

# Stability of collisionless systems

2<sup>nd</sup> part

# Outlines

## Linear response theory

- in fluid systems
- in stellar systems

## The Jeans instability

- in fluid systems
- in stellar systems

Our goal      Study the stability of systems  
at equilibrium

Method :      perturbation theory

perturbation       $\rightarrow$       response

Types of responses

- Exponential growth of the perturbation
- Oscillation of the perturbation
- Die of the perturbation



**Stability of collisionless systems**

**Linear response theory**

# Linear response theory

Study the perturbation of system at the equilibrium

Perturbation: external gravitational field  $-\varepsilon \vec{\nabla} \phi_e$  :  $|\vec{\nabla} \phi_e| \sim |\vec{\nabla} \phi_0|$

stellar/system  
at equilibrium



$$\rho_{s_0}(x)$$

$$\phi_{s_0}(x)$$

$$\nabla^2 \phi_{s_0} = 4\pi G \rho_{s_0}$$

external  
perturbation



$$\varepsilon \rho_e(x)$$

$$\varepsilon \phi_e(x)$$

$$\nabla^2 \phi_e = 4\pi G \rho_e$$



stellar/fluid  
responses  
linearly



$$\rho_s = \rho_{s_0} + \varepsilon \rho_{s_1}$$

$$\phi_s = \phi_{s_0} + \varepsilon \phi_{s_1}$$

$$\nabla^2 \phi_s = 4\pi G \rho_s$$

$$\nabla^2 \phi_{s_1} = 4\pi G \rho_{s_1}$$

total stellar/fluid  
linear response



$$\begin{aligned} \rho_{tot} &= \rho_{s_0} + \varepsilon \rho_{s_1} + \varepsilon \rho_e \\ &= \rho_{s_0} + \varepsilon \rho_1 \end{aligned}$$

$$\begin{aligned} \phi_{tot} &= \phi_{s_0} + \varepsilon \phi_{s_1} + \varepsilon \phi_e \\ &= \phi_{s_0} + \varepsilon \phi_1 \end{aligned}$$

$$\nabla^2 \phi_1 = 4\pi G \rho_1$$

$$\nabla^2 \phi_{tot} = 4\pi G \rho_{tot}$$

Conventions :  $\rho_{s_0} = \rho_0$   $\phi_{s_0} = \phi_0$   $\rho_{tot} = \rho$   $\phi_{tot} = \phi$

# Linearized equations for a self-gravitating system

Self-gravitating fluid

$\rho(\vec{x}, t)$   $\phi(\vec{x}, t)$   $p(\vec{x}, t)$   $\vec{v}(\vec{x}, t)$

6 Equ.  
6 Unkn.

① Continuity Equation

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{v}) = 0$$

③ The Poisson Equation

$$\nabla^2 \phi = 4\pi G \rho$$

② Euler Equation

$$\frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \vec{\nabla}) \vec{v} = - \frac{\vec{\nabla} p}{\rho} - \vec{\nabla} \phi$$

④ Equation of state (barotropic)

$$p(\vec{x}, t) = p(\rho(\vec{x}, t))$$

Self-gravitating stellar system

$f(\vec{x}, \vec{v}, t)$ ,  $\rho(\vec{x}, t)$ ,  $\phi(\vec{x}, t)$

3 Equ  
3 Unkn.

① The collisionless Boltzmann Equation

$$\frac{\partial f}{\partial t} + \vec{v} \cdot \frac{\partial f}{\partial \vec{x}} - \frac{\partial \phi}{\partial \vec{x}} \cdot \frac{\partial f}{\partial \vec{v}} = 0$$

$$= \frac{\partial f}{\partial t} + [f, \mathcal{H}] = 0$$

② The Poisson Equation

$$\nabla^2 \phi = 4\pi G \rho = 4\pi G \int d^3v f(\vec{x}, \vec{v}, t)$$

## Linearizing equations

Goal: describe the response of the system (without the perturbation)

$$f_s(\tilde{x}, t) = f_{s0}(\tilde{x}) + \varepsilon f_{s1}(\tilde{x}, t) \quad \phi_s \quad \tilde{v}_s \quad p_s \quad f_s$$

- ① Equations for  $f_s(\tilde{x}, t)$
- ② Equations for  $f_{s0}(\tilde{x})$  (system at equilibrium)
- ③ Keep only first order terms ( $\varepsilon^2 \rightarrow 0$ )

linear differential equations for  $f_{s1}$   $\phi_{s1} \quad \tilde{v}_{s1} \quad p_{s1} \quad f_{s1}$

# Linearized Equations for a self-gravitating fluid

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Equations for a self-gravitating fluid (we follow only the system, without the perturbation)

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System of density  $\rho_s(\vec{x}, t)$   $\phi_s(\vec{x}, t)$   $\vec{v}_s(\vec{x}, t)$   $p_s(\vec{x}, t)$

① Continuity Equation

$$\frac{\partial \rho_s}{\partial t} + \vec{\nabla} \cdot (\rho_s \vec{v}_s) = 0$$

total potential  $\phi = \phi_s + \epsilon \phi_e$

② Euler Equation

$$\frac{\partial \vec{v}_s}{\partial t} + (\vec{v}_s \cdot \vec{\nabla}) \vec{v}_s = - \frac{\vec{\nabla} p_s}{\rho_s} - \vec{\nabla} \phi$$

③ The Poisson Equation

$$\nabla^2 \phi_s = 4\pi G \rho_s$$

④ Equation of state

$$p_s = P(\rho_s)$$



Definition :

specific enthalpy

$$h(p_s) = \int_0^{p_s} \frac{1}{\rho'} \frac{\partial p_s}{\partial \rho_s}(\rho') d\rho'$$

for a barotropic  
EOS  $P = P(\rho)$

$$\vec{\nabla} h_s = \frac{1}{\rho_s} \vec{\nabla} p_s$$

Euler equation  
becomes

$$\frac{\partial \vec{v}_s}{\partial t} + (\vec{v}_s \cdot \vec{\nabla}) \vec{v}_s = - \frac{\vec{\nabla} p_s}{\rho_s} - \vec{\nabla} \phi$$

$$\frac{\partial \vec{v}_s}{\partial t} + (\vec{v}_s \cdot \vec{\nabla}) \vec{v}_s = - \vec{\nabla} (h_s + \phi)$$

Definition :

sound speed

$$v_s^2 = \left. \frac{\partial P(\rho)}{\partial \rho} \right|_{\rho_0}$$

for the  
unperturbed  
system



## More on enthalpy

$$h := u + \frac{P}{\rho}$$

$\underbrace{\quad}_{\text{spec. internal energy}} + \underbrace{\quad}_{\text{mechanical energy}}$

with  $du = T ds + \frac{P}{\rho^2} d\rho$

$$dh = du + \frac{dP}{\rho} - \frac{P}{\rho^2} d\rho$$

$$dh = T ds + \frac{dP}{\rho}$$

For  $S = \text{cte}$  and  $P = P(\rho)$

(barotropic EOS)

$$dh = \frac{dP}{\rho} = \frac{1}{\rho} \frac{\partial P}{\partial \rho} d\rho$$

Thus

$$h(\rho) = \int_0^\rho \frac{1}{\rho'} \frac{\partial P}{\partial \rho'}(\rho') d\rho'$$

# Isolated fluid at equilibrium

$$p_{s0}(\bar{x}) \quad \bar{v}_{s0}(x) \quad h_{s0}(\bar{x}) \quad \phi_{s0}(x)$$

solutions of

① Continuity Equation

$$\frac{\partial p_{s0}}{\partial t} + \bar{\nabla} \cdot (\rho_{s0} \bar{v}_{s0}) = 0$$

② Euler Equation

$$\frac{\partial \bar{v}_{s0}}{\partial t} + (\bar{v}_{s0} \cdot \bar{\nabla}) \bar{v}_{s0} = -\bar{\nabla}(h_{s0} + \phi_{s0})$$

③ The Poisson Equation

$$\nabla^2 \phi_{s0} = 4\pi G \rho_{s0}$$

④ Equation of state

$$h_{s0}(p_{s0}) = \int_0^{p_{s0}} \frac{1}{p'} \frac{\partial p_{s0}}{\partial p_{s0}}(p') dp'$$

$$p_{s0} = P(p_{s0})$$

The response of the system to a weak perturbation

$$- \varepsilon \nabla \phi_e$$

$$\rho_{s0}(\bar{x}) \rightarrow \rho_s(\bar{x}, t) = \rho_{s0}(\bar{x}) + \varepsilon \rho_{s1}(\bar{x}, t)$$

$$h_{s0}(\bar{x}) \rightarrow h_s(\bar{x}, t) = h_{s0}(\bar{x}) + \varepsilon h_{s1}(\bar{x}, t)$$

$$\vec{v}_{s0}(\bar{x}) \rightarrow \vec{v}_s(\bar{x}, t) = \vec{v}_{s0}(\bar{x}) + \varepsilon \vec{v}_{s1}(\bar{x}, t)$$

$$\phi_{s0}(\bar{x}) \rightarrow \phi_s(\bar{x}, t) = \phi_{s0}(\bar{x}) + \varepsilon \phi_{s1}(\bar{x}, t)$$

$$\phi_{s0}^{\text{tot}}(\bar{x}) \rightarrow \phi(\bar{x}, t) = \phi_{s0}(\bar{x}) + \varepsilon \phi_1(\bar{x}, t)$$



system only,  
without the  
perturbation

total pot. include  
the perturbation

$$= \phi_{s0}(\bar{x}) + \varepsilon \phi_{s1}(\bar{x}, t) + \varepsilon \phi_e(\bar{x}, t)$$

contrib. of the ext. perturb.

→ insert those equations into the equations for a self-gravitating fluid  $\rho_s(\bar{x}, t)$   $\phi_s(\bar{x}, t)$   $\vec{v}_s(\bar{x}, t)$   $h_s(\bar{x}, t)$

→ use equations for the unperturbed fluid

→ keep only first order terms ( $\varepsilon^2 \rightarrow 0$ )

We get a set of linear differential equations

→ time evolution of the perturbation

① "Continuity Equation"

$\rho_{s1}$   $\vec{v}_{s1}$   $\phi_{s1}$   $h_{s1}$   
6 unknowns  
6 equations

$$\frac{\partial}{\partial t} \rho_{s1} + \bar{\nabla} \cdot (\rho_{s0} \vec{v}_{s1}) + \bar{\nabla} \cdot (\rho_{s1} \vec{v}_{s0}) = 0$$

② "Euler Equation"

$$\begin{aligned} \frac{\partial}{\partial t} \vec{v}_{s1} + \vec{v}_{s0} \cdot (\bar{\nabla} \cdot \vec{v}_{s1}) + \vec{v}_{s1} (\bar{\nabla} \cdot \vec{v}_{s0}) &= - \bar{\nabla} (h_{s1} + \phi_{s1} + \phi_e) \\ &= - \frac{\bar{\nabla} p_{s1}}{\beta_0} - \bar{\nabla} (\phi_{s1} + \phi_e) \end{aligned}$$

③ "Poisson Equation"

$$\bar{\nabla} \cdot \phi_{s1} = 4\pi G \rho_{s1}$$

④ "Equation of state"

$$h_{s1} = \left. \frac{dP(\rho)}{d\rho} \right|_{\rho_0} \frac{\rho_{s1}}{\rho_0} = v_s^2 \frac{\rho_{s1}}{\rho_0}$$

# Linearized Equations for a self-gravitating stellar system

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## Equations for a self-gravitating stellar system

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System of DF

$$f_s(\vec{x}, \vec{v}, t) \rightarrow f_s(\vec{x}, t) \quad \phi_s(\vec{x}, t)$$

(without the perturbation)

① The collisionless Boltzmann Equation

total potential  $\phi = \phi_s + \epsilon \phi_c$

$$\frac{\partial f_s}{\partial t} + \vec{v} \frac{\partial f_s}{\partial \vec{x}} - \frac{\partial \phi}{\partial \vec{x}} \frac{\partial f_s}{\partial \vec{v}} = 0$$

$$= \frac{\partial f_s}{\partial t} + [f_s, \mathcal{H}] = 0$$

$$\mathcal{H} = \frac{1}{2} \vec{v}^2 + \phi(\vec{x}, t)$$

② The Poisson Equation

$$\nabla^2 \phi_s = 4\pi G \rho_s = 4\pi G \int d^3v f_s(\vec{x}, \vec{v}, t)$$

Isolated stellar system at equilibrium

$$f_0(\vec{x}, \vec{v}) \quad \rho_0(\vec{x}) \quad \phi_0(\vec{x})$$

solutions of

① The collisionless Boltzmann Equation

$$\frac{\partial f_0}{\partial t} + [f_0, \mathcal{H}_0] = 0$$

$$\mathcal{H}_0 = \frac{1}{2} \vec{v}^2 + \phi_0(\vec{x})$$

② The Poisson Equation

$$\nabla^2 \phi_0 = 4\pi G \rho_0 = 4\pi G \int d^3v f_0(\vec{x}, \vec{v}, t)$$

The response of the system to a weak perturbation

$$- \varepsilon \nabla \phi_e$$

$$\rho_{s0}(\bar{x}, \bar{v}) \rightarrow \rho_s(\bar{x}, \bar{v}, t) = \rho_{s0}(\bar{x}, \bar{v}) + \varepsilon \rho_{s1}(\bar{x}, \bar{v}, t)$$

$$\rho_{s0}(\bar{x}) \rightarrow \rho_s(\bar{x}, t) = \rho_{s0}(\bar{x}) + \varepsilon \rho_{s1}(\bar{x}, t)$$

$$\phi_{s0}(\bar{x}) \rightarrow \phi_s(\bar{x}, t) = \phi_{s0}(\bar{x}) + \varepsilon \phi_{s1}(\bar{x}, t)$$

$$\text{|||}$$

$$\phi_{s0}(\bar{x}) \rightarrow \phi(\bar{x}, t) = \phi_{s0}(\bar{x}) + \varepsilon \phi_1(\bar{x}, t)$$

$$= \phi_{s0}(\bar{x}) + \varepsilon \phi_{s1}(\bar{x}, t) + \varepsilon \phi_e(\bar{x}, t)$$

total pot. include the perturbation

contrib of the ext. perturb.

$$H_0(\bar{x}) \rightarrow H_{\text{tot}}(\bar{x}, t) = \frac{1}{2} \bar{v}^2 + \phi_0(\bar{x}) + \varepsilon \phi_1(\bar{x}, t)$$

$$= H_0(\bar{x}, \bar{v}) + \varepsilon \phi_1(\bar{x}, t)$$

include the perturbation

→ insert those equations into the equations for a

self-gravitating stellar system  $\rho_s(\bar{x}, \bar{v}, t)$   $\rho_s(\bar{x}, t)$   $\phi_s(\bar{x}, t)$

→ use equations for the unperturbed stellar system

→ keep only first order terms ( $\varepsilon^2 \rightarrow 0$ )



