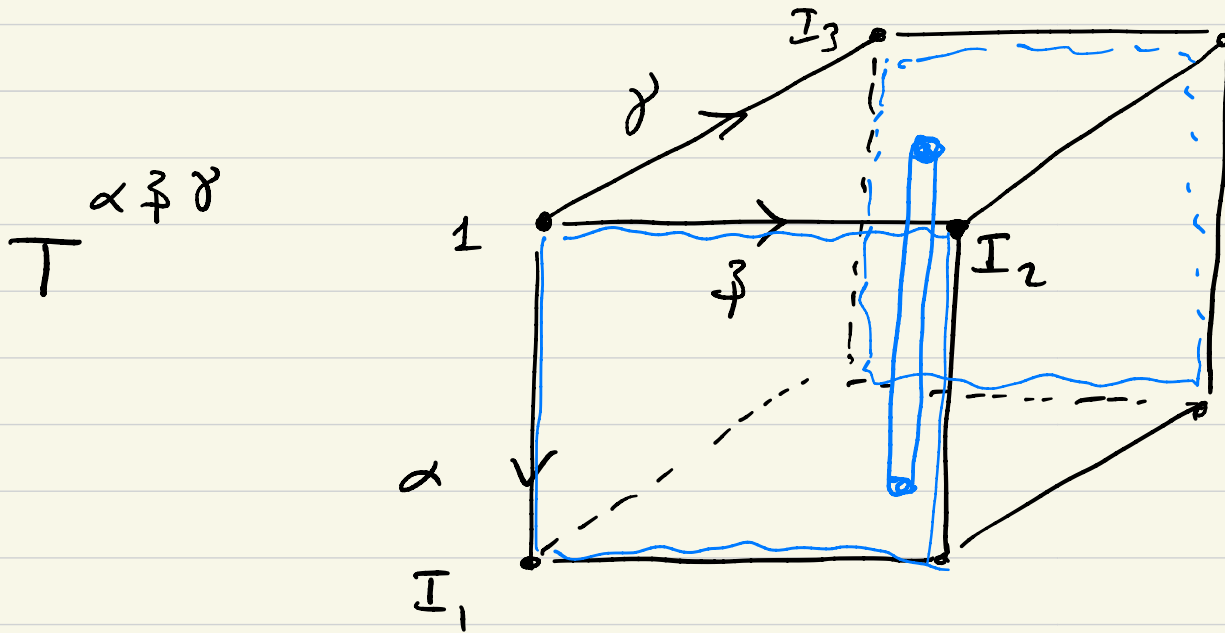
apply lin alg  
methods / here  
apply least squares  
methodology.

1) Look at Matricisations of a Tensor.

2) Introduce useful products ( Kronecker product  
Khatri-Rao product  
Hadamard product )

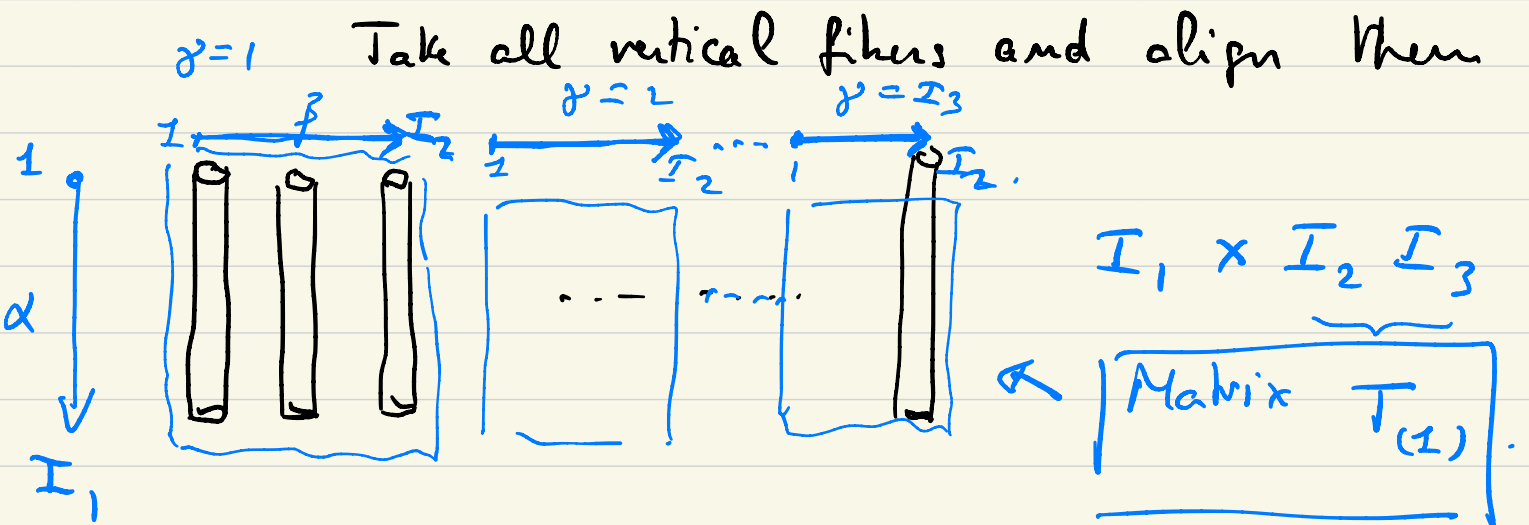
3) ALS algorithm.