We get a set of linear differential equations

→ time evolution of the perturbation

① "The collisionless Boltzmann Equation"

$\rho_{s1}$   $\rho_{s1}$   $\phi_{s1}$   
3 unknowns  
3 equations

$$\frac{\partial \rho_{s1}}{\partial t} + [\rho_{s1}, H_{s0}] = [\rho_{s0}, \phi_{s1}]$$

$$\frac{\partial \rho_{s1}}{\partial t} + \frac{\partial \rho_{s1}}{\partial \vec{x}} \vec{v} - \frac{\partial \rho_{s1}}{\partial \vec{v}} \frac{\partial \phi_{s0}}{\partial \vec{x}} = \frac{\partial \rho_{s0}}{\partial \vec{v}} \frac{\partial \phi_{s1}}{\partial \vec{x}}$$

② "The Poisson Equation"

$$\nabla^2 \phi_{s1} = 4\pi G \rho_{s1} = 4\pi G \int d^3v \rho_{s1}$$

# Interpretation

Reminder

Variation of  $\rho_{s1}$  along the flow (Lagrangian derivative)

$$\frac{\partial \rho_{s1}}{\partial t} + [\rho_{s1}, H_{s0}] = [\rho_{s0}, \phi_1]$$

$$\frac{\partial \rho_{s1}}{\partial t} + \frac{\partial \rho_{s1}}{\partial \vec{x}} \vec{v} - \frac{\partial \rho_{s1}}{\partial \vec{v}} \frac{\partial \phi_{s0}}{\partial \vec{x}} = \frac{\partial \rho_{s0}}{\partial \vec{v}} \frac{\partial \phi_1}{\partial \vec{x}}$$

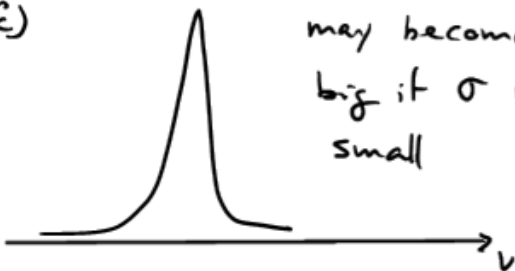
$\frac{d}{dt} \rho_{s1}$

velocity

source

gravity

$P_v(\vec{x})$



may become  
big if  $\sigma$  is  
small

# Linear differential equations

C'est a revoire...

$$f(x) : \frac{d^2 f}{dx^2} g_1(x) + \dots + \frac{d^3 f}{dx^3} g_n(x) + \frac{df}{dx} g_{n+1}(x) + f(x) g_{n+2}(x) = c$$

$g_i(x)$  : a continuous function

Ici, q'une var x !!!

if  $f_1, f_2$  are solutions  $a f_1 + b f_2$  is a solution

## Illustration

- 1-D continuity equation  $(\rho, v)$  Ici, 2 var rho, v !!!

$$\frac{d}{dt} \rho + \underbrace{\rho \frac{\partial v}{\partial x} + v \frac{\partial \rho}{\partial x}}_{\text{these terms mixes } \rho \text{ and } v} = 0$$

- 1-D linearized continuity equation  $(\rho_{s1}, v_1)$

$$\frac{d}{dt} \rho_{s1} + \rho_0 \frac{\partial v_1}{\partial x} + v_0 \frac{\partial \rho_{s1}}{\partial x} = 0$$

-- no mixing

# **Stability of collisionless systems**

## **The Jeans instability**

**(1902)**

# The Jeans instability

Homogeneous medium subject to a perturbation

- consider an infinite static homogeneous system at equilibrium

- $\triangle$  no polytropic homogeneous system exists

$$\vec{V}_0 = 0$$

Euler Equation

$$\cancel{\frac{\partial \vec{v}_0}{\partial t}} + (\cancel{\vec{v}_0 \cdot \nabla}) \vec{v}_0 = - \cancel{\frac{\nabla \cdot \vec{p}_0}{\rho_0}} - \nabla \phi_0$$

$$\Rightarrow \nabla \phi_0 = 0$$

Poisson Equation

$$\nabla^2 \phi_0 = 4\pi G \rho_0 \quad \Rightarrow \quad \underline{\rho_0 = 0}$$

Linearized Poisson

$$\nabla^2 \phi_s = 4\pi G \rho_s \equiv \nabla^2 (\phi_0 + \epsilon \phi_{s1}) = 4\pi G (\rho_0 + \epsilon \rho_{s1})$$

$$\nabla^2 \phi_{s1} = 4\pi G \rho_{s1}$$

Jeans swindle

# The response of an homogeneous fluid

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Linearized fluid equations

$\rho_{s1}(\bar{x}, t)$ ,  $\phi_{s1}(\bar{x}, t)$ ,  $\vec{v}_{s1}(\bar{x}, t)$ ,  $h_{s1}(\bar{x}, t)$

$$\left\{ \begin{array}{l} \textcircled{1} \quad \frac{\partial}{\partial t} \rho_{s1} + \bar{\nabla}(\rho_0 \vec{v}_{s1}) + \cancel{\bar{\nabla}(\rho_{s1} \vec{v}_0)} = 0 \\ \textcircled{2} \quad \frac{\partial}{\partial t} \vec{v}_{s1} + \cancel{\vec{v}_0 \cdot (\bar{\nabla} \cdot \vec{v}_{s1})} + \cancel{\vec{v}_{s1} (\bar{\nabla} \cdot \vec{v}_0)} = - \bar{\nabla} (h_{s1} + \phi_{s1} + \phi_e) \\ \textcircled{3} \quad \bar{\nabla} \phi_{s1} = 4\pi G \rho_{s1} \\ \textcircled{4} \quad h_{s1} = v_s^2 \frac{\rho_{s1}}{\rho_0} \end{array} \right.$$

$$\boxed{\vec{v}_0 = 0}$$

Solution

$$\frac{\partial}{\partial t} \textcircled{1} : \frac{\partial^2}{\partial t^2} \rho_{s1} + \rho_0 \bar{\nabla} \cdot \left( \frac{\partial}{\partial t} \vec{v}_{s1} \right) = 0$$

$$\bar{\nabla} \cdot \textcircled{2} : \bar{\nabla} \cdot \frac{\partial \vec{v}_{s1}}{\partial t} = - \nabla^2 (h_{s1} + \phi_{s1} + \phi_e)$$

Thus, we have (  $\bar{\nabla} \cdot \textcircled{2}$  into  $\frac{\partial}{\partial t} \textcircled{1}$  )

$$\frac{\partial^2}{\partial t^2} \rho_{s1} - \rho_0 \nabla^2 (h_{s1} + \phi_{s1} + \phi_e) = 0$$

$$\frac{\partial^2}{\partial t^2} \rho_{s1} - \rho_0 \nabla^2 (h_{s1} + \phi_{s1} + \phi_e) = 0$$

$$\frac{\partial^2}{\partial t^2} \rho_{s1} - \rho_0 \nabla^2 h_{s1} - \rho_0 \nabla^2 \phi_{s1} = \rho_0 \nabla^2 \phi_e$$

$$\textcircled{2} \quad \vec{\nabla} h_{s1} = \frac{1}{\rho_s} \vec{\nabla} \rho_{s1}$$

$$\frac{1}{\rho_0} \frac{\partial^2}{\partial t^2} \rho_{s1} - \vec{\nabla} \cdot \left( \frac{\vec{\nabla} \rho_{s1}}{\rho_s} \right) - \vec{\nabla} \cdot (\vec{\nabla} \phi_{s1}) = \vec{\nabla} \cdot (\vec{\nabla} \phi_e)$$

Growth accel.  
of  $\rho_{s1}$

$F_{\text{pressure}}$

$F_{\text{grav, self}}$

$F_{\text{grav, ext}}$

(spec. forces)

$$\frac{\partial^2}{\partial t^2} \rho_{s1} - \rho_0 \nabla^2 h_{s1} - \rho_0 \nabla^2 \phi_{s1} = \rho_0 \nabla^2 \phi_e$$

$\textcircled{4}$

$$- v_s^2 \nabla^2 \rho_{s1}$$

$\textcircled{3}$

$$- 4\pi G \rho_0 \rho_{s1}$$

$$4\pi G \rho_0 \rho_e$$

$$\nabla^2 \phi_e = 4\pi G \rho_e$$

$$\frac{\partial^2}{\partial t^2} \rho_{s1} - v_s^2 \nabla^2 \rho_{s1} - 4\pi G \rho_0 \rho_{s1} = 4\pi G \rho_0 \rho_e$$

pressure

self grav.

ext. grav.

Differential equation for  $\rho_{s1}$  only  
Evolution of a perturbation in an  
homogeneous fluid

## Some simple cases

$$\frac{\partial^2}{\partial t^2} p_{s1} - v_s^2 \nabla^2 p_{s1} - 4\pi G \rho_0 p_{s1} = 4\pi G \rho_0 p_e$$

1) no gravity, no ext forces

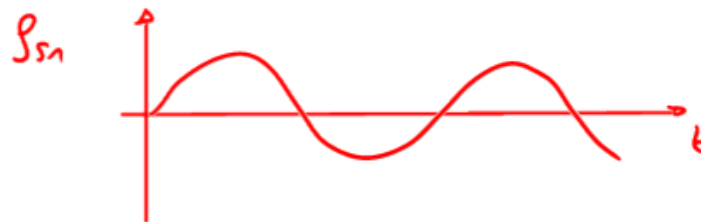
$$\frac{\partial^2}{\partial t^2} p_{s1} - v_s^2 \nabla^2 p_{s1} = 0$$

In 1-D  $\frac{\partial^2}{\partial t^2} p_{s1}(x,t) - v_s^2 \frac{\partial^2}{\partial x^2} p_{s1}(x,t) = 0$  (wave equation)

general solution :  $f$  : an arbitrary function

$$p_{s1}(x,t) = \underbrace{f(x - v_s t)}_{\text{move at speed } v_s} + \underbrace{f(x + v_s t)}_{\text{move at speed } -v_s}$$

sound wave traveling at sound speed  $v_s$



oscillatory  
solution

**STABLE**



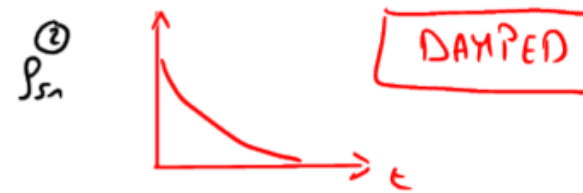
$$\frac{\partial^2}{\partial t^2} \rho_{s1} - v_s^2 \nabla^2 \rho_{s1} - 4\pi G \rho_0 \rho_{s1} = 4\pi G \rho_0 \rho_e$$

2) no pressure, no external forces

$$\frac{\partial^2}{\partial t^2} \rho_{s1} = 4\pi G \rho_0 \rho_{s1}$$

Solutions: any linear combination of

$$\rho_{s1}^{(1)}(x,t) = \tilde{\rho}(\vec{x}) e^{\sqrt{4\pi G \rho_0} t} \quad \text{and} \quad \rho_{s1}^{(2)}(x,t) = \tilde{\rho}(\vec{x}) e^{-\sqrt{4\pi G \rho_0} t}$$



3) no external forces

$$\frac{\partial^2}{\partial t^2} \rho_{s1} - v_s^2 \nabla^2 \rho_{s1} - 4\pi G \rho_0 \rho_{s1} = 0$$

pressure  
stabilize

self-gravity  
destabilize

## General solutions

$$e^{-i(\vec{k}\vec{x} - \omega t)}$$

•  $\times e^{-i\vec{k}\vec{x}} + \int d^3\vec{x} \Rightarrow$  spatial Fourier transform

$$\bar{f}_{S_1}(\vec{k}, t) = \int d^3x e^{-i\vec{k}\vec{x}} f_{S_1}(\vec{x}, t)$$

$$\frac{\partial^2}{\partial t^2} \bar{f}_{S_1}(\vec{k}, t) + v_s^2 k^2 \bar{f}_{S_1}(\vec{k}, t) - 4\pi G \rho_0 \bar{f}_{S_1}(\vec{k}, t) = 4\pi G \rho_0 \bar{f}_e(\vec{k}, t)$$

(after the)

Evolution in absence of perturbation

$$f_e(x, t) = 0 \quad \bar{f}_e = 0$$

Solutions are in the form

$$\bar{f}_{S_1}(\vec{k}, t) \sim e^{i\omega t} \quad \omega = \omega(|\vec{k}|) \in \mathbb{C}$$
$$k = |\vec{k}|$$

Introducing in the previous equation, we get the dispersion relation

$$\omega^2(k) = v_s^2 k^2 - 4\pi G \rho_0$$

Definition : Jeans wave number

$$k_J^2 = \frac{4\pi G \rho_0}{v_s^2}$$

$$\omega^2(k) = v_s^2 k^2 - 4\pi G \rho_0$$

→

$$\omega^2(k) = v_s^2 (k^2 - k_J^2)$$

$$f_{sn} \sim e^{ikx} e^{-i\omega t} \quad (k \in \mathbb{R}_e)$$

- If  $k > k_J$  →  $\omega^2 > 0$  →  $\omega \in \mathbb{R}_e$      $\bar{f}_{sn} \sim e^{-i\omega t}$      $\bar{f}_{sn} \sim \text{oscillate}$

A perturbation with a short wavelength ( $k > k_J$ ) will see its amplitude oscillate

- If  $k < k_J$  →  $\omega^2 < 0$  →  $\omega \in \mathbb{I}_m$      $\bar{f}_{sn} \sim e^{-\omega t}$      $\omega = i\omega \in \mathbb{R}_e$   
 $\bar{f}_{sn} \sim \begin{cases} \text{decay} \\ \text{growth} \end{cases}$

A perturbation with a long wavelength ( $k < k_J$ ) will see its amplitude decay or growth exponentially

More discussion

$$k_J^2 = \frac{4\pi G \rho_0}{v_s^2}$$

$$\omega^2(k) = v_s^2(k^2 - k_J^2)$$

Assume a perturbation with a fixed wave number  $k$ .