1) Matrixisations of an order 3 tensor.

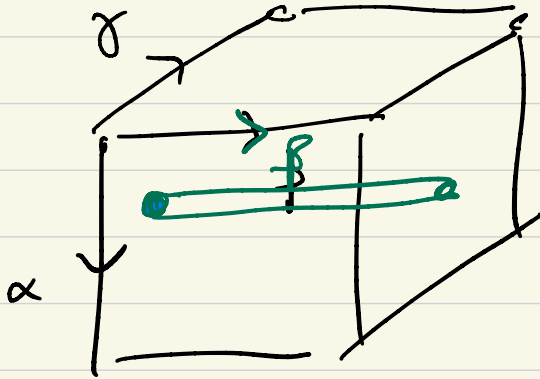



3 Matrix representations of T:  $T_{(1)}, T_{(2)}, T_{(3)}$

- first matrix  $T_{(1)}$ :  $\left( T \cdot \beta \gamma \right)_{\alpha=1 \dots I_3}$   
 for  $\beta \gamma$  fixed vector called a "fiber".

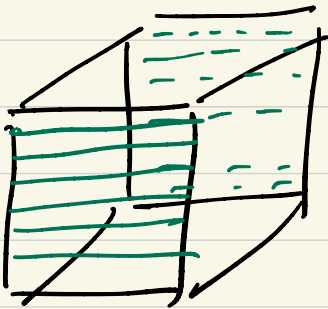
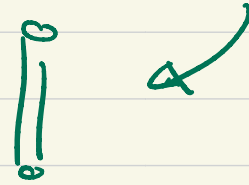


• secunde Matrix  $T_{(2)}$  :  $\left( \begin{array}{c} \alpha \cdot \delta \\ \beta \end{array} \right)_{\beta=1 \dots I_2}$   
 "fiber" or "recta"



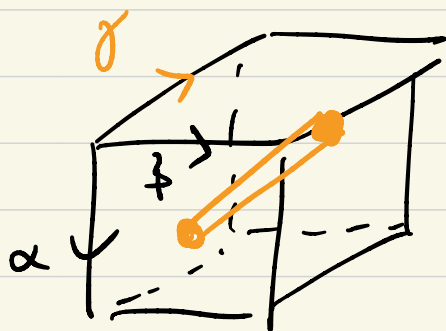
horizontal fiber. 

align all horizontal fiber



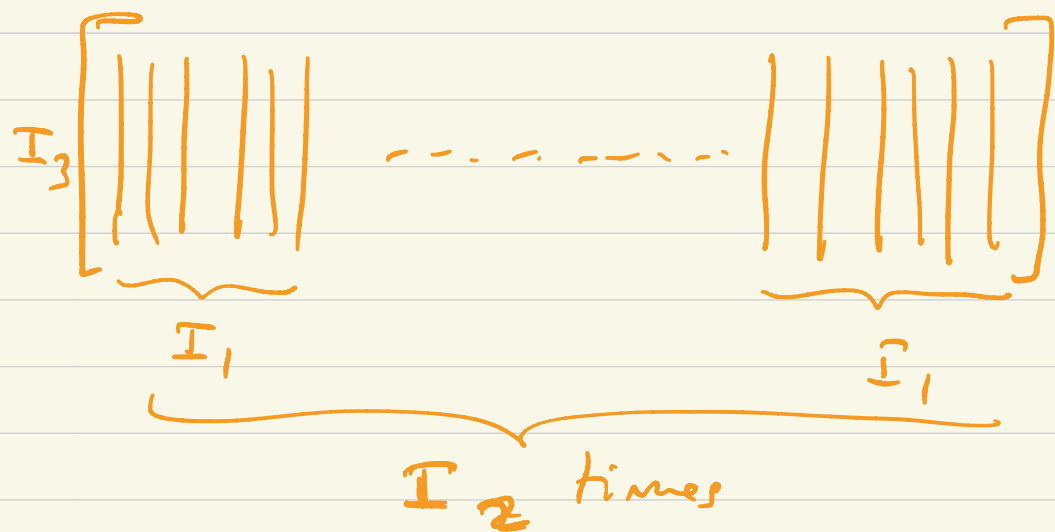
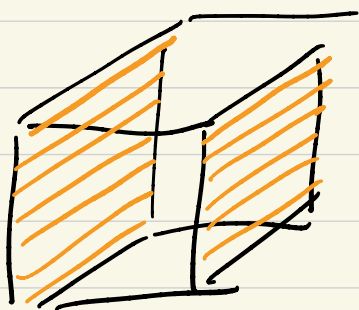
$$I_2 \left[ \underbrace{\left[ \begin{array}{c} | \\ | \\ | \\ | \end{array} \right]}_{\substack{I_1 \\ 1}} \dots \underbrace{\left[ \begin{array}{c} | \\ | \\ | \\ | \end{array} \right]}_{\substack{I_1 \\ I_3}} \right] = T_{(2)} : \begin{array}{l} I_2 \times I_1 I_3 \\ \text{Matrix} \end{array}$$