①  $G = 0$  (no gravity)

$$\Rightarrow k_J = 0$$

$$\underline{k > k_J}$$

$$\omega^2(k) = v_s^2 k^2 \in \mathbb{R}_e$$

dispersion relation  
for a sound wave  
oscillation at frequ.  $\omega$

$$\bar{p}_{sn} \sim e^{-i\omega t}$$

**STABLE**

②  $G \neq 0$

$$\underline{k > k_J}$$

$\omega$  decreases with  $k$  increases

**STABLE**

$$\underline{k = k_J}$$

$$\omega = 0$$

$$\underline{k < k_J}$$

$$\omega \in \mathbb{I}_m$$

**UNSTABLE**

③  $\rho \gg v_s^2 / 4\pi G$  (no pressure)  $k_J \rightarrow \infty$

**UNSTABLE**

## Definitions

Jeans length

$$\lambda_J = \frac{e\pi}{k_J} = \sqrt{\frac{\pi v_s^2}{G\rho_0}}$$

$$\lambda > \lambda_J \Rightarrow \text{UNSTABLE}$$

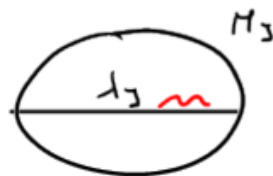
Jeans mass

Mass inside a sphere of radius  $\frac{1}{2} \lambda_J$

$$M_J = \frac{4}{3} \pi \left(\frac{1}{2} \lambda_J\right)^3 \rho_0$$

$$M_J = \frac{\pi^{5/2}}{6} \frac{v_s^3}{G^{3/2} \rho_0^{1/2}}$$

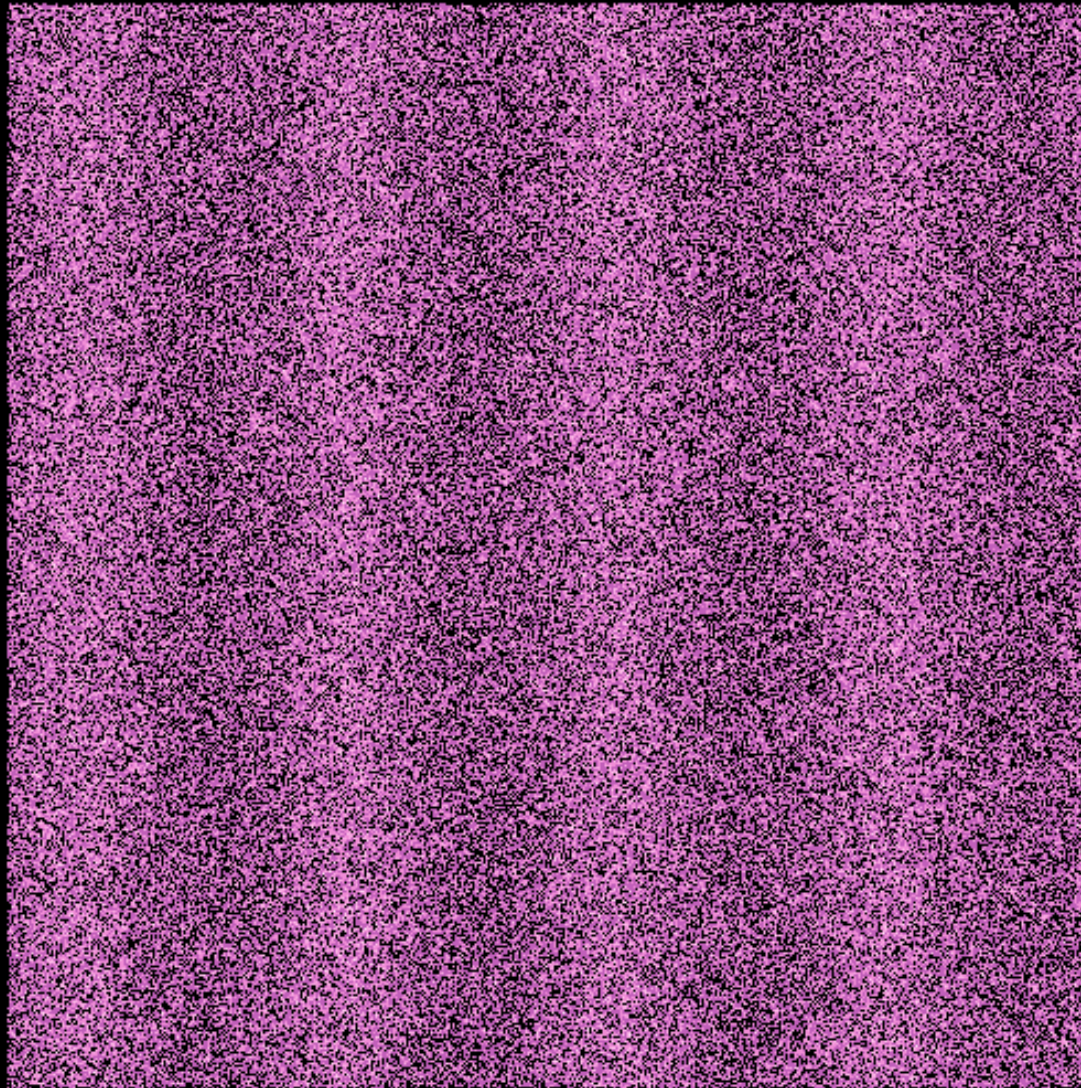
"Minimum mass that can collapse"



any perturbation with  $\lambda < \lambda_J$  i.e. involving a mass  $< M_J$  will be **STABLE**

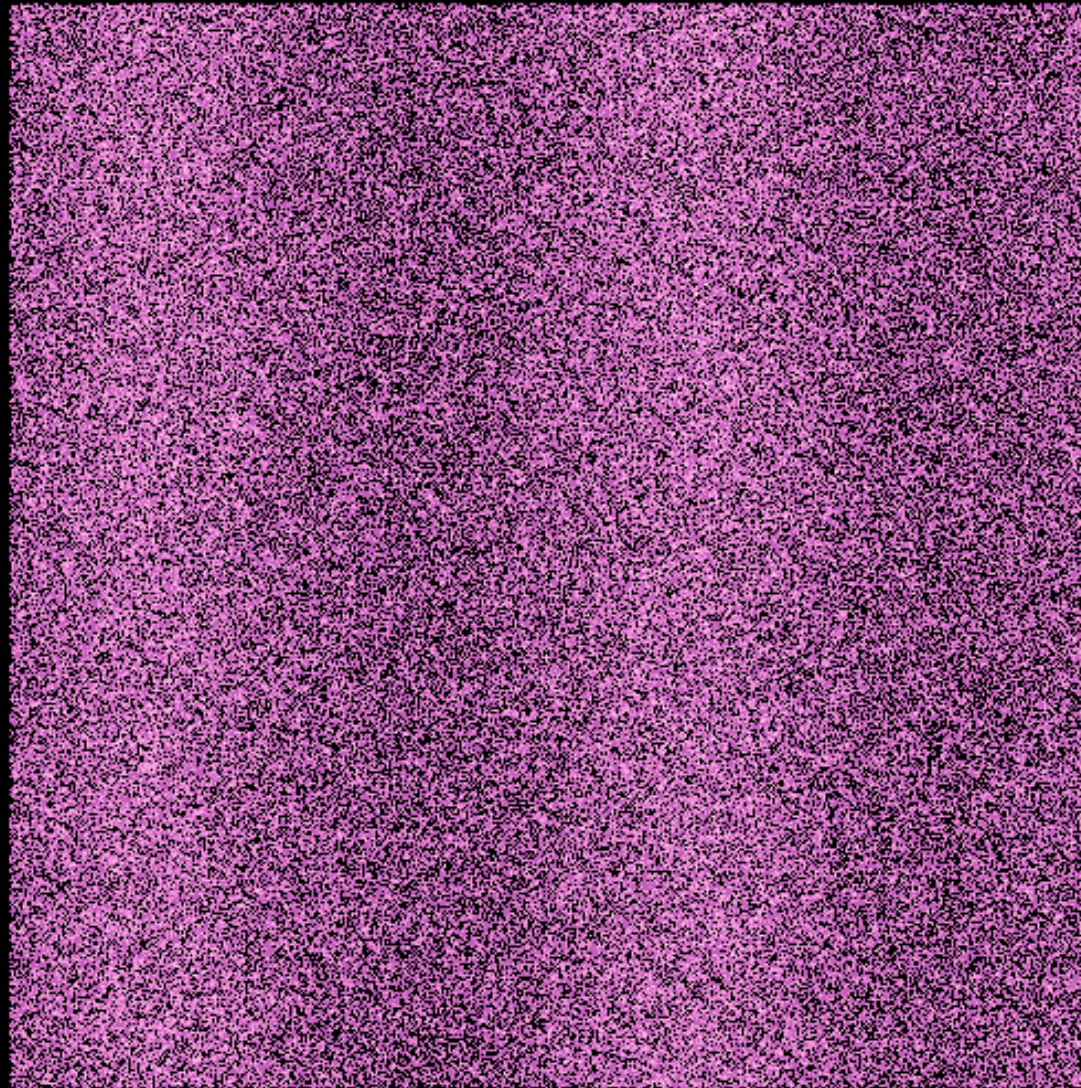
The Jeans instability in fluid systems

$$\lambda_J = 1.50 \quad \lambda = 0.25$$



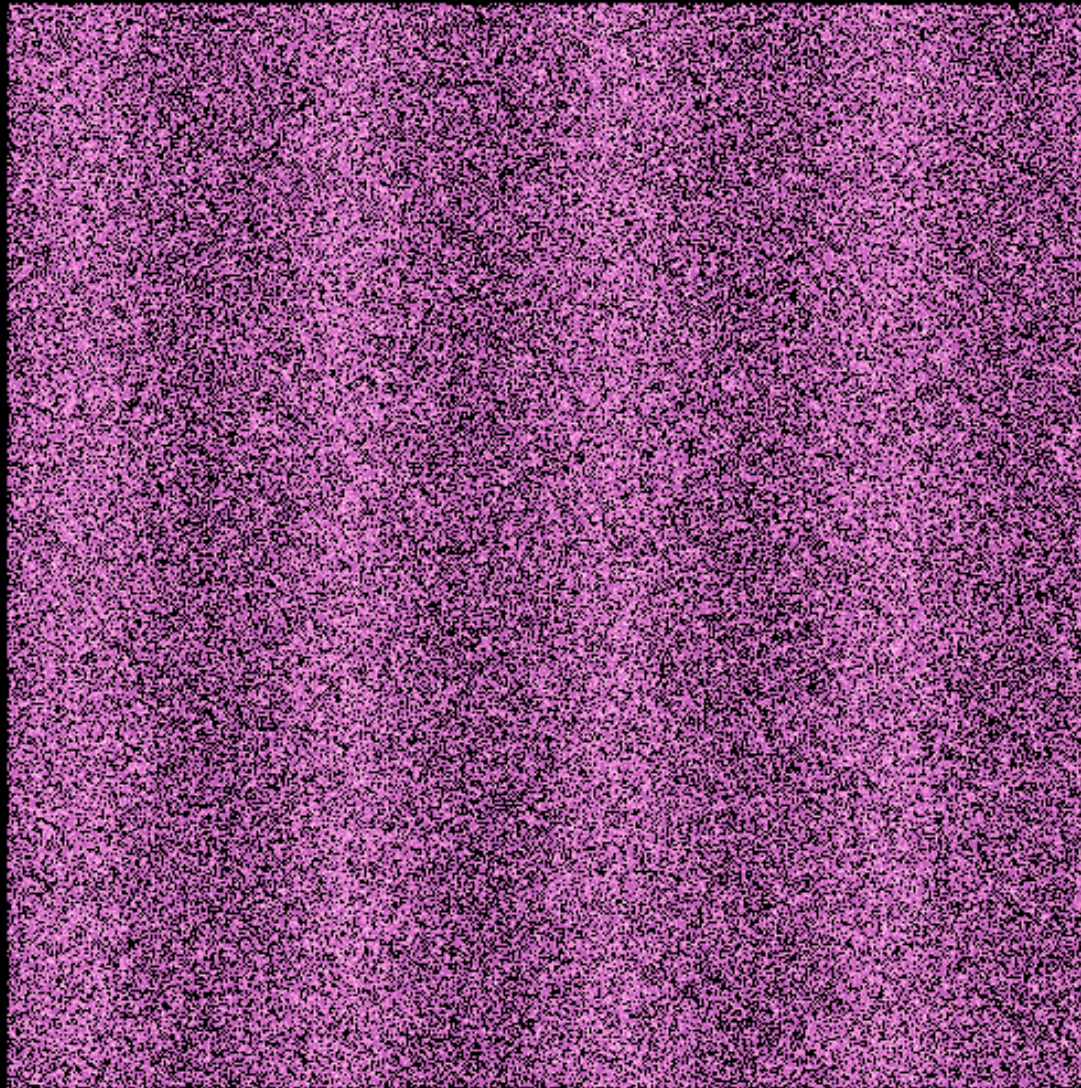
The Jeans instability in fluid systems

$$\lambda_J = 1.50 \quad \lambda = 0.50$$



The Jeans instability in fluid systems

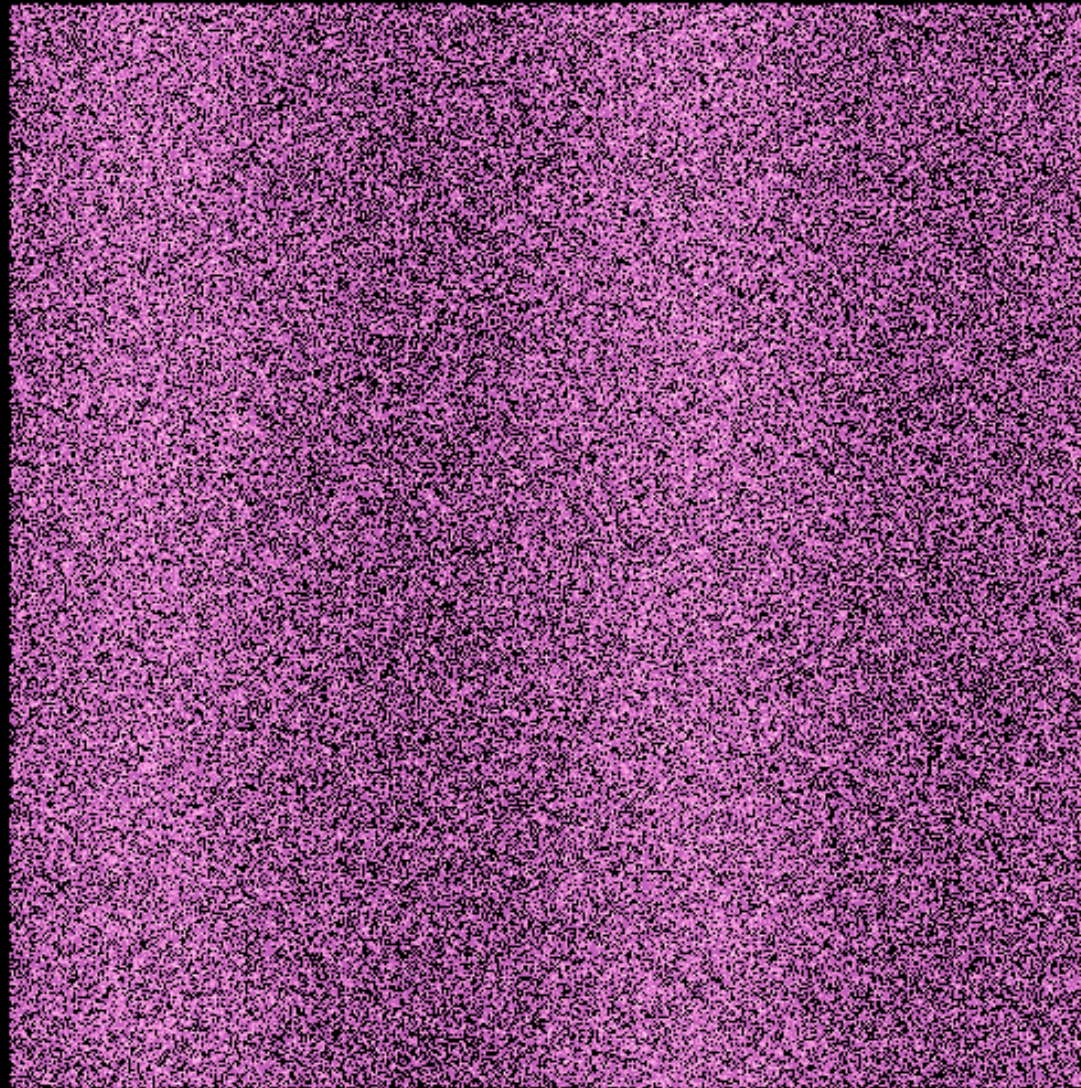
$$\lambda_J = 0.25 \quad \lambda = 0.25$$





The Jeans instability in fluid systems

$$\lambda_J = 0.25 \quad \lambda = 0.50$$



# The response of an homogeneous stellar system

## Linearized equations

$$\left\{ \begin{array}{l} \textcircled{1} \quad \frac{\partial \rho_{s1}}{\partial t} + [\rho_{s1}, H_0] = [\rho_0, \phi_1] \\ \equiv \quad \frac{\partial \rho_{s1}}{\partial t} + \frac{\partial \rho_{s1}}{\partial \vec{x}} \vec{v} - \frac{\partial \rho_{s1}}{\partial \vec{v}} \frac{\partial \phi_0}{\partial \vec{x}} = \frac{\partial \rho_0}{\partial \vec{v}} \frac{\partial \phi_1}{\partial \vec{x}} \equiv \frac{\partial \rho_0}{\partial \vec{v}} \frac{\partial}{\partial \vec{x}} (\phi_{s1} + \phi_e) \\ \textcircled{2} \quad \nabla^2 \phi_{s1} = 4\pi G \rho_{s1} = 4\pi G \int d^3\vec{v} \rho_{s1} \end{array} \right.$$

*$\phi_0 = 0$*

## Manipulation + special Fourier space

$$\bar{\rho}_{s1}(\vec{k}, \vec{v}, t) = i\vec{k} \cdot \frac{\partial \rho_0}{\partial \vec{v}} \int_{-\infty}^t dt' e^{i\vec{k}\vec{v}(t-t')} [\bar{\phi}_{s1}(\vec{k}, t') + \bar{\phi}_e(\vec{k}, t')]$$

$\triangle$  The DF depends on the past history  $\left( \int_{-\infty}^t \rho_{s1} + \phi_e \right)$

## Integration over $d^3\vec{v}$ + Poisson

$$\downarrow$$

$$\bar{f}_{sn}(\vec{k}, t) = -\frac{4\pi G}{k^2} i \int d^3\vec{v} \vec{k} \cdot \frac{\partial f_0}{\partial \vec{v}} \int_{-\infty}^t dt' e^{i\vec{k}\cdot\vec{v}(t-t')} [\bar{f}_{sn}(\vec{k}, t') + \bar{f}_e(\vec{k}, t')]$$

In temporal Fourier space

This term may diverge if  $\vec{k}\cdot\vec{v} = \omega$

$$\tilde{f}_{sn}(\vec{k}, \omega) = \int dt \bar{f}_{sn}(\vec{k}, t) e^{-i\omega t}$$

$$\tilde{f}_{sn}(\vec{k}, \omega) = \left( -\frac{4\pi G}{k^2} \int \frac{d^3\vec{v}}{\vec{k}\cdot\vec{v} - \omega} \vec{k} \cdot \frac{\partial f_0}{\partial \vec{v}} \right) \left( \tilde{f}_{sn}(\vec{k}, \omega) + \hat{f}_e(\vec{k}, \omega) \right)$$

In absence of perturbation

$$f_e = 0$$

we must have:

$$-\frac{4\pi G}{k^2} \int \frac{d^3\vec{v}}{\vec{k}\cdot\vec{v} - \omega} \vec{k} \cdot \frac{\partial f_0}{\partial \vec{v}} = 1$$

$$\frac{\text{Im}(\omega) > 0}{\text{Im}(\omega) > 0}$$

(instead, we may have a divergence)

This is our dispersion relation

$$\omega = \omega(\vec{k}, f_0)$$

Assuming a Maxwellian for the unperturbed DF  $f_0$

$$f_0(\vec{v}) = \frac{f_0}{(2\pi\sigma^2)^{3/2}} e^{-\frac{v^2}{2\sigma^2}}$$

The dispersion relation becomes

$$-\frac{4\pi G}{k^2} \int \frac{d^3\vec{v}}{k \cdot \vec{v} - \omega} \bar{k} \cdot \frac{\partial f_0}{\partial \vec{v}} = 1 \quad \Rightarrow \quad \frac{4\pi G f_0}{k^2 \sigma^2} (1 + w' Z(w')) = 1$$

with

$$w' = \sqrt{2} k \sigma w \quad Z(w') = \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} ds \frac{e^{-s^2}}{s - w'} = i\sqrt{\pi} e^{-w'^2} [1 + \text{erf}(iw')]$$

$$k = |k|$$

$$\text{erf}(z) = \frac{2}{\sqrt{\pi}} \int_0^z dt e^{-t^2}$$

The dispersion relation is  $\text{Im}(w) > 0$

$$\frac{4\pi G \rho_0}{k^2 \sigma^2} (1 + w' z(w')) = 1$$

$$w' = \sqrt{2} k \sigma w$$

$$z(w') = \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} ds \frac{e^{-s^2}}{s - w'}$$

Defining  $k_j^2 = \frac{4\pi G \rho_0}{\sigma^2}$

fluid  $k_j^2 = \frac{4\pi G \rho_0}{c_s^2}$

$$\frac{k^2}{k_j^2} = 1 + w' z(w')$$

$$\frac{k^2}{k_j^2} = 1 + \frac{w^2}{k_j^2 c_s^2}$$

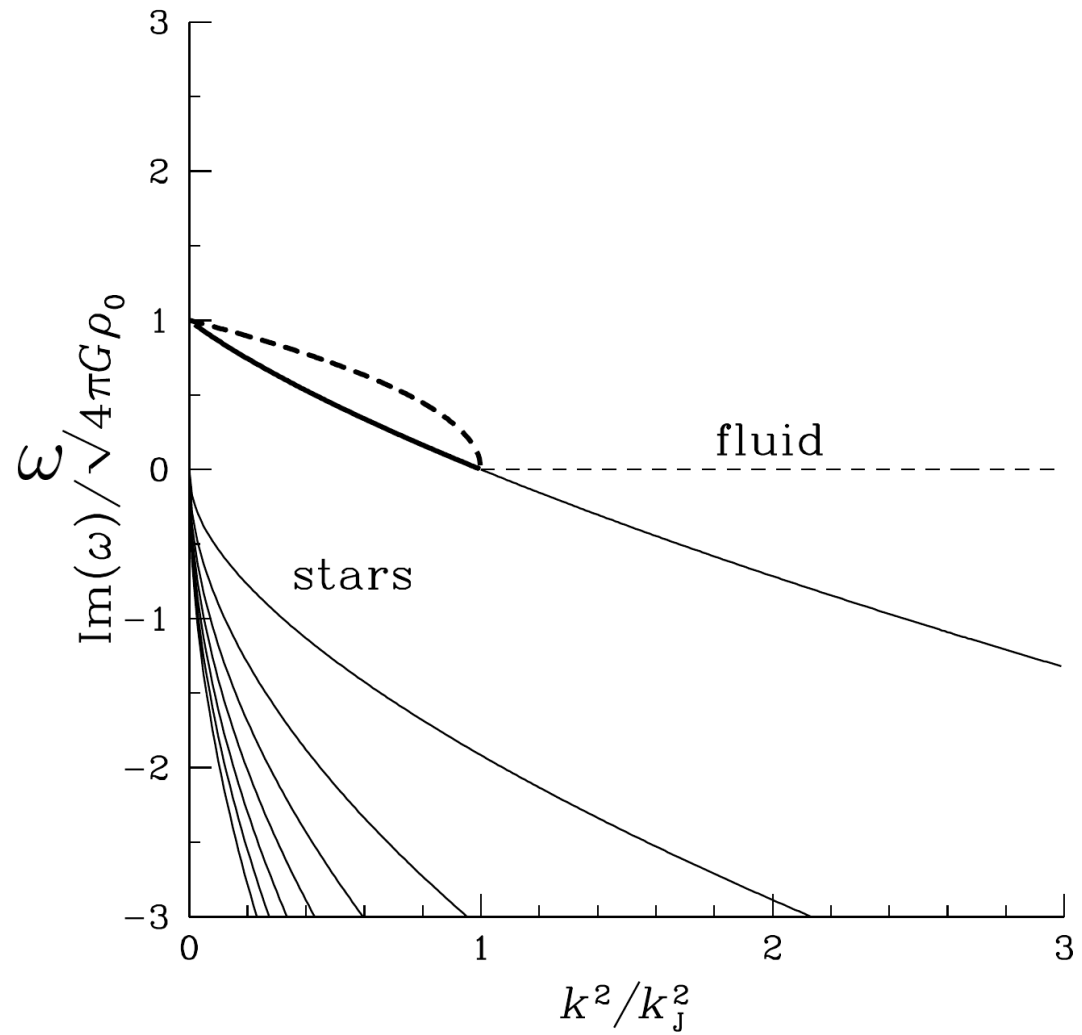
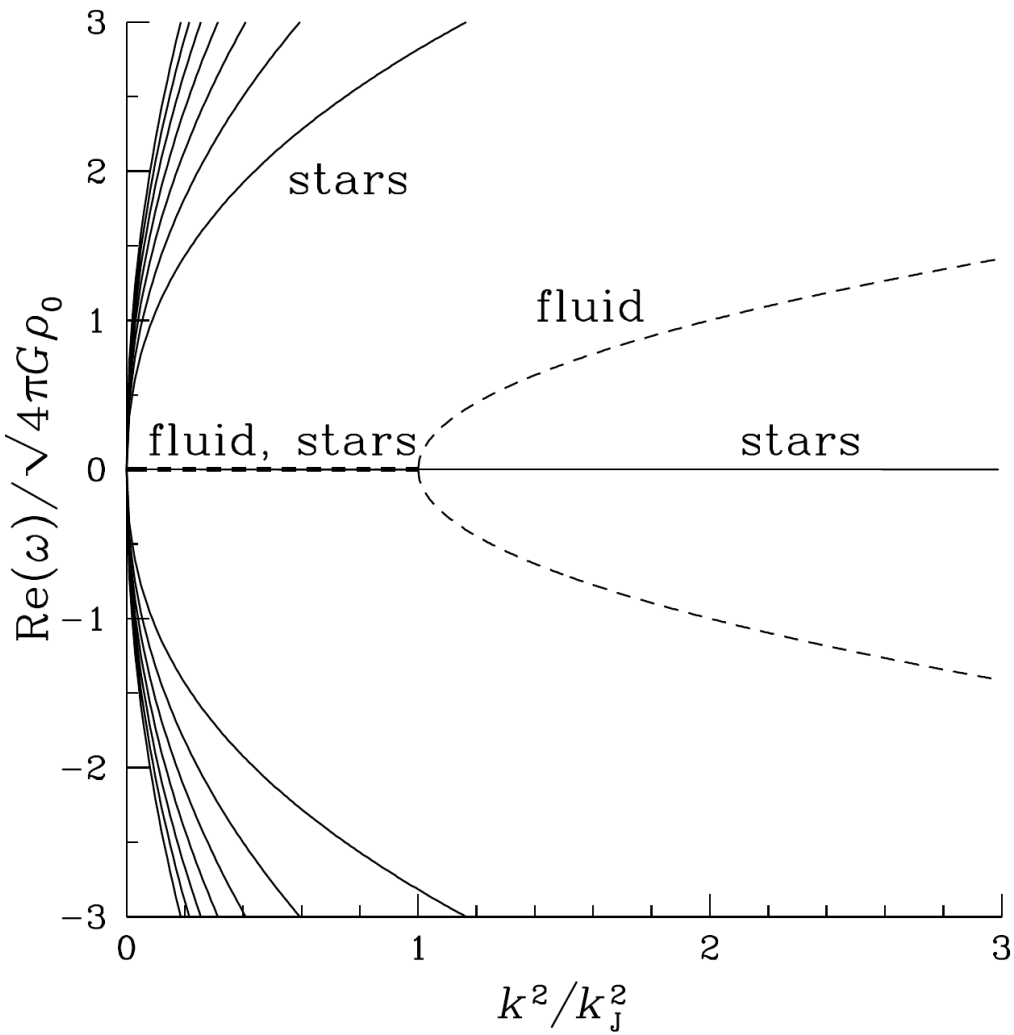
$$\frac{w^2}{z(w')} = \sigma^2 (k^2 - k_j^2)$$