• Third Metricizer  $T_{(3)}$   $\left( T^{\alpha \beta} \right)_{\beta=1 \dots I_3}$



fiber with  $I_3$  components  
along the depth.

and you align them again



$$= T_{(3)}$$

Matrix with  
dimensions

$$I_3 \times I_1, I_2$$

We will have to understand how to write down Metricization in a more analytic way.  $\rightarrow$  Necessary to use some concepts

related to tensor product  $\otimes$

New products:

a) Kronecker product  $\otimes_{Kro}$

b) Khatri-Rao product  $\otimes_{Khr}$

c) Hadamard . \*

Remark about notation: often  $\otimes$  is denoted  $\odot$   
tensor prod

and  $\otimes_{Kro}$  is denoted by  $\otimes$

(this is the case ~~for~~ the review on the web page of class)

a) Kronecker Product:  $\underline{c}$  &  $\underline{b}$  two column vectors.

$\uparrow$   $\uparrow$   
 dim  $I_3$   $I_2$

$$\underbrace{\underline{c} \otimes_{\text{kro}} \underline{b}}_{\text{Kro pr of two columns}} = \begin{bmatrix} c^1 \\ \vdots \\ c^{I_3} \end{bmatrix} \otimes_{\text{kro}} \begin{bmatrix} b^1 \\ \vdots \\ b^{I_2} \end{bmatrix} \equiv \begin{bmatrix} c^1 \underline{b} \\ c^2 \underline{b} \\ \vdots \\ c^{I_3} \underline{b} \end{bmatrix}$$

$\uparrow$   
 column vector of dim  $I_3 I_2$

(Remember  $\underline{c} \otimes \underline{b}$  is a matrix // list of components in  $\underline{c} \otimes \underline{b}$  and  $\underline{c} \otimes_{\text{kro}} \underline{b}$  is the same might say  $\underline{c} \otimes_{\text{kro}} \underline{b}$  is a "vectorisation" of  $\underline{c} \otimes \underline{b}$ ).

Two properties:

- $(\underline{c} \otimes_{\text{kro}} \underline{b})^T = [c^1 \underline{b}^T, \dots, c^{I_3} \underline{b}^T] \equiv \underbrace{\underline{c}^T \otimes_{\text{kro}} \underline{b}^T}_{\text{Kro pr of lines}}$
- $(\underline{e} \otimes_{\text{kro}} \underline{d})^T \cdot (\underline{c} \otimes_{\text{kro}} \underline{b}) = (\underbrace{\underline{e}^T \cdot \underline{c}}_{\text{scalar pr}}) (\underbrace{\underline{d}^T \cdot \underline{b}}_{\text{Prove this!}}) \checkmark$

## b) Khatri-Rao product

$$C = [ \underline{c}_1 \ \dots \ \underline{c}_R ] \quad \mathbb{I}_3 \times R \text{ matrix}$$

$$B = [ \underline{b}_1 \ \dots \ \underline{b}_R ] \quad \mathbb{I}_3 \times R \text{ matrix}$$

$$C \otimes_{\text{Khr}} B = [ \underline{c}_1 \otimes_{\text{Khr}} \underline{b}_1 ; \underline{c}_2 \otimes_{\text{Khr}} \underline{b}_2 ; \dots ; \underline{c}_R \otimes_{\text{Khr}} \underline{b}_R ]$$

$\mathbb{I}_2 \mathbb{I}_3 \times R$  matrix.

## c) Hadamard product

A & B two matrices  $(A * B)_{ij} = A_{ij} B_{ij}$ .

$$\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} * \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix} = \begin{pmatrix} a_{11} b_{11} & a_{12} b_{12} \\ a_{21} b_{21} & a_{22} b_{22} \end{pmatrix}.$$

#.

Property (exercise)

$$(E \otimes_{\text{Khr}} D)^T (C \otimes_{\text{Khr}} B) = (E^T C) * (D^T B)$$

useful identity to make calculations!



Let us here recall something that was proved in the exercise session:

Lemma: Let  $C$  and  $B$  have full column rank (all columns of  $C$  are lin indep, idem for columns of  $B$ ).

Then  $C \otimes_{K \times R} B$  is also full column rank.

i.e.  $\underline{c}_1 \otimes_{K \times R} \underline{b}_1 ; \underline{c}_2 \otimes_{K \times R} \underline{b}_2 ; \dots ; \underline{c}_R \otimes_{K \times R} \underline{b}_R$ .

This will be used also for the ALS algorithm.

Last tool missing is write down some analytic

expressions for Minimization of  $\underline{a} \otimes \underline{b} \otimes \underline{c}$

and  $\sum_{k=1}^R \underline{a}_k \otimes \underline{b}_k \otimes \underline{c}_k$ . ?