$$w^2 = c_s^2 (k^2 - k_j^2)$$

one k is hidden here

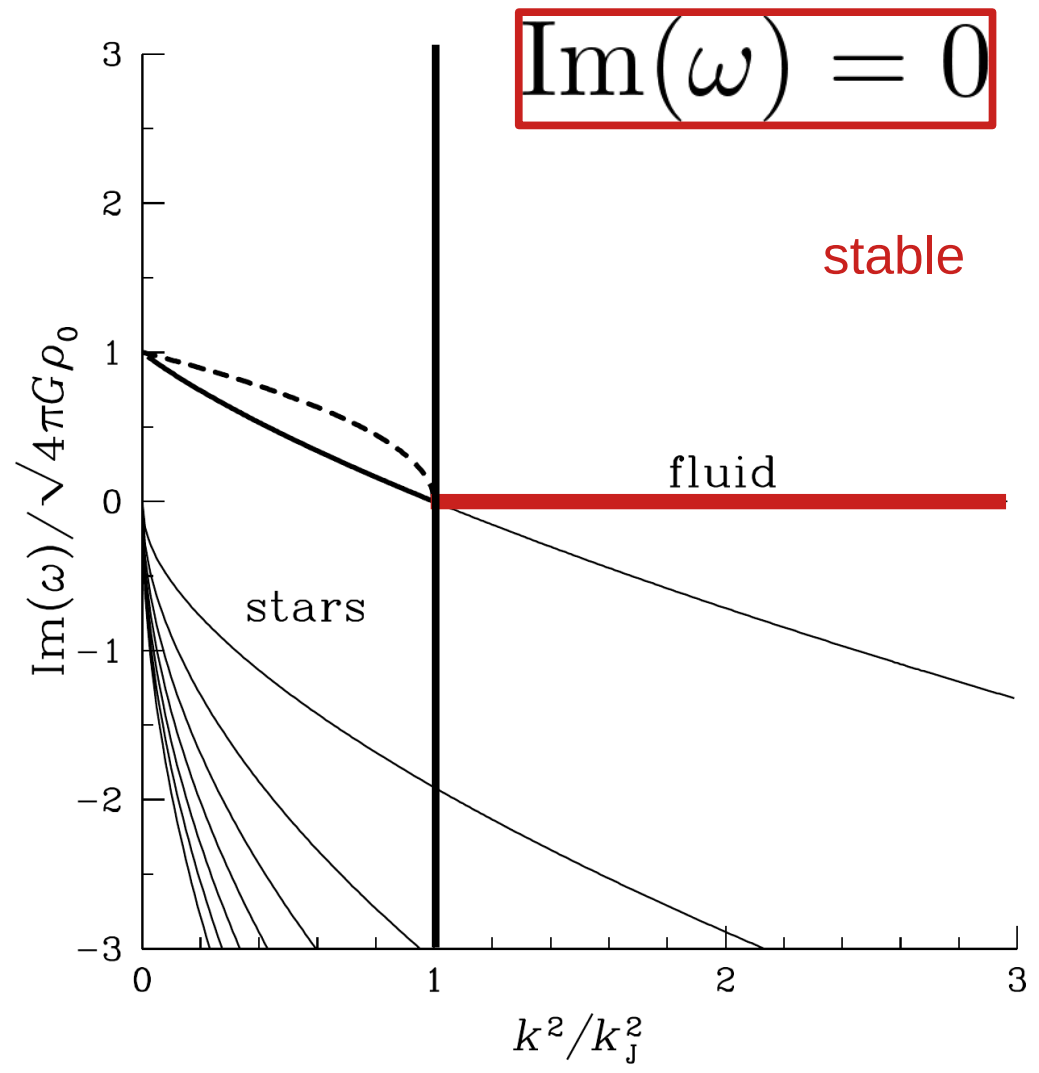
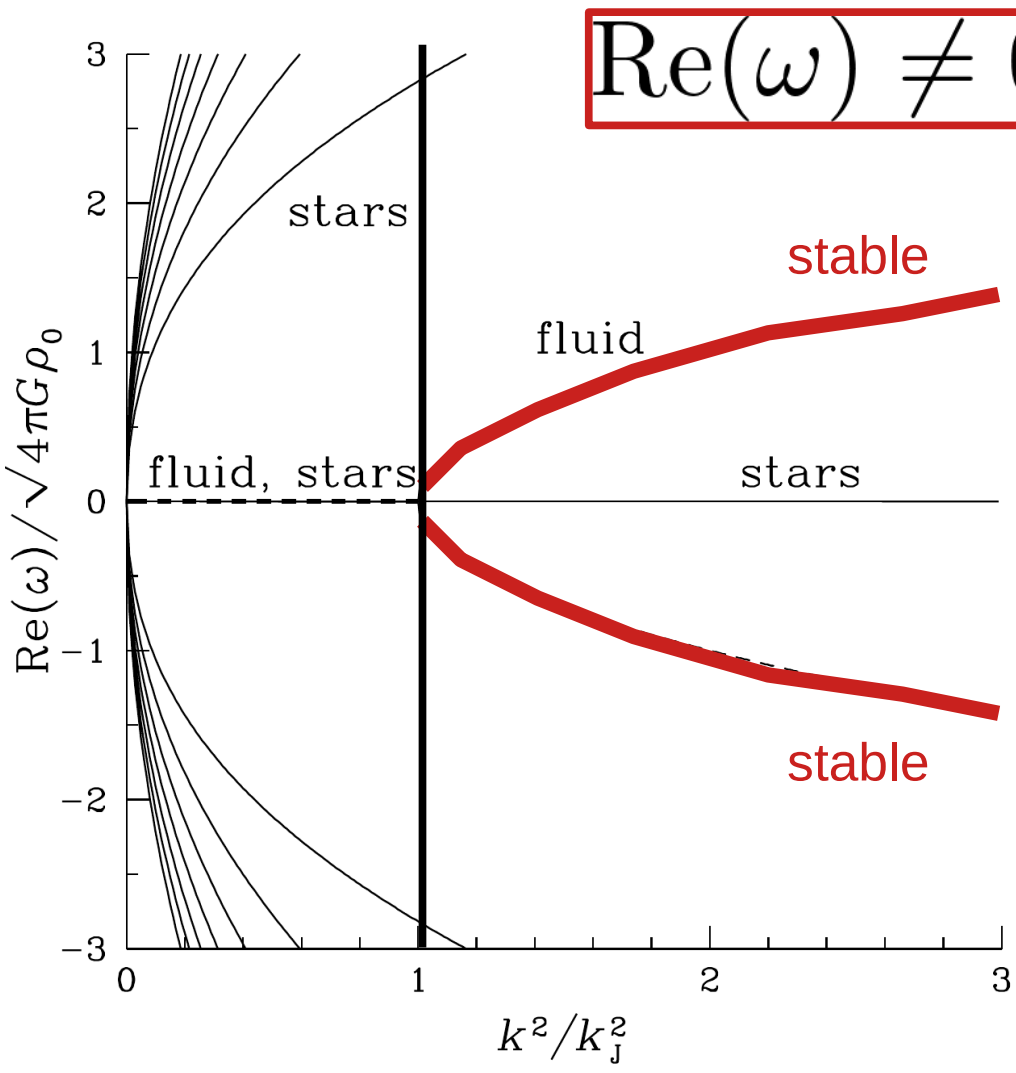
! for  $\text{Im}(w) = 0$  or  $\text{Im}(w) < 0$  (a bit more tricky)

# The dispersion relation for fluids and stellar systems



# The dispersion relation for fluids

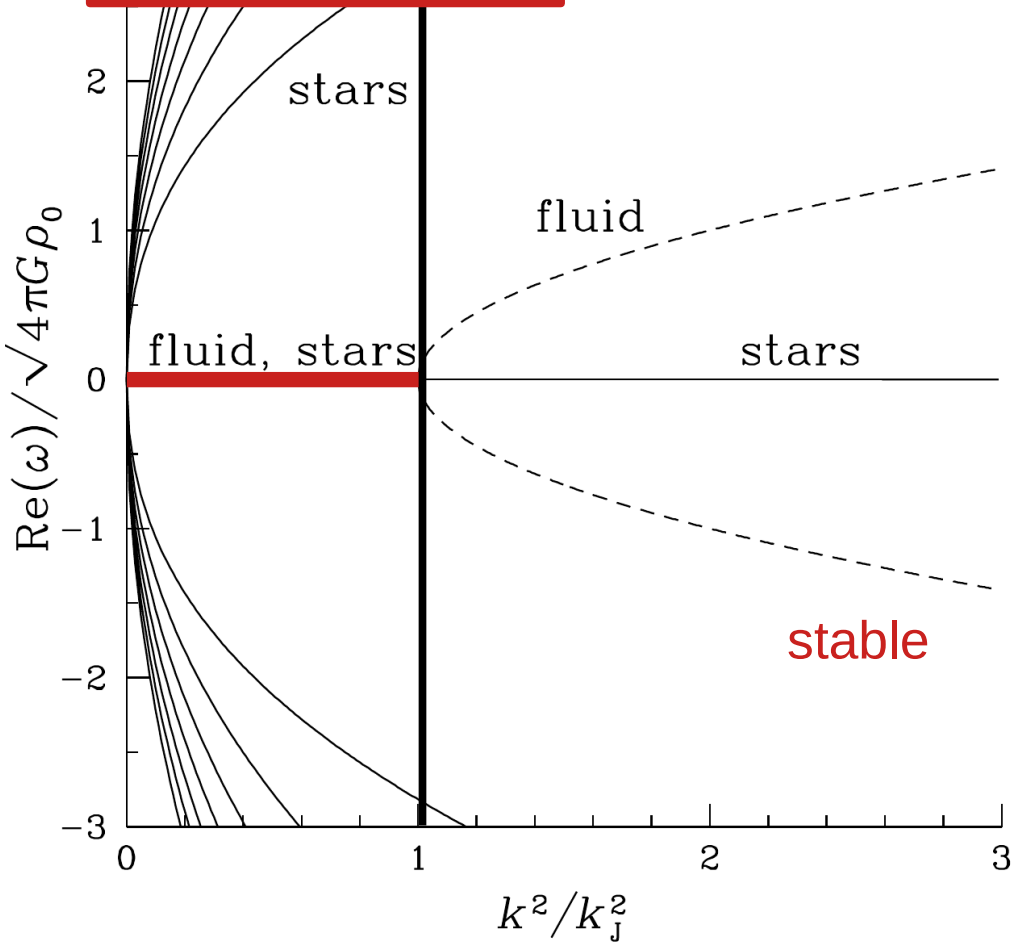
$$\frac{k^2}{k_J^2} = 1 + \frac{\omega^2}{k_J^2 v_s^2}$$



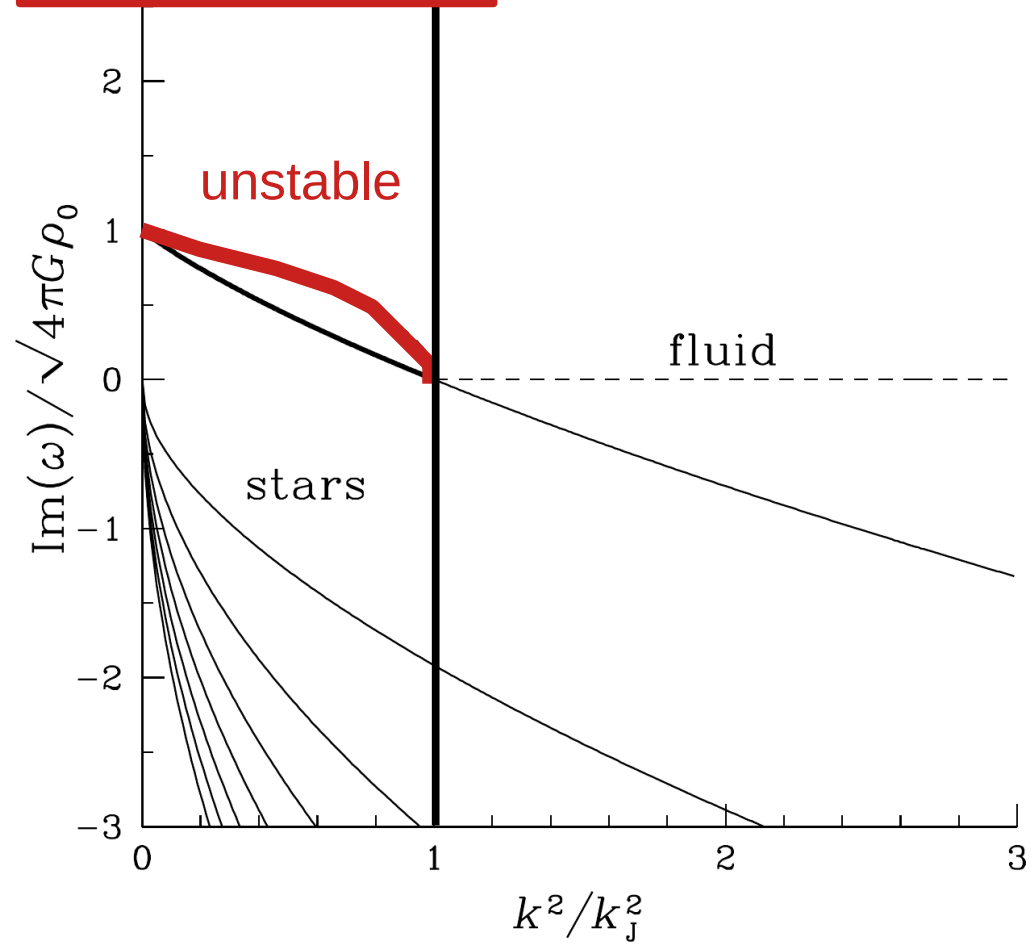
# The dispersion relation for fluids

$$\frac{k^2}{k_J^2} = 1 + \frac{\omega^2}{k_J^2 v_s^2}$$

$$\text{Re}(\omega) = 0$$



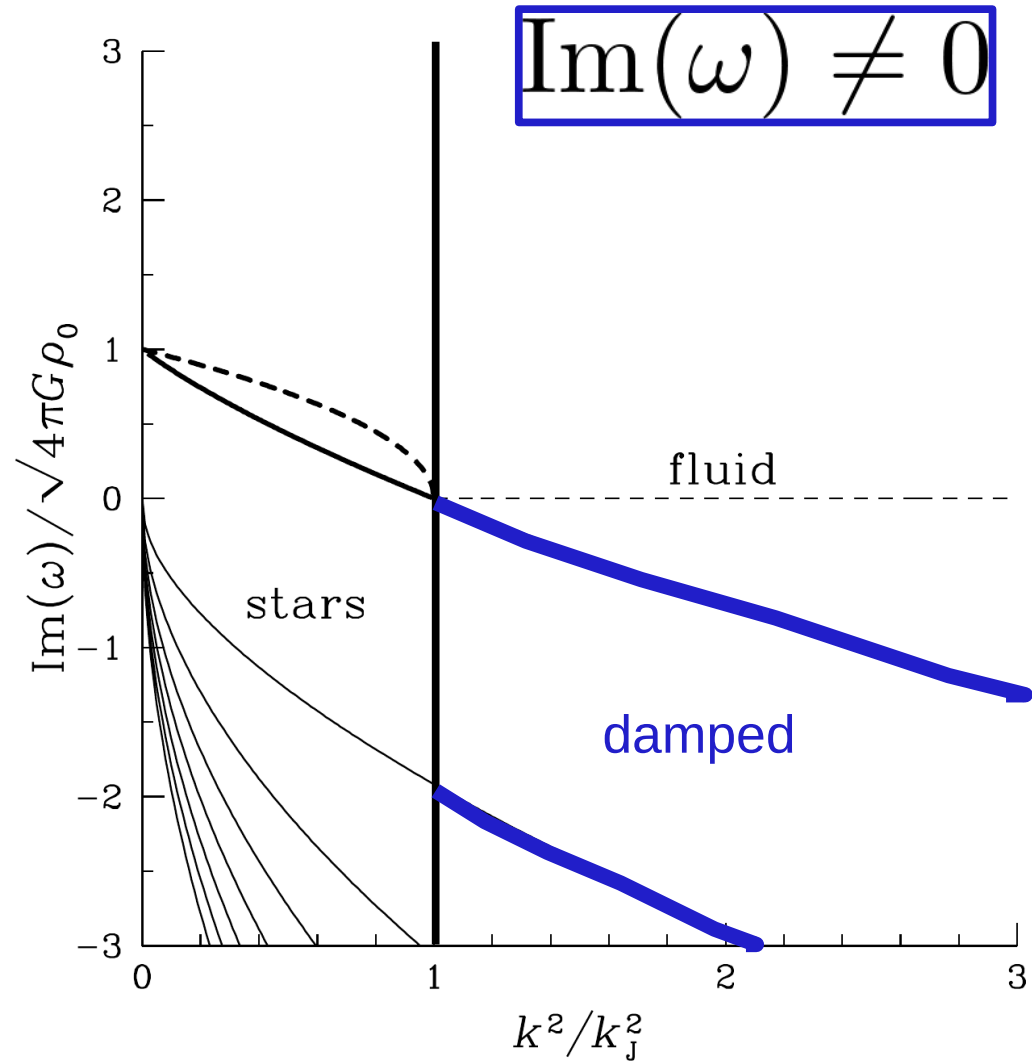
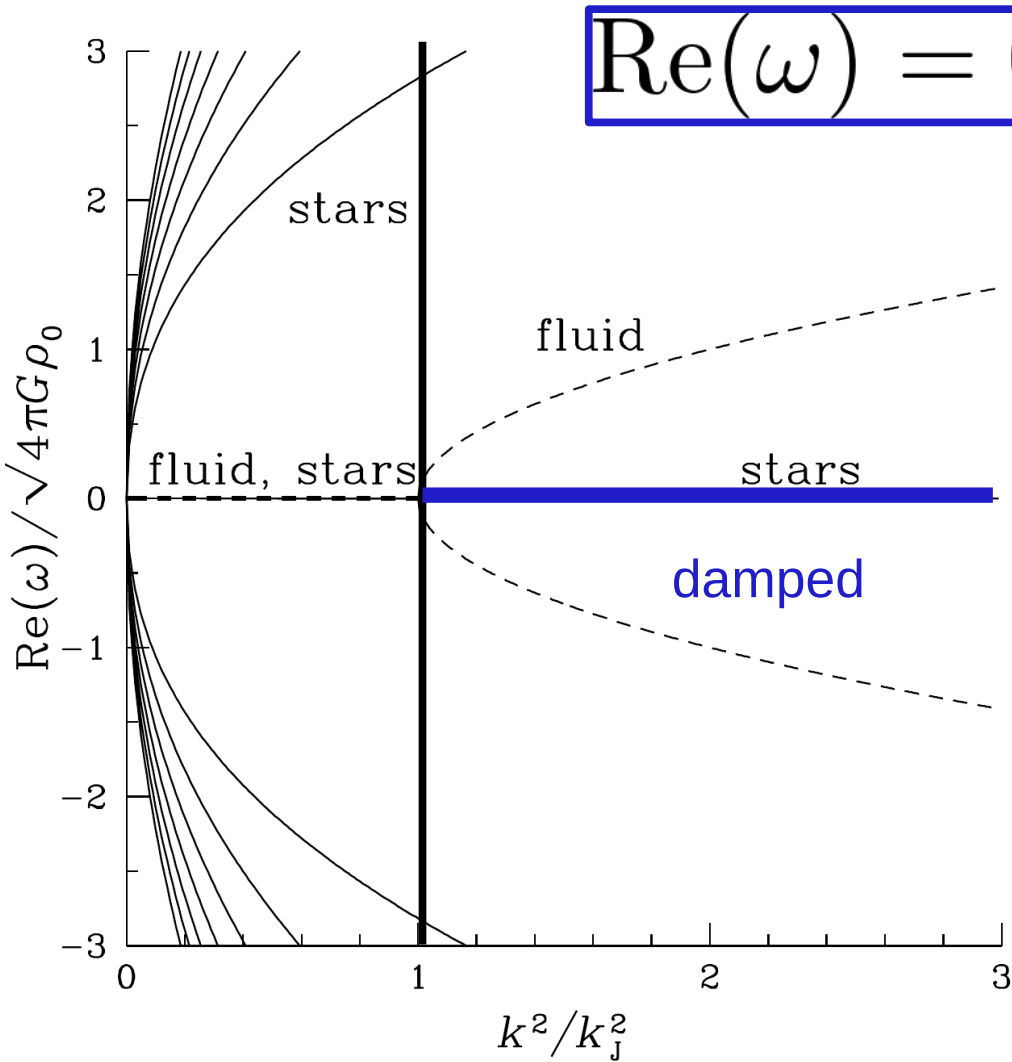
$$\text{Im}(\omega) \neq 0$$





# The dispersion relation for stellar systems

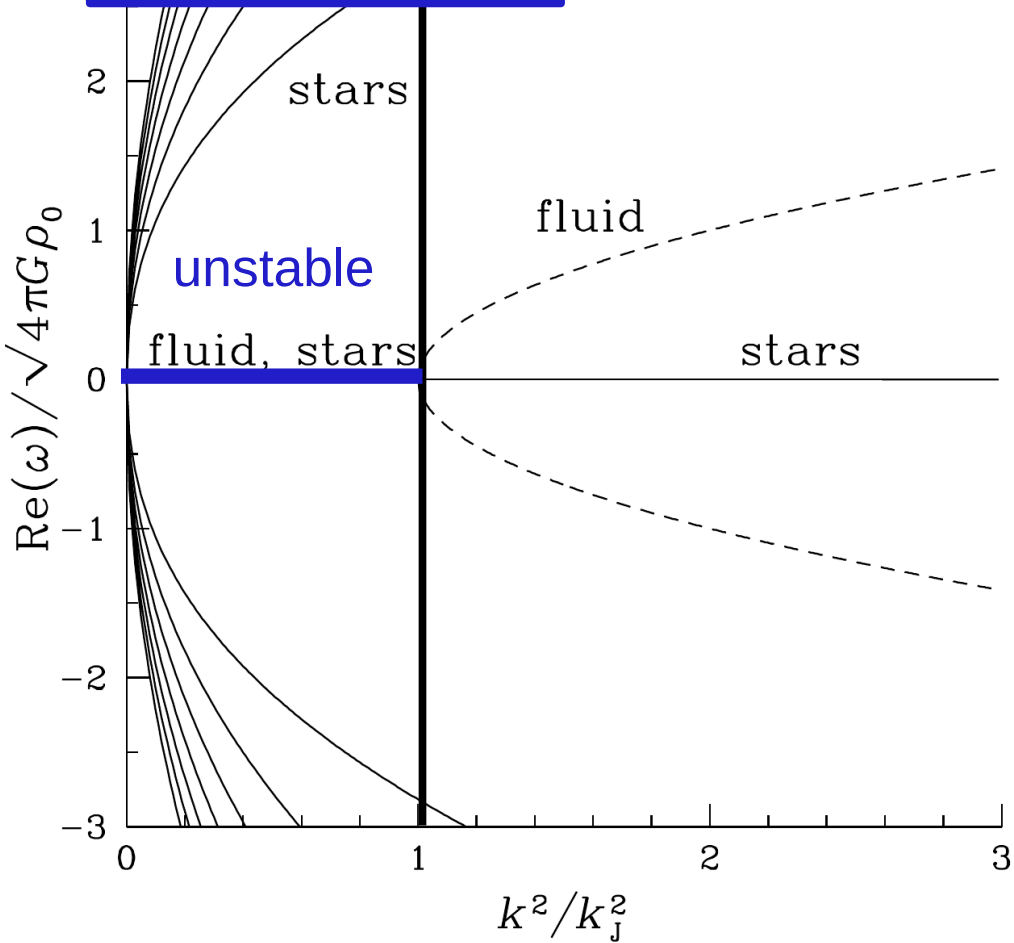
$$\frac{k^2}{k_J^2} = \omega + \omega' \cdot \zeta(\omega')$$



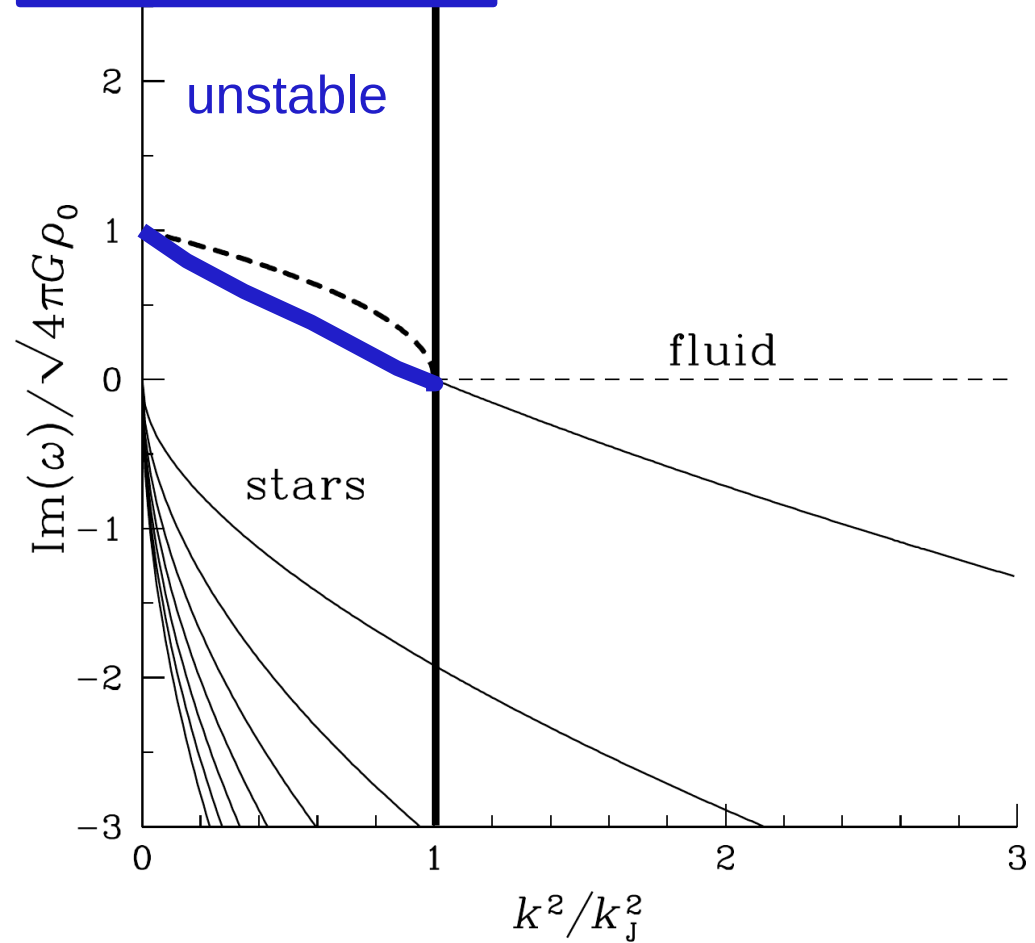
# The dispersion relation for stellar systems

$$\frac{k^2}{k_J^2} = \gamma + \omega' \cdot \zeta(\omega')$$

$$\text{Re}(\omega) = 0$$



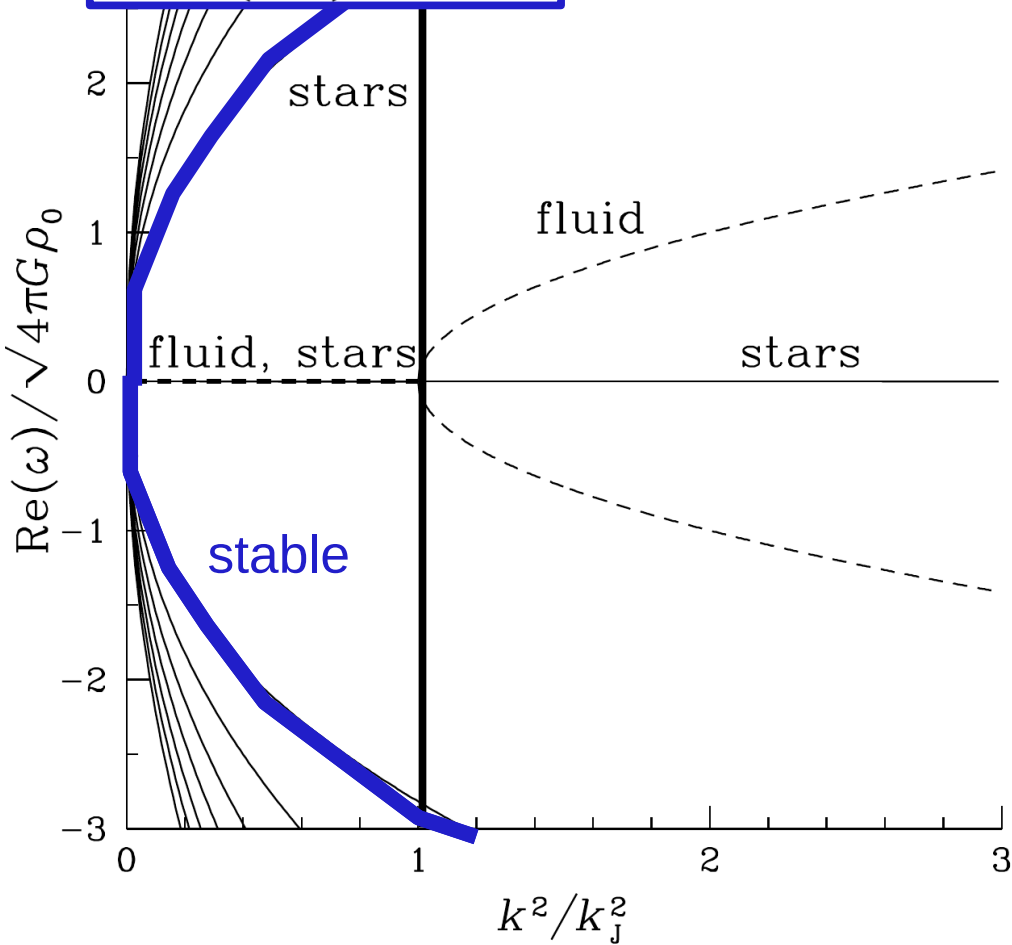
$$\text{Im}(\omega) \neq 0$$



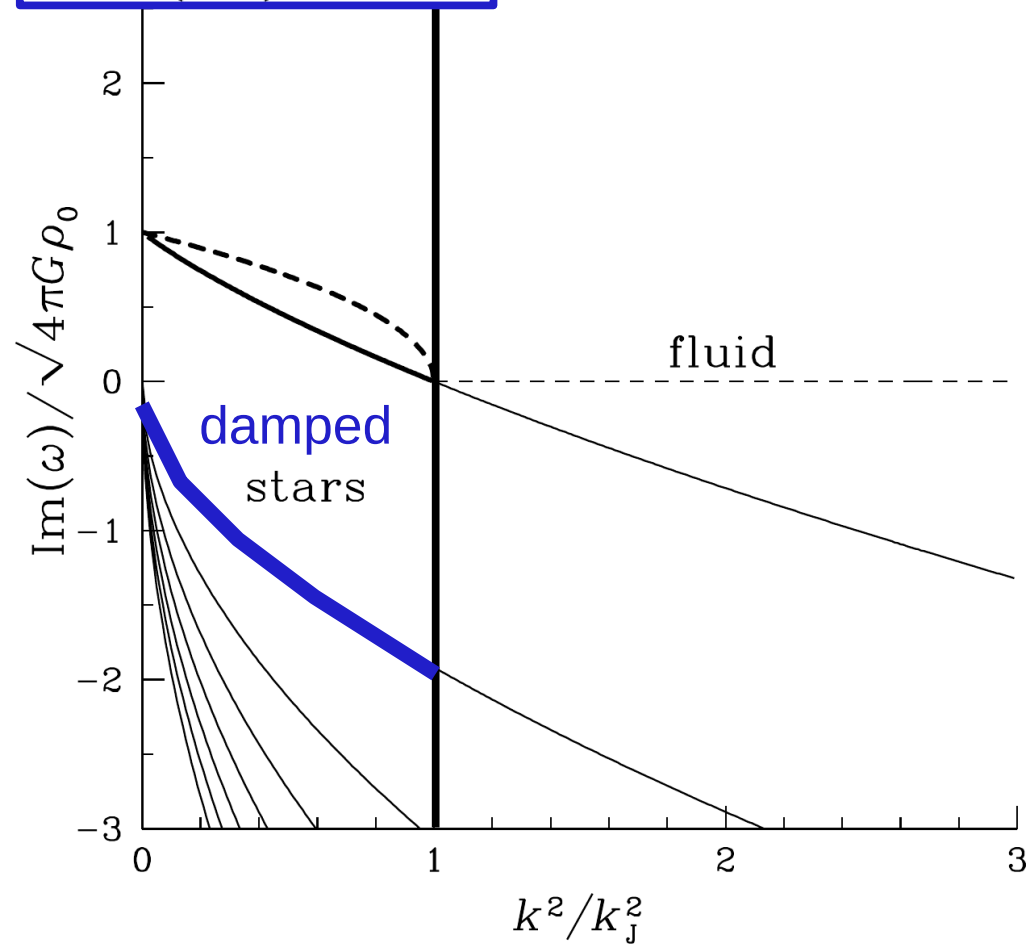
# The dispersion relation for stellar systems

$$\frac{k^2}{k_J^2} = \omega + \omega' \cdot \gamma(\omega')$$

$\text{Re}(\omega) \neq 0$



$\text{Im}(\omega) \neq 0$



# Stability

$$\hat{f} \sim e^{-i\omega t}$$

(A) Unstable

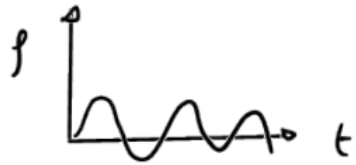
$$\text{Im}(\omega) > 0, \text{Re}(\omega) = 0$$



$$\underline{k^2 < k_J^2} \quad (\text{same than hydro})$$

(B) Stable

$$\text{Im}(\omega) = 0, \text{Re}(\omega) \neq 0$$

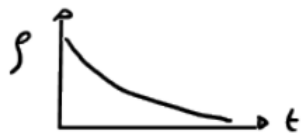


$$\underline{\omega = 0, k = k_J}$$

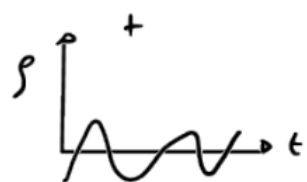
$\Rightarrow$  no stable solution

(C) Damped

$$\text{Im}(\omega) < 0$$



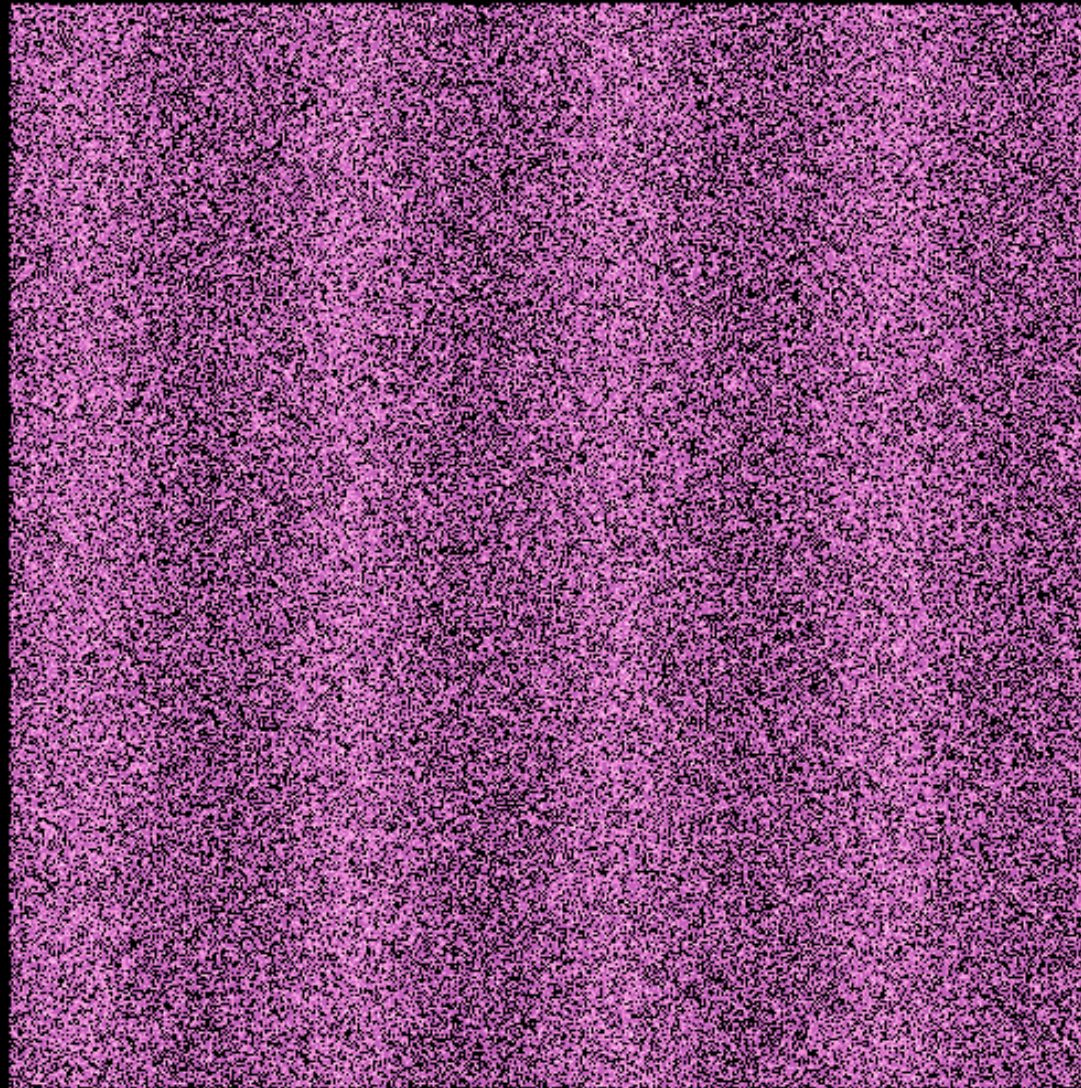
$\rightarrow$  plenty of damped solutions



(with or without oscillation)

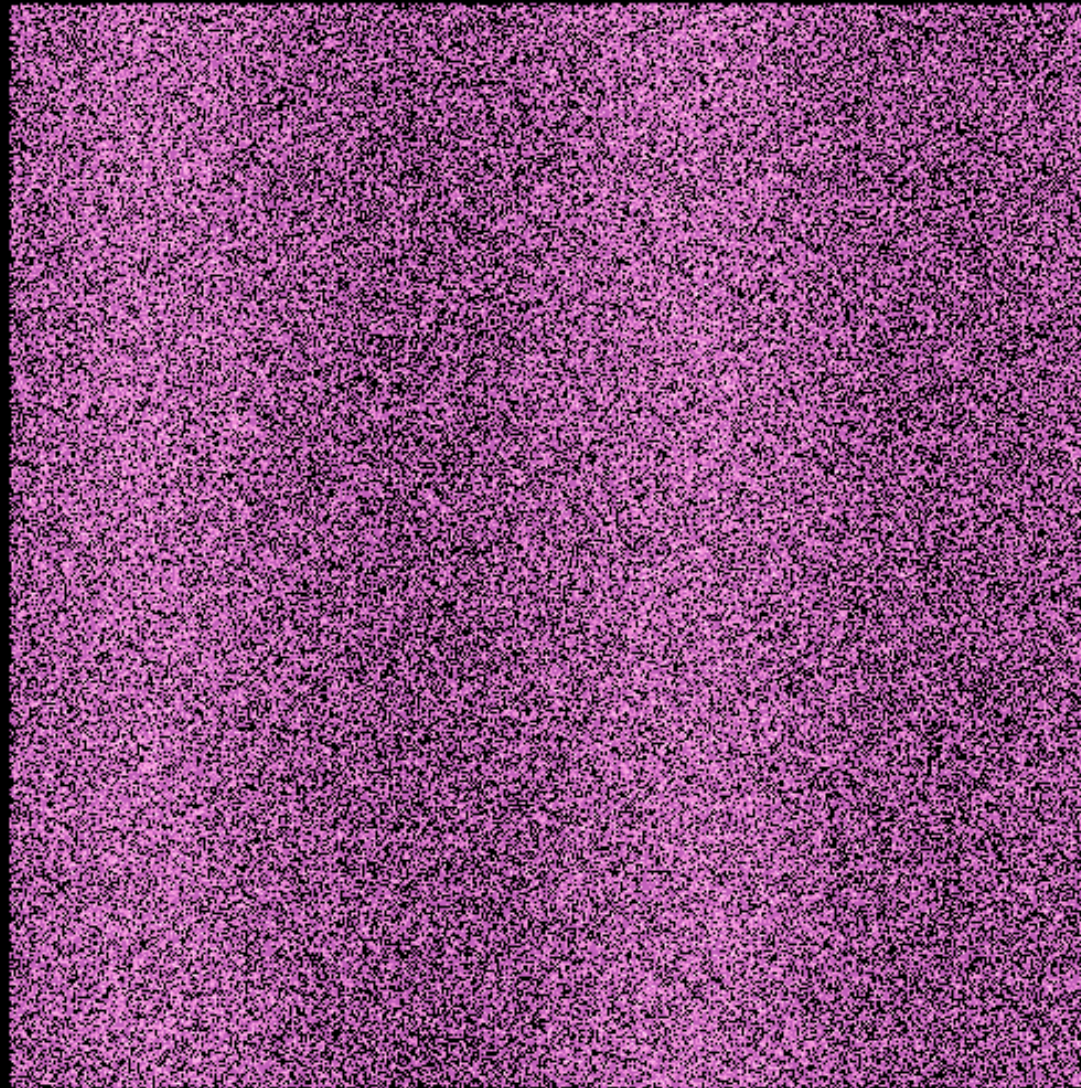
The Jeans instability in stellar systems

$$\lambda_J = 1.50 \quad \lambda = 0.25$$



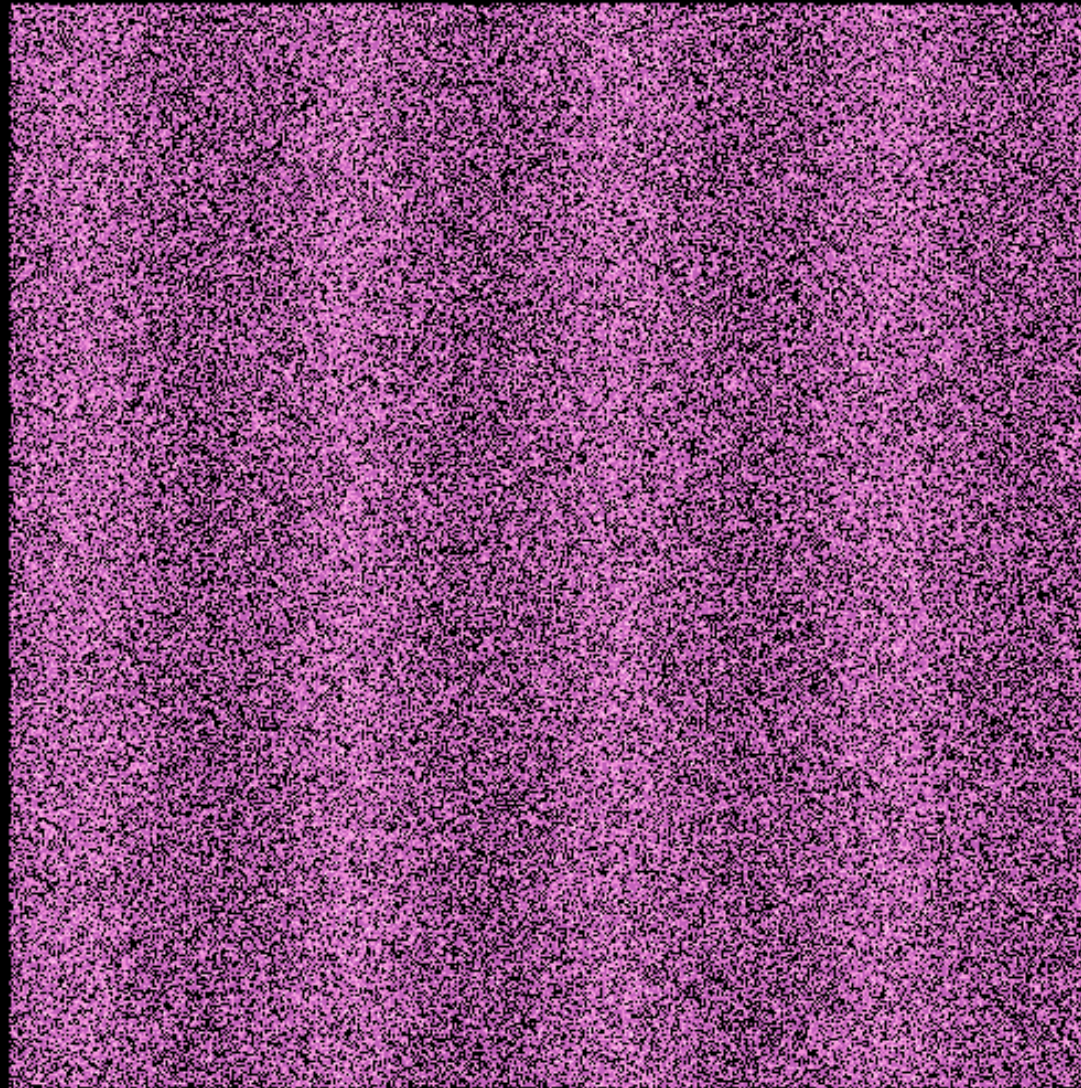
The Jeans instability in stellar systems

$$\lambda_J = 1.50 \quad \lambda = 0.50$$



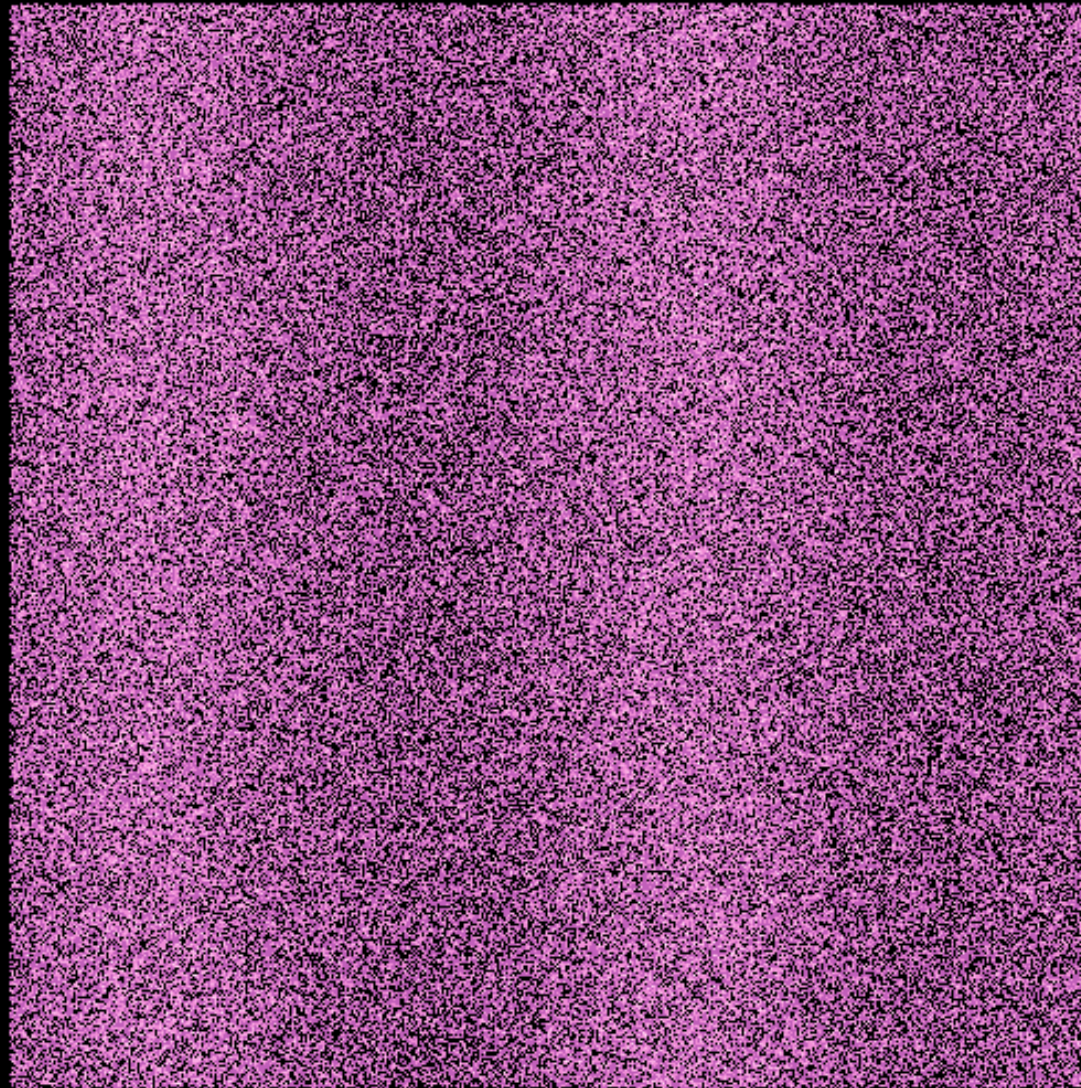
The Jeans instability in stellar systems

$$\lambda_J = 0.25 \quad \lambda = 0.25$$



The Jeans instability in stellar systems

$$\lambda_J = 0.25 \quad \lambda = 0.50$$





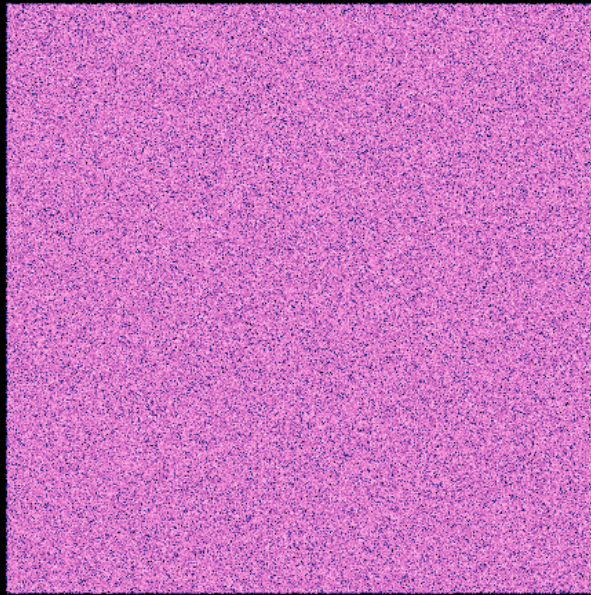
No perturbation : the instability is triggered by the noise due to the discretisation

$$\sigma = 0.1, r_J = 0.005$$

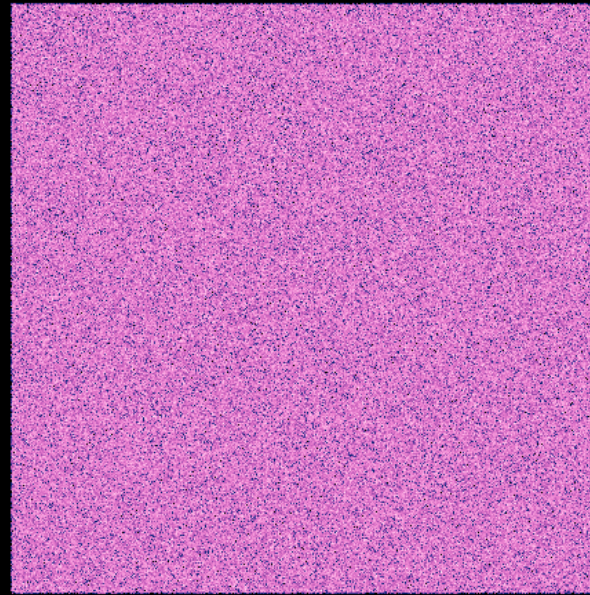
$$\sigma = 0.3, r_J = 0.05$$

$$\sigma = 0.7, r_J = 0.25$$

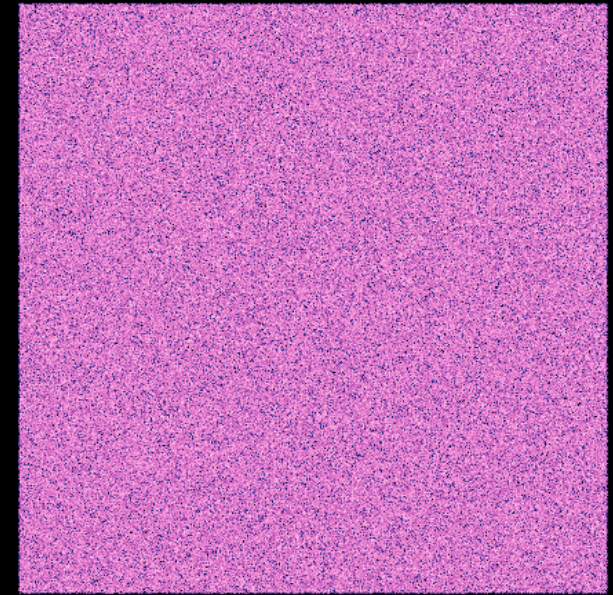
$t = 0.00$



$r_J = 0.005$



$r_J = 0.05$



$r_J = 0.25$

## Landau damping

The existence of solutions with  $\text{Im}(\omega) < 0$  is due to

$$\hat{f}_{S_1}(\vec{k}, \omega) = \left( -\frac{q\bar{n}G}{k^2} \int \frac{d^3\vec{v}}{\boxed{\vec{k}\cdot\vec{v} - \omega}} \vec{k} \cdot \frac{\partial f_0}{\partial \vec{v}} \right) \left( \hat{f}_{S_1}(\vec{k}, \omega) + \hat{f}_e(\vec{k}, \omega) \right)$$

## Wave in 1-D

$$f \sim f(kx - \omega t)$$



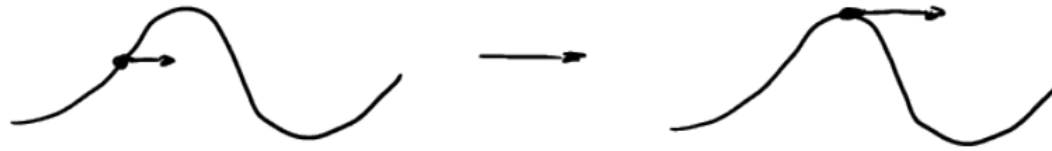
position / velocity of a static point with respect to the wave

$$x = \frac{\omega t}{k} + ck \quad v = \frac{\omega}{k} \quad \Rightarrow \quad \boxed{kv - \omega = 0}$$

$\Rightarrow$  the integral diverges for particles moving at the same velocity than the wave

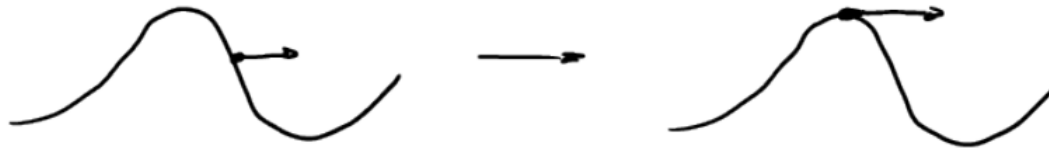
Interpretation: Density wave (perturbation) with a speed  $v_w = \frac{\omega}{k}$

① if a particle with  $v > v_w$  is trapped by the wave



$\Rightarrow$  energy is **given** to the wave

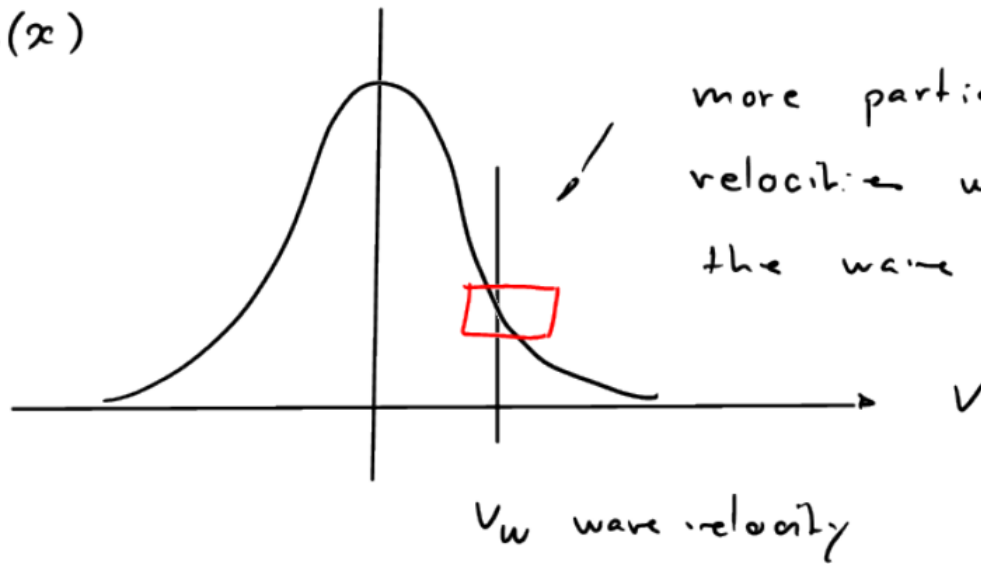
② if a particle with  $v < v_w$  is trapped by the wave



$\Rightarrow$  energy is **taken** from the wave

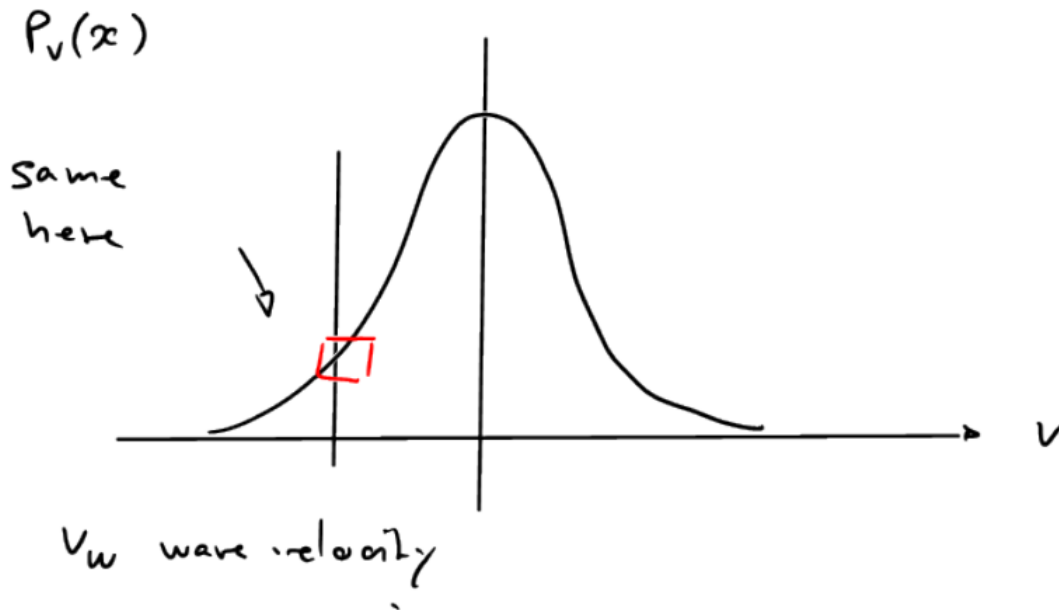
If the velocity distribution function is Maxwellian:

$P_v(x)$



LANDAU  
DAMPING

$P_v(x)$



**The End**

## Linear differential equations

$$f(x) : \frac{d^n f}{dx^n} g_0(x) + \dots + \frac{d^2 f}{dx^2} g_2(x) + \frac{df}{dx} g_1(x) + f(x) g_0(x) = c$$

$g_i(x)$  : a continuous function

if  $f_1, f_2$  are solutions  $a f_1 + b f_2$  is a solution

### Illustration

- 1-D continuity equation ( $f, v$ )

$$\frac{d}{dt} f + \underbrace{f \frac{\partial v}{\partial x} + v \frac{\partial f}{\partial x}} = 0$$

→ those terms mixes  $f$  and  $v$

- 1-D linearized continuity equation ( $f_{s1}, v_1$ )

$$\frac{d}{dt} f_{s1} + f_0 \frac{\partial v_1}{\partial x} + v_0 \frac{\partial f_{s1}}{\partial x} = 0$$

→ no mixing